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Comment on Jackson's analysis of electric charge quantization due to interaction with Dirac's magnetic monopole

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Magnetic monopole; Dirac monopole; Electric charge quantization; Vector potential vorticity. **Abstract.** In J.D. Jackson's *Classical Electrodynamics* textbook, the analysis of Dirac's charge quantization condition in the presence of a magnetic monopole has a mathematical omission and an all-too-brief physical argument that might mislead some students. This paper presents a detailed derivation of Jackson's main result, explains the significance of the missing term, and highlights the close connection between Jackson's findings and Dirac's original argument.

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1. Introduction

In a 1931 paper [1], Dirac showed that the existence of a single magnetic monopole in the universe suffices to explain the observed discreteness of electrical charge. Dirac postulated a magnetic monopole residing at the terminus of a semi-infinite, uniformly magnetized string, as shown in Figure 1. He thus ensured the satisfaction of Maxwell's equation $\nabla \cdot \mathbf{B} = 0$, which is a prerequisite for defining the vector potential \mathbf{A} via the identity $\nabla \times \mathbf{A} = \mathbf{B}$.

Dirac's subtle argument relies on the strong vorticity of the vector potential surrounding the string, which prevents the quantum-mechanical wave-function of an electrically charged particle (e.g., an electron) from penetrating the string; the string thus remains invisible to the electrically charged particle. However, for the phase of the wave-function in the vicinity of the string to be single-valued, Dirac argued that the product of the particle's electric charge q and the monopole's magnetic charge m_0 must be an integermultiple of Planck's constant h. (Note: Dirac's quantization condition is $qm_0 = nh$ in the SI system of units, and $4\pi qm_0 = nhc$ in the Gaussian system; here, h is Planck's constant, c is the speed of light in vacuum, and n is an arbitrary nonzero integer.)

The presentation of Dirac's argument in J.D. Jackson's *Classical Electrodynamics* textbook [2] deviates somewhat from Dirac's original line of reasoning. Jackson arrives at the correct charge quantization condition despite a mathematical omission and a rather hasty physical argument. There is much to recommend Jackson's analysis of Dirac's quantization condition, and it would be a pity if a minor omission and a hasty shortcut distracted the reader from fully appreciating the significance of this analysis. The present paper aims to expand upon and clarify Jackson's discussion of charge quantization in the presence of a Dirac magnetic monopole.

Following the publication of Dirac's famous 1931 paper, there have appeared many books and papers that elaborate and expand upon Dirac's ideas. There have also been several attempts at capturing and detecting magnetic monopoles. The short list of cited references here [3-7] is by no means intended to provide a comprehensive guide to the vast literature of the sub-

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ject. We do hope, however, that, upon consulting these references, the interested reader will catch a glimpse of where the studies of magnetic monopoles stand today.

2. String's vector potential

With reference to Figure 1, a semi-infinite magnetized string (or solenoid) may be modelled as follows:

$$\mathbf{M}(\mathbf{r}) = \mathbf{m}(z)\delta\left[x - x_s(z)\right]\delta\left[y - y_s(z)\right].$$
 (1)

Here, $\mathbf{m}(z)$ is the magnetic dipole moment per unit length of the string at $[x_s(z), y_s(z), z]$ and $\mathbf{M}(\mathbf{r})$ is the magnetization density at $\mathbf{r} = (x, y, z)$. There are no magnetic charges anywhere along the length of the string except at its extremities. As shown in Appendix A, the z-component of $\mathbf{m}(z)$ must be a constant, that is, $m_z(z) = m_0$, where m_0 is the charge of the magnetic monopole at the terminal point $[x_s(z_0), y_s(z_0), z_0]$ of the string (here, the magnetic induction **B**, the magnetic field **H**, and the magnetization **M** are related via $\mathbf{B} = \mu_0 \mathbf{H} + \mathbf{M}$, where μ_0 is the permeability of free space. Both **B** and **M** thus have units of weber/m², resulting in m_0 being in webers).

To confirm that arbitrary bends and twists of a tightly wound solenoidal string do not leak its internal magnetic flux to the outside world, a systematic calculation of the string's vector potential is presented in Appendix A. In the end, our derivation yields the same simple formula for the string's vector potential as that used by Jackson [2], namely, a direct integral over infinitesimal vector potentials at the observation point **r** contributed by small lengths $d\ell$ of the string located at **r**_s, as follows:

$$\mathbf{A}_{s}(\mathbf{r}) = \frac{m_{0}}{4\pi} \int_{\infty}^{z_{0}} \left(\mathbf{\nabla}_{r} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \right) \times d\boldsymbol{\ell}.$$
 (2)

As a simple example (and one that was analyzed in detail by Dirac), we calculate \mathbf{A}_{S_1} for a monopole at the end of a string S_1 aligned with the negative zaxis. The monopole m_0 is thus located at the origin of coordinates, and the observation point $\mathbf{r} = x\hat{\mathbf{x}} + y\hat{\mathbf{y}} + z\hat{\mathbf{z}}$ has spherical coordinates (r, θ, ϕ) . A straightforward evaluation of Eq. (2) yields:

$$\mathbf{A}_{S_1}(\mathbf{r}) = \frac{m_0}{4\pi} \int_{-\infty}^0 \left\{ \nabla_r \left[x^2 + y^2 + (z - \tilde{z})^2 \right]^{-1/2} \right\} \times \hat{\mathbf{z}} d\tilde{z}$$
$$= -\frac{m_0}{4\pi} \int_{-\infty}^0 \frac{\left[x \hat{\mathbf{x}} + y \hat{\mathbf{y}} + (z - \tilde{z}) \hat{\mathbf{z}} \right] \times \hat{\mathbf{z}}}{\left[x^2 + y^2 + (z - \tilde{z})^2 \right]^{3/2}} d\tilde{z}$$
$$= \frac{m_0 (x \hat{\mathbf{y}} - y \hat{\mathbf{x}})}{4\pi (x^2 + y^2)} \int_{\cot \theta}^{\infty} \frac{d\zeta}{(1 + \zeta^2)^{3/2}}$$
$$= \frac{m_0 \hat{\phi}}{4\pi \sqrt{x^2 + y^2}} \times \frac{\zeta}{\sqrt{1 + \zeta^2}} \Big|_{\cot \theta}^{\infty}$$
$$= \frac{m_0 \hat{\phi}}{4\pi r \sin \theta} \left(1 - \frac{\cot \theta}{\sqrt{1 + \cot^2 \theta}} \right)$$
$$= \frac{m_0 (1 - \cos \theta) \hat{\phi}}{4\pi r \sin \theta}.$$
(3)



Figure 1. Semi-infinite magnetized string ending at a magnetic monopole at $z = z_0$. The coordinates of the string at elevation z are given by the functions $x_s(z)$ and $y_s(z)$. The magnetic dipole moment per unit length of the string at $[x_s(z), y_s(z), z]$ is given by $\mathbf{m}(z)$, which is aligned with the local orientation of the string and vanishes above $z = z_0$. The polar coordinates $\theta(z)$ and $\phi(z)$ of the string are related to its Cartesian coordinates via the identities $x'_s(z) = \tan \theta \cos \phi$ and $y'_s(z) = \tan \theta \sin \phi$. The alignment of $\mathbf{m}(z)$ with the local orientation of the string thus implies that $m_x(z)/m_z(z) = x'_s(z)$ and $m_y(z)/m_z(z) = y'_s(z)$. The model used for the string in Eq. (1) gives the string a constant cross-section in the xy-plane. To ensure that magnetic charge does not appear anywhere along the string (except at $z = z_0$), the z-component of $\mathbf{m}(z)$ must be a constant, that is, $m_z(z) = m_0$. The magnetic charge of the monopole at $[x_s(z_0), y_s(z_0), z_0]$ is thus equal to m_0 , which, in the SI system, has units of weber.

The term $(1 - \cos \theta) / \sin \theta$ may be further simplified and written as $\tan(\frac{1}{2}\theta)$. The vector potential of a semiinfinite string aligned with the negative z-axis is thus seen to have a singularity at the location of the string, i.e. at $\theta = \pi$. The vortex-like \mathbf{A}_{S_1} circling the negative z-axis integrates to m_0 over a tight circle surrounding the string, in accordance with $\oint \mathbf{A}_{S_1} d\ell = \int \mathbf{B}_{S_1} d\sigma =$ m_0 . Now, Dirac's original argument in [1] appears to have been that the integral of \mathbf{A}_{S_1} around a tight loop circling the string, when multiplied by e/\hbar , is a phasefactor for the Schrödinger wave-function $\psi_{S_1}(\mathbf{r})$ of an electron of charge e in the presence of the magnetic monopole, which must be equal to an integer-multiple of 2π . Dirac's quantization condition, $em_0/\hbar = 2\pi n$, is an immediate consequence of this assumption. (Here, as usual, $\hbar = h/2\pi$.)

Suppose now that a string, S_2 , extends from z = 0 to $+\infty$ along the positive z-axis, with the magnetic monopole m_0 residing at its lower terminus. A similar analysis as in Eq. (3) now yields:

$$\mathbf{A}_{S_2}(\mathbf{r}) = \frac{m_0(-1-\cos\theta)\hat{\boldsymbol{\phi}}}{4\pi r\sin\theta}.$$
(4)

This time, the vector potential has vortex-like behavior around the positive z-axis, but, elsewhere in space, it produces the same *B*-field as does \mathbf{A}_{S_1} . The difference between the two vector potentials in Eqs. (3) and (4) is readily seen to be:

$$\mathbf{A}_{S_1}(\mathbf{r}) - \mathbf{A}_{S_2}(\mathbf{r}) = \frac{m_0 \hat{\boldsymbol{\phi}}}{2\pi r \sin \theta} = \boldsymbol{\nabla}(\frac{m_0}{2\pi} \phi).$$
(5)

The two vector potentials thus differ by the gradient of a scalar function, which might indicate that they are related via a gauge transformation. Note, however, that along the entire z-axis, the scalar function $m_0\phi/2\pi$ is ill-defined. Consequently, the z-axis is a singularity of the gradient of the scalar function. The difference between \mathbf{A}_{S_1} and \mathbf{A}_{S_2} is more than a simple gauge transformation; the curl of $\mathbf{A}_{S_1} - \mathbf{A}_{S_2}$ is the infinite magnetization inside a long, thin string extending all the way from $z = -\infty$ to $z = +\infty$.

3. Change in vector potential in consequence of a change of the string

In Jackson's treatment [3] of Dirac's magnetic monopole, we are reminded that the specific shape and/or location of the string is irrelevant and that, therefore, the vector potentials \mathbf{A}_{S_1} and \mathbf{A}_{S_2} corresponding to two strings S_1 and S_2 , which terminate on the same monopole, must differ by a gauge transformation; see Figure 2. This means that $\mathbf{A}_{S_1}(\mathbf{r}) - \mathbf{A}_{S_2}(\mathbf{r}) = \nabla \chi(\mathbf{r})$, where $\chi(\mathbf{r})$ is some well-defined function of the spatial coordinates. Jackson proceeds to determine $\chi(\mathbf{r})$ along the following lines, but, toward the end, he appears to have inadvertently omitted a term containing a δ -function. (Justifications for some of the steps taken below are given in Appendix B.)

$$\mathbf{A}_{S_1}(\mathbf{r}) - \mathbf{A}_{S_2}(\mathbf{r}) = \frac{m_0}{4\pi} \oint_c \left(\boldsymbol{\nabla}_r |\mathbf{r} - \mathbf{r}_s|^{-1} \right) \times d\boldsymbol{\ell}$$
(6a)

$$= \frac{m_0}{4\pi} \oint_c \boldsymbol{\nabla}_r \times \frac{d\boldsymbol{\ell}}{|\mathbf{r} - \mathbf{r}_s|}$$
(6b)

$$=\frac{m_0}{4\pi}\boldsymbol{\nabla}_r \times \oint_c \frac{d\boldsymbol{\ell}}{|\mathbf{r}-\mathbf{r}_s|} \tag{6c}$$

$$= -\frac{m_0}{4\pi} \boldsymbol{\nabla}_r \times \int_s (\boldsymbol{\nabla}_{r_s} |\mathbf{r} - \mathbf{r}_s|^{-1}) \times d\boldsymbol{\sigma} \ (6d)$$

$$=\frac{m_0}{4\pi}\boldsymbol{\nabla}_r \times \int_s \left(\boldsymbol{\nabla}_r |\mathbf{r} - \mathbf{r}_s|^{-1}\right) \times d\boldsymbol{\sigma}$$
(6e)

$$=\frac{m_0}{4\pi}\boldsymbol{\nabla}_r \times \boldsymbol{\nabla}_r \times \int_s \frac{d\boldsymbol{\sigma}}{|\mathbf{r} - \mathbf{r}_s|} \qquad (6f)$$

$$= \frac{m_0}{4\pi} \boldsymbol{\nabla}_r \int_s \boldsymbol{\nabla}_r \cdot \left(\frac{d\boldsymbol{\sigma}}{|\mathbf{r} - \mathbf{r}_s|}\right)$$
$$-\frac{m_0}{4\pi} \int_s \boldsymbol{\nabla}_r^2 \left(\frac{d\boldsymbol{\sigma}}{|\mathbf{r} - \mathbf{r}_s|}\right) \tag{6g}$$

$$= \frac{m_0}{4\pi} \boldsymbol{\nabla}_r \int_s (\boldsymbol{\nabla}_r |\mathbf{r} - \mathbf{r}_s|^{-1}) d\boldsymbol{\sigma}$$
$$- \frac{m_0}{4\pi} \int_s (\nabla_r^2 |\mathbf{r} - \mathbf{r}_s|^{-1}) d\boldsymbol{\sigma} \qquad (6h)$$

$$= \frac{m_0}{4\pi} \nabla_r \int_s \frac{(\mathbf{r}_s - \mathbf{r}) d\boldsymbol{\sigma}}{|\mathbf{r} - \mathbf{r}_s|^3} + m_0 \int_s \delta_3(\mathbf{r} - \mathbf{r}_s) d\boldsymbol{\sigma}$$
(6i)

$$= \frac{m_0}{4\pi} \boldsymbol{\nabla}_r \int_s d\Omega(\mathbf{r}; \mathbf{r}_s) + m_0 \int_s \delta_3(\mathbf{r} - \mathbf{r}_s) d\boldsymbol{\sigma}$$
(6j)

$$= \frac{m_0}{4\pi} \boldsymbol{\nabla} \Omega_c(\mathbf{r}) + m_0 \delta(r_\perp) \hat{\mathbf{r}}_\perp.$$
 (6k)

In the preceding equation, $\Omega_c(\mathbf{r})$ is the solid angle subtended by the contour c when viewed from \mathbf{r} , and r_{\perp} is the perpendicular distance from \mathbf{r} to the surface s. Since $\delta(r_{\perp})$ is nonzero only when \mathbf{r} is extremely close to s, the unit-vector $\hat{\mathbf{r}}_{\perp}$ coincides with the local surface normal, its orientation being determined by the sense of travel around c. The sign of r_{\perp} is positive or negative, depending on which side of the surface s (as



Figure 2. When two semi-infinite strings S_1 and S_2 terminate on the same magnetic monopole, the difference $\mathbf{A}_{S_1} - \mathbf{A}_{S_2}$ between their vector potentials is given by an integral over the closed loop c, which is the boundary of the shaded area s. The loop in this figure is traversed counterclockwise. The solid angle subtended by the closed loop c at the observation point \mathbf{r} is denoted by $\Omega_c(\mathbf{r})$. The points on the surface s (and its boundary c) are denoted by \mathbf{r}_s . An elemental surface area of s is denoted by $d\sigma$, whose direction, while perpendicular to the local surface, is also tied to the direction of travel around c via the right-hand rule. The elemental solid angle subtended at the observation point \mathbf{r} by the surface element $d\sigma$ at \mathbf{r}_s is denoted by $d\Omega(\mathbf{r};\mathbf{r}_s)$.

indicated by the direction of $\hat{\mathbf{r}}_{\perp}$) the observation point \mathbf{r} happens to fall.

In Jackson's analysis [2], the term $m_0 \delta(r_\perp) \hat{\mathbf{r}}_\perp$ on the right-hand-side of Eq. (6k) is missing. This is the aforementioned mathematical omission, whose effects are subsequently compounded by the brevity of Jackson's physical argument. Jackson notes that, when the observation point \mathbf{r} crosses the surface s along the surface-normal $\hat{\mathbf{r}}_{\perp}$, the solid angle $\Omega_c(\mathbf{r})$ suddenly drops from 2π to -2π . This discontinuity of $\Omega_c(\mathbf{r})$ at the surface s gives rise to a δ -function of magnitude 4π whenever $\nabla \Omega_{\rm c}({\bf r})$ is evaluated at a point r located on the surface s. However, the resulting δ -function contained in $(m_0/4\pi) \nabla \Omega_c(\mathbf{r})$ is readily cancelled out by the term $m_0 \delta(r_\perp) \hat{\mathbf{r}}_\perp$ appearing in Eq. (6k). This means that $\mathbf{A}_{S_1} - \mathbf{A}_{S_2}$ is a well-defined, continuous function of **r** everywhere except on the closed loop c (i.e., on the boundary of s). It is worth emphasizing that, while $\Omega_c(\mathbf{r})$ is inherently discontinuous at the surface s, the vector-potentials $\mathbf{A}_{S_1}(\mathbf{r})$ and $\mathbf{A}_{S_2}(\mathbf{r})$ are expected to be smooth and well-behaved functions of \mathbf{r} everywhere in space—except, of course, on their respective strings S_1 and S_2 . Consequently, the presence of $m_0 \delta(r_\perp) \hat{\mathbf{r}}_\perp$ in Eq. (6k) is absolutely essential if the δ -function contained in $\nabla \Omega_c(\mathbf{r})$ is to be neutralized.

At this point, one is not yet in a position to specify a gauge, because $\Omega_c(\mathbf{r})$, a function that is well-defined everywhere except on c, has a 4π discontinuity on s. This discontinuity gives rise to a δ -function in $\nabla\Omega_c$, which is removed only after an equal and opposite δ -function is added to $\nabla\Omega_c$. One must somehow eliminate, or render invisible, the discontinuity of Ω_c at s, which is responsible for the undesirable δ -function appearing in Eq. (6k). Removal of this discontinuity requires that Ω_c be incorporated into a phase-factor, as explained in the next section.

4. Schrödinger's equation for point-charge in the presence of magnetic monopole

Suppose $\psi_{s_2}(\mathbf{r}, t)$ is a solution of Schrödinger's equation for a point-particle of charge q and mass m in the presence of the string S_2 , whose vector potential is \mathbf{A}_{S_2} . Let us multiply the wave-function ψ_{s_2} by the *spurious* phase-factor $\exp[iqm_0\Omega_c(\mathbf{r})/(4\pi\hbar)]$. This phase-factor will be discontinuous at the surface s, where Ω_c has a 4π jump, unless qm_0/\hbar happens to be an integermultiple of 2π . Therefore, imposing Dirac's quantization condition $qm_0 = 2\pi n\hbar = nh$ renders *invisible* the discontinuity of Ω_c at s. Under such circumstances, when evaluating the gradient of the phase-factor, one is obligated to add the necessary δ -function to $\nabla\Omega_c$ in order to ensure that the resulting function is wellbehaved, that is:

$$-\mathrm{i}\hbar\boldsymbol{\nabla}\exp\left(\frac{\mathrm{i}qm_{0}\Omega_{c}}{4\pi\hbar}\right)$$
$$=\frac{qm_{0}}{4\pi}\left[\boldsymbol{\nabla}\Omega_{c}+4\pi\delta(r_{\perp})\hat{\mathbf{r}}_{\perp}\right]\exp\left(\frac{\mathrm{i}qm_{0}\Omega_{c}}{4\pi\hbar}\right).$$
(7)

Substitution from Eq. (6) into the above equation now yields:

$$-\mathrm{i}\hbar\nabla\exp\left(\frac{\mathrm{i}qm_{0}\Omega_{c}}{4\pi\hbar}\right) = q(\mathbf{A}_{S_{1}} - \mathbf{A}_{S_{2}})\exp\left(\frac{\mathrm{i}qm_{0}\Omega_{c}}{4\pi\hbar}\right)_{(8)}$$

Note how the imposition of Dirac's quantization condition has "patched up" the discontinuity of the phasefactor in such a way as to render Ω_c effectively continuous at the surface s. Had the δ -function in Eq. (6k) been absent, there would have been no need in Jackson's analysis [2] for Dirac's quantization condition, because the function $(m_0/4\pi)\Omega_c(\mathbf{r})$, in spite of its discontinuity at s, would have been an acceptable gauge.

It is now easy to show, with the aid of Eq. (8), that the product of ψ_{s_2} and the *spurious* phase-factor satisfies Schrödinger's equation for the point-particle of charge q and mass m in the presence of \mathbf{A}_{S_1} , the vector potential of S_1 . (To simplify the notation, we pretend in what follows that Ω_c is continuous at the surface s and proceed to omit the δ -function that, in accordance with Eq. (7), must accompany $\nabla \Omega_c$.) We write:

$$\frac{1}{2m} \left(-i\hbar \nabla - q \mathbf{A}_{S_1} \right) \cdot \left(-i\hbar \nabla - q \mathbf{A}_{S_1} \right) \left[\exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \psi_{s_2} \right] \\
= \frac{1}{2m} \left(-i\hbar \nabla - q \mathbf{A}_{S_1} \right) \\
\cdot \left[-i\hbar \nabla \psi_{s_2} - q (\mathbf{A}_{S_1} - \frac{m_0}{4\pi} \nabla \Omega_c) \psi_{s_2} \right] \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \\
= \frac{1}{2m} \left(-i\hbar \nabla - q \mathbf{A}_{S_1} \right) \\
\cdot \left[\left(-i\hbar \nabla \psi_{s_2} - q \mathbf{A}_{S_2} \psi_{s_2} \right) \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \right] \\
= \frac{1}{2m} \left\{ \left[-i\hbar \nabla - q (\mathbf{A}_{S_1} - \frac{m_0}{4\pi} \nabla \Omega_c) \right] \\
\cdot \left(-i\hbar \nabla \psi_{s_2} - q \mathbf{A}_{S_2} \psi_{s_2} \right) \right\} \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \\
= \frac{1}{2m} \left[\left(-i\hbar \nabla - q (\mathbf{A}_{S_1} - \frac{m_0}{4\pi} \nabla \Omega_c) \right) \right] \\
\cdot \left(-i\hbar \nabla \psi_{s_2} - q \mathbf{A}_{S_2} \psi_{s_2} \right) \right\} \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \\
= \frac{1}{2m} \left[\left(-i\hbar \nabla - q \mathbf{A}_{S_2} \right) \psi_{s_2} \right] \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \\
= \left(i\hbar \partial_t \psi_{s_2} \right) \exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \\
= i\hbar \partial_t \left[\exp \left(\frac{iq m_0 \Omega_c}{4\pi \hbar} \right) \psi_{s_2} \right].$$
(9)

Clearly, $\exp[iqm_0\Omega_c/(4\pi\hbar)]\psi_{s_2}$ is a solution of Schrödinger's equation for the charge q in the presence of S_1 . However, multiplication by a phase-factor is physically meaningless, since it is equivalent to a change of gauge. The fact that the phase-factor is ill-defined over the contour c does not seem to have any physical significance either, as the wave-functions always vanish on the corresponding strings. It should now be clear that the vector potential associated with one string, say S_1 , can produce, aside from a spurious phase-factor, the solution to Schrödinger's equation for any other string, such as S_2 , as well.

In his original paper [1], Dirac gives an explicit example in which the vector potential associated with a string along the negative z-axis produces two eigen solutions to Schrödinger's equation, namely, ψ_{1a} = $f(r)\cos(\theta/2)$ and $\psi_{1b} = f(r)\sin(\theta/2)\exp(i\phi)$. The first solution corresponds to the string whose presence along the negative z-axis has been assumed, while the second solution, aside from the spurious phase-factor $\exp(i\phi)$, represents an eigen wave-function associated with a string along the positive z-axis. Note that the function $\exp(i\phi)$ is ill-defined along the entire z-axis, which, in the present example, represents the contour c. (Note: There is a minus sign missing in Dirac's paper; the spurious phase-factor for ψ_{1b} should in fact be $\exp(-i\phi)$, as can be readily checked by substitution into his equation (13).)

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Appendix A

We derive a formula for the vector potential $\mathbf{A}_s(\mathbf{r})$ of the arbitrary string S depicted in Figure 1, whose magnetization $\mathbf{M}(\mathbf{r})$ is given by Eq. (1). It must be pointed out that, in our notation, $\mathbf{B} = \mu_0 \mathbf{H} + \mathbf{M}$, and that, therefore, magnetic induction \mathbf{B} and magnetization \mathbf{M} have the same units (tesla or weber/m²). Here \mathbf{H} is the magnetic field (ampere/m) and μ_0 is the permeability of free space (henry/m). The fundamental constraint on $\mathbf{M}(\mathbf{r})$ is that its magnetic charge-density along the length of S must vanish, that is:

$$\nabla .\mathbf{M}(\mathbf{r}) = m_x(z)\delta' [x - x_s(z)] \,\delta[y - y_s(z)] + m_y(z)\delta[x - x_s(z)]\delta'[y - y_s(z)] + m'_z(z)\delta[x - x_s(z)]\delta[y - y_s(z)] - m_z(z)x'_s(z)\delta'[x - x_s(z)]\delta[y - y_s(z)] - m_z(z)y'_s(z)\delta[x - x_s(z)]\delta'[y - y_s(z)] = 0.$$
(A.1)

Consequently, $x'_s(z) = m_x(z)/m_z(z)$, $y'_s(z) = m_y(z)/m_z(z)$, and $m'_z(z) = 0$, which yields $m_z(z) = m_0$. Note that the string's local magnetic moment $\mathbf{m}(z)$, which may also be described in terms of the polar angles $[\theta(z), \phi(z)]$, is aligned with the string's local orientation $d\boldsymbol{\ell} = (x'_s \hat{\mathbf{x}} + y'_s \hat{\mathbf{y}} + \hat{\mathbf{z}}) dz$. At the terminus of the string, where $z = z_0$, there is a sudden change in $m_z(z)$, from m_0 to zero. At this terminal point, therefore, $m'_z(z_0) = -m_0 \delta(z - z_0)$, yielding the magnetic charge-density of the string as follows:

$$\rho_m(\mathbf{r}) = -\boldsymbol{\nabla} \cdot \mathbf{M}(\mathbf{r})$$
$$= m_0 \delta[x - x_s(z_0)] \delta[y - y_s(z_0)] \delta(z - z_0). (A.2)$$

The strength of the magnetic monopole located at $[x_s(z_0), y_s(z_0), z_0]$ is thus seen to be m_0 , which has the dimensions of magnetic-dipole-moment-per-unit-length. In the SI system of units, m_0 is in webers. Note that while $\mathbf{m}(z)$ must terminate at $z = z_0$, the functions $x_s(z)$ and $y_s(z)$ may continue indefinitely beyond the terminal point.

To find the vector potential of the semi-infinite string, we first calculate its bound current-density, namely:

$$\begin{aligned} \mathbf{J}_{\text{bound}}(\mathbf{r}) &= \mu_0^{-1} \boldsymbol{\nabla} \times \mathbf{M}(\mathbf{r}) \\ &= \mu_0^{-1} \big\{ \partial_y [m_z \delta(x - x_s) \delta(y - y_s)] \\ &- \partial_z [m_y \delta(x - x_s) \delta(y - y_s)] \big\} \hat{\mathbf{x}} \\ &+ \mu_0^{-1} \big\{ \partial_z [m_x \delta(x - x_s) \delta(y - y_s)] \\ &- \partial_x [m_z \delta(x - x_s) \delta(y - y_s)] \big\} \hat{\mathbf{y}} \end{aligned}$$

$$+ \mu_{0}^{-1} \{ \partial_{x} [m_{y} \delta(x - x_{s}) \delta(y - y_{s})] \\ - \partial_{y} [m_{x} \delta(x - x_{s}) \delta(y - y_{s})] \} \hat{z}$$

$$= \mu_{0}^{-1} [m_{z} \delta(x - x_{s}) \delta'(y - y_{s}) \\ - \partial_{z} (m_{y}) \delta(x - x_{s}) \delta(y - y_{s}) \\ + m_{y} x_{s}' \delta'(x - x_{s}) \delta(y - y_{s}) \\ + m_{y} y_{s}' \delta(x - x_{s}) \delta'(y - y_{s})] \hat{x}$$

$$+ \mu_{0}^{-1} [\partial_{z} (m_{x}) \delta(x - x_{s}) \delta(y - y_{s}) \\ - m_{x} x_{s}' \delta'(x - x_{s}) \delta(y - y_{s}) \\ - m_{x} y_{s}' \delta(x - x_{s}) \delta'(y - y_{s}) \\ - m_{z} \delta'(x - x_{s}) \delta(y - y_{s})] \hat{y}$$

$$+ \mu_{0}^{-1} [m_{y} \delta'(x - x_{s}) \delta(y - y_{s})] \hat{z}. \qquad (A.3)$$

The vector potential at an arbitrary point \mathbf{r} is obtained by integrating over the volume of space (coordinates denoted by $\tilde{\mathbf{r}}$) which contains the bound currentdensity given by Eq. (A.3). The distance between the observation point \mathbf{r} and an arbitrary source point $\tilde{\mathbf{r}}$ is written:

$$|\mathbf{r} - \tilde{\mathbf{r}}| = \sqrt{(x - \tilde{x})^2 + (y - \tilde{y})^2 + (z - \tilde{z})^2}.$$
 (A.4)

In what follows, $\partial_{\tilde{x}} |\mathbf{r} - \tilde{\mathbf{r}}|^{-1}$ is replaced with $-\partial_x |\mathbf{r} - \tilde{\mathbf{r}}|^{-1}$ and $\partial_{\tilde{y}} |\mathbf{r} - \tilde{\mathbf{r}}|^{-1}$ with $-\partial_y |\mathbf{r} - \tilde{\mathbf{r}}|^{-1}$. When $\tilde{\mathbf{r}}$ happens to reside on the string, its distance to the observation point \mathbf{r} will be:

$$|\mathbf{r} - \mathbf{r}_s| = \sqrt{[x - x_s(\tilde{z})]^2 + [y - y_s(\tilde{z})]^2 + (z - \tilde{z})^2}.$$
(A.5)

In this case, we will have:

$$\partial_{\tilde{z}} |\mathbf{r} - \mathbf{r}_s|^{-1} = - \left[x'_s(\tilde{z}) \partial x + y'_s(\tilde{z}) \partial_y + \partial_z \right] |\mathbf{r} - \mathbf{r}_s|^{-1}.$$
(A.6)

The standard sifting properties of the δ -function, namely,

$$\int_{-\infty}^{\infty} f(x)\delta(x-\tilde{x})dx = f(\tilde{x}).$$

and:

$$\int_{-\infty}^{\infty} f(x)\delta'(x-\tilde{x})dx = -f'(\tilde{x})$$

will be used in the following derivations. The vector potential of the semi-infinite string may now be written as follows:

$$\begin{split} \mathbf{A}_{S}(\mathbf{r}) &= \frac{\mu_{0}}{4\pi} \iiint \frac{\mathbf{J}_{\text{bound}}(\tilde{\mathbf{r}})}{|\mathbf{r} - \tilde{\mathbf{r}}|} d\tilde{x} d\tilde{y} d\tilde{z} \\ &= \frac{\hat{\mathbf{x}}}{4\pi} \int \left\{ m_{z} \partial_{y} |\mathbf{r} - \mathbf{r}_{s}|^{-1} - \frac{\partial_{\tilde{z}}(m_{y})}{|\mathbf{r} - \mathbf{r}_{s}|} \right. \\ &+ m_{y} x_{s}' \partial_{x} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \\ &+ m_{y} y_{s}' \partial_{y} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \right\} d\tilde{z} \\ &+ \frac{\hat{\mathbf{y}}}{4\pi} \int \left\{ \frac{\partial_{\tilde{z}}(m_{x})}{|\mathbf{r} - \mathbf{r}_{s}|} - m_{x} x_{s}' \partial_{x} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \right. \\ &- m_{x} y_{s}' \partial_{y} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \\ &- m_{z} \partial_{x} |\mathbf{r} - \mathbf{r}_{s}|^{-1} \right\} d\tilde{z} \\ &+ \frac{\hat{\mathbf{z}}}{4\pi} \int (m_{y} \partial_{x} - m_{x} \partial_{y}) |\mathbf{r} - \mathbf{r}_{s}|^{-1} d\tilde{z}. \quad (A.7) \end{split}$$

The integral $\int \partial_{\tilde{z}}(m_x) |\mathbf{r} - \mathbf{r}_s|^{-1} d\tilde{z}$ can be evaluated using the method of integration by parts, namely:

$$\int_{\infty}^{z_0^+} \frac{\partial_{\tilde{z}}(m_x)}{|\mathbf{r} - \mathbf{r}_s|} d\tilde{z} = \frac{m_x(\tilde{z})}{|\mathbf{r} - \mathbf{r}_s|} \Big|_{\infty}^{z_0^+} + \int_{\infty}^{z_0^+} m_x(\tilde{z}) (x'_s \partial_x + y'_s \partial_y + \partial_z) |\mathbf{r} - \mathbf{r}_s|^{-1} d\tilde{z}.$$
 (A.8)

Note that the first term on the right-hand-side of Eq. (A.8) vanishes at both ends of the string. A similar procedure can be applied to $\int \partial_{\bar{z}}(m_y) |\mathbf{r} - \mathbf{r}_s|^{-1} d\bar{z}$. Substitution into Eq. (A.7) and using the fact that $m_x = x'_s m_z$ and $m_y = y'_s m_z$ now yields:

$$\begin{split} \mathbf{A}_{S}(\mathbf{r}) &= \frac{\hat{\mathbf{x}}}{4\pi} \int m_{z} (\partial_{y} - y_{s}^{\prime} \partial_{z}) |\mathbf{r} - \mathbf{r}_{s}|^{-1} d\tilde{z} \\ &+ \frac{\hat{\mathbf{y}}}{4\pi} \int m_{z} (x_{s}^{\prime} \partial_{z} - \partial_{x}) |\mathbf{r} - \mathbf{r}_{s}|^{-1} d\tilde{z} \\ &+ \frac{\hat{\mathbf{z}}}{4\pi} \int m_{z} (y_{s}^{\prime} \partial_{x} - x_{s}^{\prime} \partial_{y}) |\mathbf{r} - \mathbf{r}_{s}|^{-1} d\tilde{z}. (A.9) \end{split}$$

Finally, noting that $m_z = m_0$, and that an infinitesimal segment of the string may be described as $d\ell = (x'_s \hat{\mathbf{x}} + y'_s \hat{\mathbf{y}} + \hat{\mathbf{z}})d\tilde{z}$, one may further simplify Eq. (A.9) to arrive at:

$$\mathbf{A}_{S}(\mathbf{r}) = \frac{m_{0}}{4\pi} \int_{\infty}^{z_{0}} (\boldsymbol{\nabla}_{r} |\mathbf{r} - \mathbf{r}_{s}|^{-1}) \times d\boldsymbol{\ell}.$$
 (A.10)

The above expression of $\mathbf{A}_{S}(\mathbf{r})$ has the expected form of an integral over the vector potentials produced by elemental dipoles whose continuous arrangement constitutes the string. Jackson rightly uses Eq. (A.10) as the starting point of his analysis in [2]. Our lengthy derivation of Eq. (A.10) has not uncovered any problems with this straightforward integration of the contributions by infinitesimal dipoles to the vector potential at the observation point \mathbf{r} . The exercise is nevertheless worthwhile considering that it is not a *priori* obvious that the arbitrary turns and twists of a tightly wound solenoid will *not* cause a leakage of its internal magnetic flux. Our rigorous treatment of the long thin string thus confirms that it is possible to avoid producing magnetic charges along the string without constraining its geometric configuration.

Appendix B

Use $\nabla \times (\psi \mathbf{A}) = \nabla \psi \times \mathbf{A} + \psi \nabla \times \mathbf{A}$ in going from Eq. (6a) to Eq. (6b) and also from Eq. (6e) to Eq. (6f); use $\oint_c \psi d\ell = -\int_s \nabla \psi \times d\sigma$ in going from Eq. (6c) to Eq. (6d); use $\nabla \times (\nabla \times \mathbf{A}) = \nabla (\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$ in going from Eq. (6f) to Eq. (6g); use $\nabla \cdot (\psi \mathbf{A}) =$ $\mathbf{A} \cdot \nabla \psi + \psi \nabla \cdot \mathbf{A}$ in going from Eq. (6g) to Eq. (6h); use $\nabla^2 |\mathbf{r}^{-1}| = -4\pi \delta_3(\mathbf{r})$ in going from Eq. (6h) to Eq. (6i).

In Eq. (6j), the solid angle subtended by the surface element $d\sigma$ located at \mathbf{r}_s and viewed from \mathbf{r} is $d\Omega(\mathbf{r}; \mathbf{r}_s)$.

When the observation point \mathbf{r} resides outside the surface s, the second integral in Eq. (6j) vanishes.

In Eq. (6k), r_{\perp} is the perpendicular distance from the observation point **r** to the surface *s*. As **r** approaches *s*, the unit-vector $\hat{\mathbf{r}}_{\perp}$ coincides with the local surface-normal.

Biography

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