

Research Note

Sharif University of Technology

Scientia Iranica Transactions B: Mechanical Engineering www.scientiairanica.com



Comparison and successive iteration of approximate solution of ordinary differential equations with initial conditions by the new modified Krasnoselskii iteration method

N. Bildik*, Y. Bakir and A. Mutlu

Celal Bayar University, Faculty of Arts and Science, Department of Mathematics, Muradiye Campus, 45030, Manisa, Turkey.

Received 9 May 2012; received in revised form 7 January 2013; accepted 20 April 2013

KEYWORDS

Ordinary differential equation; Euler method; Fixed point; Modified Krasnoselskii iteration method; Numerical analysis; Picard successive iteration method. **Abstract.** In this paper, we used the Picard successive iteration method and the new modified Krasnoselskii iteration method in order to solve different types of ordinary linear differential equations having initial conditions. By applying the new modified Krasnoselskii iteration method, not only do we obtain the approximate solutions for the problem, but also establish the corresponding iterative schemes. Finally, it is shown that the accuracy of the new iteration method (called the new modified Krasnoselskii iteration method) is substantially improved by employing variable steps which adjust themselves to the solution of the differential equation.

© 2013 Sharif University of Technology. All rights reserved.

1. Introduction

Iterative methods such as the Krasnoselskii method are increasingly being used for many mathematical models in science and engineering in order to solve the different types of ordinary differential equations. In fact, Krasnoselskii iteration method is considered an alternative solution to the linear differential equations having initial conditions. The theory of this iteration method has been extensively studied by several authors [1-3].

The authors [4,5] have used the fixed point theorem and also iteration to solve the differential equations. The fixed point theory on normed linear space was first presented by L.E.J. Brouwer in 19091913 [6]. Subsequently, several authors investigated the theorem for different types of spaces, such as metric [7], Banach [4,8] and Hilbert [9], respectively.

The fixed point theorem has become important, in recent years, as a mathematical model of phenomena in biology [10], electrical engineering [11,12], and so on.

There has been a significant development in this theory especially in the area of non-linear differential equations having boundary conditions. Recently, Sun [13] discussed the existence and successive iteration of positive solutions of boundary value problems, and He [14,15] proposed a new perturbation method using the homotopy technique. The presented method, requiring no parameters in the equation, can readily eliminate the limitations of the traditional perturbation methods.

Motivated by this work, we defined the new modified Krasnoselskii iteration method, in order to solve ordinary linear differential equations having initial conditions. Additionally, we compared the numerical

^{*.} Corresponding author. E-mail addresses: necdet.bildik@bayar.edu.tr (N. Bildik), jasmin_demirel@hotmail.com (Y. Bakir), ali.mutlu@bayar.edu.tr (A. Mutlu).

results using the Euler Method [16,17], Runge-Kutta Method [16-20] and Picard iteration method [16,17] according to the exact solution. Comparison of the numerical results show that the new modified Krasnoselskii iteration method is effective and convenient for solving different types of linear differential equations.

On the other hand, the variational iteration method will be more fully explained and applied to the differential type of the linear and nonlinear problem in another paper where the relationship compared with other techniques will be given in detail.

2. Preliminaries

Some basic definitions and properties of the new modified Krasnoselskii iteration method used in this paper are required. X is the metric linear spaces of the continuous function and $T: X \to Y$ is a given operator with $x \in X$.

Krasnoselskii [5] proved that the sequence of iteration $\{T^n(x_0)\}$, starting from a given point, $x_0 \in E$, does not converge necessarily to a fixed point of T, whereas the sequence $\{T_{\lambda}^{n}(x_{0})\}$ where $T_{\lambda} = (1-\lambda)I +$ $\lambda T, 0 < \lambda \leq 1$ may converges to a fixed point of T, as shown by Krasnoselskii [5], who assumes $\lambda =$ 1/2. Here, E is compact and X is uniformly convex. This topic of research plays an important role in the stability problem of fixed point iterations. In 1995, Liu [21] initiated a study of fixed point iterations with errors. On the other hand, there are some attempts in the double sequence setting [22,23]. The fixed point theorems, presented in this paragraph, are all related to the Banach contraction principle, which asserts that every complete metric space is a fixed point space for the class of contractive mappings.

2.1. Banach contraction principle

The Banach contraction principle is the simplest and one of the most versatile elementary results in fixed point theory. Based on an iteration process, it can be implemented on a computer to find the fixed point of a contractive map. It produces approximations of any required accuracy. Even, the number of iterations needed to get a specified accuracy can be determined [24].

Theorem 1. (Banach contraction principle). Let (Y, d) be a complete metric space and $T : Y \to Y$ be contractive. Then T has a unique fixed point u, and $T^n(y) \to u$ for each $y \in Y$ (see [24]).

The Banach principle has a useful local version that involves an open ball, B, in a complete metric space, Y, and a contractive map of B into Y which does not displace the center of the ball too far:

Corollary 1. Let (Y, d) be complete and B =

 $B(y_0,r) = \{y|d(y,y_0) < r\}$. Let $T : B \to Y$ be a contractive map with constant $\alpha < 1$. If $d(T(y_0), y_0) < (1-\alpha)r$, then T has a fixed point (see [24]).

Proof. Choose $\varepsilon < r$, such that $d(Ty_0, y_0) < (1 - \alpha)\varepsilon < (1 - \alpha)r$. We show that T maps the closed ball, $K = \{y|d(y, y_0) \le \varepsilon\}$, into itself: for, if $y \in K$, then:

$$d(Ty, y_0) \le d(Ty, Ty_0) + d(Ty_0, y_0) \le \alpha d(y, y_0)$$
$$+ (1 - \alpha)\varepsilon < \varepsilon.$$

Since K is complete, then the conclusion of corollary 1 is proved by Banach contraction principle. \Box

Definition 1. If the $\{x_n\}_{n=0}^{\infty}$ sequence provides the condition $x_{n+1} = Tx_n$ for $n = 0, 1, 2, \dots$, then this is called Picard iteration [25].

Definition 2. If $x_0 \in X$, $\lambda \in [0,1]$ and also the $\{x_n\}_{n=0}^{\infty}$ sequence provides the condition $x_{n+1} = (1-\lambda)x_n + \lambda T x_n$ for $n = 0, 1, 2, \cdots$ then this is called Krasnoselskii iteration [26].

Definition 3. If $\lambda \in [0,1]$, $x_0 \in X$ and T is defined as the contraction mapping with regards to Picard iteration, and also the $\{x_n\}_{n=0}^{\infty}$ sequence provides the conditions:

$$y_{n+1} = y_0 + \int_{x_0}^{x} F(t, y_n(t)) dt \qquad n = 0, 1,$$

$$y_{n+1} = (1 - \lambda)y_n + \lambda T y_{n-2} \qquad n = 2, 3, \cdots$$

$$T y_{n-1} = y_n \qquad 0 < \lambda < 1,$$

then this is called a modified Krasnoselskii iteration.

3. Application of methods

Example 1. Let us consider the initial value problem:

$$y' = \sqrt{|y|}$$
 $y(0) = 1.$ (1)

By Theorem 1 and Corollary 1, since $T = \int_{x_0}^{x} F(t, y_n(t))$, then:

$$|T(x) - T(y)| = \left| \int_{0}^{x} \sqrt{t} - \int_{0}^{y} \sqrt{t} \right|$$
$$= \left| \le \frac{2}{3} \right| \sqrt{x^{3}} - \sqrt{y^{3}} \left| \le \frac{2}{3} |x - y|,$$

is obtained. So:

$$|T(x) - T(y)| \le \frac{2}{3}|x - y|,$$

is found. Thus, T has a unique fixed point, which is the unique solution of integral equation $T = \int_{x_0}^x F(t, y_n(t))$ or the differential equation, $y' = \sqrt{|y|} y(0) = 1$. Firstly, we obtained the exact solution of the equation as $|y| = \frac{1}{4}(x+2)^2 = 1 + x + \frac{x^2}{4}$. Then we approached the approximate solution using by the Picard iteration method. Thus the followings are obtained:

$$y_1 = 1 + x,$$

 $y_2 = \frac{1}{3} + \frac{2}{3}(x+1)^{3/2},$

 $y_1 = 1 + x,$

If we use the Maclauren series expansion for the seventh term of y_2 then:

$$y_2 = 1 + x + \frac{x^2}{4} + \frac{x^3}{24} + \frac{x^4}{64} + \frac{x^5}{128} + \frac{7x^6}{1536}$$

is found. Now, applying the modified Krasnoselskii iteration method to Eq. (1) for $\lambda = 0, 5$ the followings are obtained:

$$\begin{split} y_2 &= 1 + x + \frac{x^2}{4} - \frac{x^3}{24} + \frac{x^4}{64} - \frac{x^5}{128} + \frac{7x^6}{1536}, \\ y_3 &= 1 + x + \frac{x^2}{8} - \frac{x^3}{48} + \frac{x^4}{128} - \frac{x^5}{256} + \frac{7x^6}{3072}, \\ y_4 &= 1 + x + 0.1875x^2 - 0.03125x^3 \\ &\quad + 0.01171875x^4 - 0.005859375x^5 \\ &\quad + 0.00341796875x^6, \\ y_5 &= 1 + x + 0.15625x^2 - 0.026041666x^3 \\ &\quad + 0.009765625x^4 - 0.0048828125x^5 \\ &\quad + 0.002848307292x^6, \\ y_6 &= 1 + x + 0.171875x^2 - 0.028645833x^3 \\ &\quad + 0.010742187x^4 - 0.00537109375x^5 \\ &\quad + 0.003133138021x^6, \\ y_7 &= 1 + x + 0.1640625x^2 - 0.027343749x^3 \\ &\quad + 0.010253906x^4 - 0.005126953125x^5 \\ &\quad + 0.002990722657x^6, \end{split}$$

and for $\lambda = 0.4$, the followings are calculated:

$$\begin{split} y_1 &= 1 + x, \\ y_2 &= 1 + x + \frac{x^2}{4} - \frac{x^3}{24} + \frac{x^4}{64} - \frac{x^5}{128} + \frac{7x^6}{1536}, \\ y_3 &= 1 + x + 0.15x^2 - 0.025x^3 + 0.009375x^4 \\ &- 0.0046875x^5 + 0.002734375x^6, \\ y_4 &= 1 + x + 0.19x^2 - 0.03167x^3 + 0.011875x^4 \\ &- 0.0059375x^5 + 0.003463541667x^6, \end{split}$$

$$y_5 = 1 + x + 0.174x^2 - 0.029002x^3 + 0.010875x^4$$
$$- 0.00454375x^5 + 0.013015625x^6,$$
$$y_6 = 1 + x + 0.1804x^2 - 0.0300692x^3 + 0.011275x^4$$
$$- 0.0056375x^5 + 0.009194791667x^6.$$

On the other hand, for $\lambda = 0.9$ the followings are founds:

$$\begin{split} y_1 &= 1 + x, \\ y_2 &= 1 + x + \frac{x^2}{4} - \frac{x^3}{24} + \frac{x^4}{64} - \frac{x^5}{128} + \frac{7x^6}{1536}, \\ y_3 &= 1 + x + 0.025x^2 - 0.0041666666667x^3 \\ &+ 0.0015625x^4 - 0.0078125x^5 \\ &+ 0.0004557291667x^6, \\ y_4 &= 1 + x + 0.2275x^2 - 0.037916666x^3 \\ &+ 0.01421875x^4 - 0.007109375x^5 \\ &+ 0.004147135417x^6, \\ y_5 &= 1 + x + 0.04525x^2 - 0.014291666x^3 \\ &+ 0.002828125x^4 - 0.0014140625x^5 \\ &+ 0.0008248697917x^6. \\ \end{split}$$

 $y_1 = 1 + x,$

1794

$$y_{2} = 1 + x + \frac{x^{2}}{4} - \frac{x^{3}}{24} + \frac{x^{4}}{64} - \frac{x^{5}}{128} + \frac{7x^{6}}{1536},$$

$$y_{3} = 1 + x + 0.029975x^{2} - 0.00416625x^{3} + 0.015623437x^{4} - 0.00781171875x^{5} + 0.0004556835938x^{6},$$

$$y_{4} = 1 + x + 0.249975002x^{2} - 0.0416625x^{3} + 0.015623437x^{4} - 0.007811718828x^{5} + 0.00455683598x^{6}.$$

Now we tend the approximate solution, using by the Euler method. Firstly, we use formula:

$$y_{n+1} = y_n + hF(x_n, y_n),$$

with $F(x, y) = \sqrt{|y|}, h = 0.2$ and $x_0 = 0$

From the initial condition, y(0) = 1, we have F(0,1) = 1. We now proceed with the calculations coomputed as follows:

 $y_0 = 1.$

$$y_1 = y_0 + hF(y_0, x_0) = 1 + 0.2 = 1.200,$$

$$x_1 = x_0 + h = 1.000 + 0.200 = 1.200,$$

$$y_2 = y_1 + hF(y_1, x_1) = 1.2 + 0.2 \cdot 1.095445115$$

$$= 1.419089023,$$

$$x_2 = x_1 + h = 1.200 + 0.200 = 1.400,$$

$$y_3 = y_2 + hF(y_2, x_2)$$

 $= 1.419089023 + 0.2 \cdot 1.19125523$

$$= 1.657340069,$$

$$x_3 = x_2 + h = 1.400 + 0.200 = 1.600.$$

Finally, applying the Runge-Kutta method to the given initial value problem, we carry out the intermediate calculations in each step to give figures after the decimal point and round off the final results each step to four such places.

Here, $F(x,y) = \sqrt{|y|}$, $x_0 = 0$ and $y_0 = 1$, and we are to use h = 0.2. Using these quantities, we calculated, successively, k_1 , k_2 , k_3 , k_4 and K_0 defined by:

1

$$k_{1} = hg(y_{0}, x_{0}),$$

$$k_{2} = hg\left(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{1}}{2}\right),$$

$$k_{3} = hg\left(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{2}}{2}\right),$$

$$k_{4} = hg(y_{0} + h, x_{0} + k_{3}),$$

and $K_0 = \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)y_{n+1} = y_n + K_0$. Thus we find k_1, k_2, k_3 and k_4 for n = 0 as:

$$k_{1} = hF(x_{0}, y_{0}) = 0.20000000,$$

$$k_{2} = hF\left(x_{0} + \frac{h}{2}, y_{0} + \frac{k_{1}}{2}\right) = 0.209761769,$$

$$k_{3} = hF\left(x_{0} + \frac{h}{2}, y_{0} + \frac{k_{2}}{2}\right) = 0.2102266628,$$

$$k_{4} = hF(x_{0} + h, y_{0} + k_{3}) = 0.220020601.$$

So, $y_1 = 1.209999565$ is obtained for $x_1 = 0.2$. On the other hand, we calculate k_1 , k_2 , k_3 and k_4 for n = 1 as:

$$k_{2} = hF\left(x_{1} + \frac{h}{2}, y_{1} + \frac{k_{1}}{2}\right) = 0.229782466,$$

$$k_{3} = hF\left(x_{1} + \frac{h}{2}, y_{1} + \frac{k_{2}}{2}\right) = 0.230207801,$$

$$k_{4} = hF(x_{1} + h, y_{1} + k_{3}) = 0.240017279.$$

Hence, $y_2 = 1.4399999194$ is calculated for $x_2 = 0.4$. Finally, we get k_1 , k_2 , k_3 and k_4 for n = 2 as:

 $k_1 = hF(x_2, y_2) = 0.239999993,$

 $k_1 = hF(x_1, y_1) = 0.21999996,$

$$k_{2} = hF\left(x_{2} + \frac{h}{2}, y_{2} + \frac{k_{1}}{2}\right) = 0.249799913,$$

$$k_{3} = hF\left(x_{2} + \frac{h}{2}, y_{2} + \frac{k_{2}}{2}\right) = 0.2250191916,$$

$$k_4 = hF(x_2 + h, y_2 + k_3) = 0.260014756.$$

Thus, $y_3 = 1.689999654$ is obtained for $x_3 = 0.6$.

After the necessary calculations shown above, a comparison is shown, schematically, in Figure 1.

On the other hand we show Tables 1 and 2 concerning the Picard iteration method, Euler method, Runge-Kutta method and the modified Krasnoselskii iteration method for different values of lambda. iteration method for different values of λ , Picard iteration method, Euler method and Runge-Kutta method.

	Ν	Aodified Krasnosels	skii iteration		
\boldsymbol{x}	$\lambda = 0.0001$	$\lambda=0.4$	$\lambda=0.5$	$\lambda=0.9$	
	$y_1 = 1.21$	$y_1 = 1.2$	$y_1 = 1.2$	$y_1 = 1.2$	
	$y_2 = 1.2097$	$y_2 = 1.2097$	$y_2 = 1.2097$	$y_2 = 1.2097$	
	$y_3 = 1.209688489$	$y_3 = 1.205813675$	$y_3 = 1.204844729$	$y_3 = 1.200966916$	
0.2	$y_4 = 1.209688489$	$y_4 = 1.207363962$	$y_4 = 1.207267094$	$y_4 = 1.20881740$	
		$y_5 = 1.206744477$	$y_5 = 1.206055911$	$y_5 = 1.201483792$	
		$y_6 = 1.206992271$	$y_6 = 1.206661503$		
			$y_7 = 1.206358707$		
	$y_1 = 1.4$	$y_1 = 1.4$	$y_1 = 1.4$	$y_1 = 1.4$	
	$y_2 = 1.437672$	$y_2 = 1.437672$	$y_2 = 1.437672$	$y_2 = 1.437672$	
	$y_3 = 1.437668233$	$y_3 = 1.4226032$	$y_3 = 1.418836$	$y_3 = 1.4036952$	
0.4	$y_4 = 1.437668233$	$y_4 = 1.428630507$	$y_4 = 1.428254$	$y_4 = 1.43428152$	
		$y_5 = 1.426259904$	$y_5 = 1.423545$	$y_5 = 1.404644632$	
		$y_6 = 1.427208145$	$y_6 = 1.4258995$		
			$y_7 = 1.42472225$		
	$y_1 = 1.6$	$y_1 = 1.6$	$y_1 = 1.6$	$y_1 = 1.6$	
	$y_2 = 1.682630125$	$y_2 = 1.682630125$	$y_2 = 1.682630125$	$y_2 = 1.682630125$	
	$y_3 = 1.6826218662$	$y_3 = 1.649578075$	$y_3 = 1.641315063$	$y_3 = 1.607716263$	
0.6	$y_4 = 1.682621863$	$y_4 = 1.662797175$	$y_4 = 1.661972594$	$y_4 = 1.675193414$	
		$y_5 = 1.657969405$	$y_5 = 1.651643828$	$y_5 = 1.607666053$	
		$y_6 = 1.659900913$	$y_6 = 1.656808211$		
			$y_7 = 1.65422602$		
x	Picard	Runge-Kutta	Euler	Exact solution	
0.2	$y_1 = 1.2$	$y_1 = 1.209999565$	$y_1 = 1.2$	y = 1.21	
	$y_2 = 1.2097$	91 1.20000000	yı	y 1.21	
0.4	$y_1 = 1.4$	$y_1 = 1.4399999194$	$y_1 = 1.419089023$	y = 1.44	
	$y_2 = 1.437672$	$y_1 = 1.1000000104$	$y_1 = 1.115005020$	y — 1.11	
0.6	$y_1 = 1.6$	$y_1 = 1.689999654$	$y_1 = 1.657340069$	y = 1.69	
0.0	$y_2 = 1.682630125$	91 - 1.000000004	91 - 1.001040000		

Table 1. Comparison of the solutions obtained by the modified Krasnoselskii iteration method, Picard iteration method, Runge-Kutta method, and Euler method with the exact solution for different values of λ .

Table 2. Absolute error of Example 1 for different values of λ (x = 0.2, x = 0.4 and x = 0.6, respectively).

	Absolute error table								
Modified Krasnoselskii iteration									
x	$\lambda=0.0001$		$\lambda=0.4$		$\lambda=0.5$		$\lambda = 0.9$		
0.2	3.1	1511 :	$\times 10^{-4}$	3.007729	$\times 10^{-3}$	3.64129	3×10^{-3}	8.51620	8×10^{-3}
0.4	2.331767×10^{-3}		1.279185	5×10^{-2}	1.527775×10^{-2}		3.5355368×10^{-1}		
0.6	7.378137×10^{-3}		3.0099087×10^{-2} 3.		3.57739	3.577398×10^{-2}		7×10^{-2}	
		x	Pi	card	Runge-	Kutta	Eul	ler	
		0.2	3×10^{-1}	- 4	4.35×1	0-7	0.01		
		0.4	$2.328 \times$	10^{-3}	8.1×10	-8	2.0910977	7×10^{-2}	
		0.6	7.36987	75×10^{-3}	4.6×10	-7	3.2659931	1×10^{-2}	

N. Bildik et al./Scientia Iranica, Transactions B: Mechanical Engineering 20 (2013) 1792-1804

y



Figure 1. Comparison of the exact solution with approximation solution of Example 1 for different values of λ .

Corollary 2. If the approximate solution compares with the different values of λ , then the conclusion may be indicated, by Table 1.

The best approximation is obtained taking different values of λ using the modified Krasnoselskii iteration method for x = 0.2 getting $\lambda = 0.9$, $\lambda = 0.5$, $\lambda = 0.4$ and $\lambda = 0.0001$, respectively, in accordance with the solution using the Picard iteration method, Runge-Kutta method, Euler iteration method and the exact solution.

Once, we obtain the solution for x = 0.4, then, the approximation is obtained to be more sensitive for $\lambda = 0.9, \lambda = 0.5, \lambda = 0.4$ and $\lambda = 0.0001$, respectively, using the modified Krasnoselskii iteration method.

Similarly, we calculated the solution for x = 0.6. Then the approximation is found to be more sensitively, for $\lambda = 0.9$, $\lambda = 0.5$, $\lambda = 0.4$ and $\lambda = 0.0001$, respectively, using the modified Krasnoselskii iteration method.

Consequently, the solution, using the modified Krasnoselskii iteration method, gives more accurate results than the solution of the Picard iteration method, Runge-Kutta method, and Euler method for different values of λ .

Corollary 3. Absolute error of the modified Krasnoselskii iteration method is computed for different values of λ which is more effective than that of the Euler method, but not better than the Runge-Kutta method and Picard iteration method, in accordance with Table 2.

Example 2. Let us consider the differential equation:

$$y' = \frac{y}{x + \ln y}$$
 $y(1) = 1,$ (2)

subject to the initial condition.

In accordance with the nature of the given differential equation, we define:

$$f(x,y) = \frac{y}{x + \ln y}, \qquad f(1,1) = 1 \neq 0, \tag{3}$$

and $\frac{df}{dx} = -\frac{y}{(x+\ln y)^2}$. Thus, the function $\frac{df}{dx}$ is bounded in the rectangular domain including point (1, 1). In this case, if y = y(x) is the local solution of this problem, then its inverse function is also the solution of:

$$x' = g(y, x), \qquad x(y_0) = x_0.$$
 (4)

Now, we state the method of successive approximation with $g(y, x) = \frac{1}{f(x,y)}$. Hence the solution x = x(y) of Problem (4) is also the solution of the problem:

$$y' = f(x, y), \qquad y(x_0) = y_0,$$
 (5)

which is the inverse solution of Problem (4). Therefore:

$$x_{n+1}(y) = x_0 + \int_{y_0}^{y} g(t, x_n(t)) dt.$$

Thus:

$$x_{n+1}(y) = 1 + \int_{1}^{y} g(t, x_n(t)) dt$$
$$= 1 + \ln y + \int_{1}^{y} \frac{x_n(t) + \ln(t)}{t} dt,$$

for $x_0 = 1$ and $y_0 = 1$. So, we may write:

$$x_{n+1}(y) = 1 + \ln y + \int_{1}^{y} \frac{x_n(t)}{t} dt$$

Using Theorem 1 and Corollary 1, since $T = \int_{y_0}^{y} F(t, x_n(t)) dt$, then T has a unique fixed point which is the unique solution of the differential equation $y' = \frac{y}{x + \ln y}$, having the initial condition y(1) = 1.

Hence we approach the approximate solution, using the Picard iteration method. Thus:

$$x_1(y) = 1 + \ln y + \frac{\ln^2 y}{2},$$

$$x_2(y) = 1 + \ln y + \ln^2 y + \frac{\ln^3 y}{6},$$

$$x_3(y) = 1 + \ln y + \ln^2 y + \frac{\ln^3 y}{3} + \frac{\ln^4 y}{24}$$

1797

Consequently, solution $x = 2y - 1 - \ln y$ is obtained as $n \to \infty$.

On the other hand the exact solution of the equation is $x = 2y - 1 - \ln y$, which coincides with the approximate solution.

Now, applying the modified Krasnoselskii iteration method to the equation for $\lambda = 0, 5$, then:

$$\begin{aligned} x_1(y) &= 1 + \ln y + \frac{\ln^2 y}{2}, \\ x_2(y) &= 1 + \ln y + \ln^2 y + \frac{\ln^3 y}{3}, \\ x_3(y) &= 1 + \ln y + \frac{3}{4} \ln^2 y + \frac{1}{6} \ln^3 y, \\ x_4(y) &= 1 + \ln y + \frac{7}{8} \ln^2 y + \frac{1}{4} \ln^3 y, \\ x_5(y) &= 1 + \ln y + \frac{13}{16} \ln^2 y + \frac{5}{24} \ln^3 y, \\ x_6(y) &= 1 + \ln y + \frac{27}{32} \ln^2 y + \frac{11}{48} \ln^3 y, \end{aligned}$$

are obtained and also for $\lambda = 0.9$,

$$\begin{aligned} x_1(y) &= 1 + \ln y + \frac{\ln^2 y}{2}, \\ x_2(y) &= 1 + \ln y + \ln^2 y + \frac{\ln^3 y}{3}, \\ x_3(y) &= 1 + \ln y + 0.55 \ln^2 y + 0.033 \ln^3 y, \\ x_4(y) &= 1 + \ln y + 0.955 \ln^2 y + 0.3033 \ln^3 y, \\ x_5(y) &= 1 + \ln y + 0.5905 \ln^2 y + 0.06003 \ln^3 y, \\ x_6(y) &= 1 + \ln y + 0.91855 \ln^2 y + 0.278973 \ln^3 y, \end{aligned}$$

are calculated. At last, for $\lambda = 0.01$:

$$\begin{split} x_1(y) &= 1 + \ln y + \frac{\ln^2 y}{2}, \\ x_2(y) &= 1 + \ln y + \ln^2 y + \frac{\ln^3 y}{3}, \\ x_3(y) &= 1 + \ln y + 0.995 \ln^2 y + 0.33 \ln^3 y, \\ x_4(y) &= 1 + \ln y + 0.99505 \ln^2 y + 0.330033333 \ln^3 y, \\ x_5(y) &= 1 + \ln y + 0.99504495 \ln^2 y + 0330033 \ln^3 y, \\ x_6(y) &= 1 + \ln y + 0.995049505 \ln^2 y + 0330033003 \ln^3 y, \\ are found. \end{split}$$

Now, we tend the approximate solution using the Euler method. Firstly, we use formula:

$$x_{n+1} = x_n + hg(y_n, x_n),$$

with $g(y, x) = \frac{x + \ln y}{y}$ and h = 0.2, such that $f(x, y) = \frac{y}{x + \ln y}$.

From the initial condition y(1) = 1, we have $x_0 = 1, y_0 = 1$. We now proceed with the calculations starting with $g(y_0, x_0) = g(1, 1) = 1.000$, then:

a)
$$x_1 = x_0 + hg(y_0, x_0) = 1.200,$$

 $y_1 = y_0 + h = 1.000 + 0.2 = 1.200.$

- b) $x_2 = x_1 + hg(y_1, x_1) = 1.430386926,$ $y_2 = y_1 + h = 1.2000 + 0.2 = 1.400.$
- c) $x_3 = x_2 + hg(y_2, x_2) = 1.682795378,$ $y_3 = y_2 + h = 1.400 + 0.2 = 1.600.$

Finally, applying the Runge-Kutta method to the given initial value problem, we carry out the intermediate calculations in each step to give figures after the decimal point and round off the final results at each step to four such places.

Here, $g(y, x) = \frac{x + \ln y}{y}$, $x_0 = 1$, $y_0 = 1$, and we are to use h = 0.2. Using these quantities, we calculate, successively, k_1 , k_2 , k_3 , k_4 and K_0 defined by:

$$k_{1} = hg(y_{0}, x_{0}),$$

$$k_{2} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{1}}{2}),$$

$$k_{3} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{2}}{2}),$$

$$k_{4} = hg(y_{0} + h, x_{0} + k_{3}),$$

and $K_0 = \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4), y_{n+1} = y_n + K_0$. Thus, we find k_1, k_2, k_3, k_4 for n = 0 starting with g(1,1) = 0.20000000, then:

$$k_{1} = hg(y_{0}, x_{0}) = 0.20000000,$$

$$k_{2} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{1}}{2}) = 0.217329123,$$

$$k_{3} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{2}}{2}) = 0.218904498,$$

$$k_{4} = hg(y_{0} + h, x_{0} + k_{3}) = 0.233537675.$$

So, $x_1 = 1.217667486$ is obtained for $y_1 = 1.20000000$. On the other hand, we calculate k_1 , k_2 , k_3 , k_4 for n = 1, as:

$$k_1 = hg(y_1, x_1) = 0.23333507,$$

$$k_2 = hg(y_1 + \frac{h}{2}, x_1 + \frac{k_1}{2}) = 0.245645769,$$

$$k_3 = hg(y_1 + \frac{h}{2}, x_1 + \frac{k_2}{2}) = 0.24659302,$$

$$k_4 = hg(y_1 + h, x_1 + k_3) = 0.257247534.$$

Hence $x_2 = 1.463510256$ is calculated for $y_2 = 1.40000000$.

Finally, we get k_1 , k_2 , k_3 , k_4 for n = 2 as:

$$k_1 = hg(y_2, x_2) = 0.257140356,$$

$$k_{2} = hg(y_{2} + \frac{h}{2}, x_{2} + \frac{k_{1}}{2}) = 0.266339405,$$

$$k_{3} = hg(y_{2} + \frac{h}{2}, x_{2} + \frac{k_{2}}{2}) = 0.266952675,$$

$$k_4 = hg(y_2 + h, x_2 + k_3) = 0.27505832.$$

Thus, $x_3 = 1.729974062$ is obtained for $y_3 = 1.60000000$.

After the necessary calculations, the comparison is shown schematically in Figure 2.

Now we show Tables 3 and 4 concerning the Picard iteration method, Euler method, Runge-Kutta method and the modified Krasnoselskii iteration method for different values of *lambda*. method for different values of λ , the Picard iteration method, Euler method and Runge-Kutta method.



Figure 2. Comparison of the exact solution with the approximation solution of Example 2 for different values of λ .

Corollary 4. If the approximate solution compares with the different values of λ , then the conclusion may be presented using Table 3.

The best approximation may be obtained for different values of λ , using the modified Krasnoselskii iteration method for x = 1.2, getting $\lambda = 0.9$, $\lambda = 0.5$ and $\lambda = 0.001$, respectively, in accordance with the solution of the Picard iteration method, Runge-Kutta method, Euler method and exact solution.

We obtained the solution for y = 1.4, then, taking $\lambda = 0.9$, $\lambda = 0.5$ and $\lambda = 0.01$, respectively, using the modified Krasnoselskii iteration method.

Similarly, we calculated the solution for y = 1.6, then, the approximation is found to be more sensitive than for $\lambda = 0.9$, $\lambda = 0.5$ and $\lambda = 0.01$, respectively, using the modified Krasnoselskii iteration method.

Consequently, the solution, using the modified Krasnoselskii iteration method, gives more accurate results than the solutions of the Picard iteration method, Runge-Kutta method and Euler method for different values of λ .

Corollary 5. The absolute error of the modified Krasnoselskii iteration method, calculated for different values of λ , is more effective than the Euler method but not better than the Runge-Kutta method and Picard iteration method, according to Table 4.

Example 3. Let us consider the differential equation

$$y' = 2x(y+1),$$
 (6)

subject to the initial condition:

$$y(0) = 0$$

Using Theorem 1 and Corollary 1, since $T = \int_{x_0}^{x} F(t, y_n(t)) dt$, then T has a unique fixed point which is the unique solution of the differential equation y' = 2x(y+1), having the initial condition y(0) = 0.

Firstly, we obtain the exact solution of the equation as $y = e^{x^2} - 1$. Then, we approach the approximate solution, using the Picard iteration method as follows:

$$y_1 = x^2,$$

$$y_2 = x^2 + \frac{x^4}{2},$$

$$y_3 = x^2 + \frac{x^4}{2} + \frac{x^6}{6},$$

$$y_4 = x^2 + \frac{x^4}{2!} + \frac{x^6}{3!} + \frac{x^8}{4!}.$$

		Modified Krasnoselskii iteration						
	\boldsymbol{y}	$\lambda = 0.$	01	$\lambda = 0$).5	$\lambda =$	0.9	
		$x_1 = 1.1989$	42132	$x_1 = 1.198$	942132	$x_1 = 1.19$	8942132	
		$x_2 = 1.2175$	829	$x_2 = 1.217$	5829	$x_2 = 1.21$	75829	
	1.2	$x_3 = 1.2173$	96492	$x_3 = 1.208$	3262515	$x_3 = 1.20$	0786007	
	1.4	$x_4 = 1.2173$	98356	$x_4 = 1.212$	922707	$x_4 = 1.21$	5738823	
		$x_5 = 1.2173$	98337	$x_5 = 1.210$	59261	$x_5 = 1.20$	2314272	
		$x_6 = 1.2173$	98338	$x_6 = 1.211$	757659	$x_6 = 1.21$	4545953	
		$x_1 = 1.3930$	7902	$x_1 = 1.393$	007902	$x_1 = 1.39$	307902	
		$x_2 = 1.4623$	83543	$x_2 = 1.462$	2383543	$x_2 = 1.46$	2383543	
	1.4	$x_3 = 1.4616$	90498	$x_3 = 1.427$	731281	$x_3 = 1.39$	9882495	
	1.4	$x_4 = 1.4616$	97428	$x_4 = 1.445$	057412	$x_4 = 1.45$	6144866	
		$x_5 = 1.4616$	97359	$x_5 = 1.436$	394347	$x_5 = 1.40$	5611583	
		$x_6 = 1.4616$	9736	$x_6 = 1.440$	72588	$x_6 = 1.45$	1091538	
		$x_1 = 1.5804$	55335	$x_1 = 1.580$	455335	$x_1 = 1.58$	0455335	
		$x_2 = 1.7255$	15509	$x_2 = 1.725$	515509	$x_2 = 1.72$	5515509	
	1.6	$x_3 = 1.7240$	64907	$x_3 = 1.652$	985422	$x_3 = 1.59$	4615268	
	1.0	$x_4 = 1.7240$	79413	$x_4 = 1.689$	250466	$x_4 = 1.71$	2456633	
		$x_5 = 1.7240$	79268	$x_5 = 1.671$	117944	$x_5 = 1.60$	6679733	
		$x_6 = 1.7240$	7927	$x_6 = 1.680$	184205	$x_6 = 1.70$	1878943	
\boldsymbol{y}	Pi	card	Rung	ge-Kutta	Eι	ıler	Exact solution	on
	$x_1 = 1.1$	98942132						
1.2	$x_2 = 1.2$	2175829	x = 1.	217667486	x = 1.2		x = 1.2176784	43
	$x_3 = 1.2$	21762894						
	$x_1 = 1.3$	9307902						
1.4	$x_2 = 1.4$	62383543	x = 1.	463510256	x = 1.43	30386926	x = 1.4635277	63
	$x_3 = 1.4$	62917598						
	$x_1 = 1.5$	80455335						
1.6	$x_2 = 1.7$	25515509	x = 1.	729974062	x = 1.68	82795378	x = 1.7299963	71
	$x_3 = 1.7$	27548772						

Table 3. Comparison of the solutions obtained by the modified Kranoselskii iteration method, Picard iteration method, Runge-Kutta method, and the Euler method with the exact solution for different values of λ .

Applying the modified Krasnoselskii iteration method to the equation $\lambda = 0, 5$, then:

 $y_1 = x^2,$

$$y_6 = x^2 + \frac{11x^4}{32},$$

are found. And, also, for $\lambda = 0, 01$:

$$y_{1} = x^{2},$$

$$y_{2} = x^{2} + \frac{x^{4}}{2},$$

$$y_{3} = x^{2} + \frac{x^{4}}{4},$$

$$y_{4} = x^{2} + \frac{3x^{4}}{8},$$

$$y_{5} = x^{2} + \frac{5x^{4}}{16},$$

$$y_{1} = x^{2},$$

$$y_{2} = x^{2},$$

$$y_{2} = x^{2} + \frac{x^{4}}{2},$$

$$y_{3} = x^{2} + 0.0495x^{4},$$

$$y_{4} = x^{2} + 0.049505x^{4},$$

$$y_{5} = x^{2} + 0.04950495x^{4},$$

$$y_{6} = x^{2}0.0495049505x^{4},$$

Table 4. Absolute error of Example 2 for different values of λ (y = 1.2, y = 1.4 and y = 1.6, respectively).

	Absolute error table								
	Modified Krasnoselskii iteration								
$y \qquad \lambda = 0.01 \qquad \lambda = 0.5 \qquad \lambda = 0.$									
1.2	0.000280105	0.005920784	0.00313249						
1.4	0.0018330403	0.022801883	0.012436265						
1.6	0.005917101	0.049854321	0.028117428						
y	Picard	Runge-Kutta	Euler						
1.2	0.000049503	0.000010957	0.017678443						
1.4	0.000610165	0.00017507	0.033140837						
1.6	0.0002447599	0.00002230898	0.047200993						

are calculated. At last, for $\lambda = 0, 9$, then:

$$y_1 = x^2,$$

$$y_2 = x^2 + \frac{x^4}{2},$$

$$y_3 = x^2 + 0.05x^4,$$

$$y_4 = x^2 + 0.0455x^4,$$

$$y_5 = x^2 + 0.0905x^4,$$

are obtained.

Now we tend the approximate solution, using the Euler method. Firstly, we use formula:

$$y_{n+1} = y_n + hF(x_n, y_n),$$

with F(x, y) = 2x(y + 1), h = 0.2 and $x_0 = 0$ $y_0 = 0$. From the initial condition y(0) = 0, we have F(0,0) = 0. We now proceed where the calculations:

$$y_1 = y_0 + hF(y_0, x_0) = 0 + 0.2 = 0.0000,$$

$$x_1 = x_0 + h = 0.000 + 0.200 = 0.2000,$$

$$y_2 = y_1 + hF(y_1, x_1) = 0.0 + 0.2 \cdot 0.4 = 0.0800,$$

 $x_2 = x_1 + h = 0.200 + 0.200 = 0.4000,$

$$y_3 = y_2 + hF(y_2, x_2) = 0.08 + 0.2 \cdot 0.864 = 0.2528,$$

 $x_3 = x_2 + h = 0.400 + 0.200 = 0.6000.$

Finally, applying the Runge-Kutta method to the given initial value problem, we carry out the intermediate calculations in each step to give figures after the decimal point, and round off the final results at each step to four such places.

Here, $F(x, y) = 2x(y + 1), x_0 = 0, y_0 = 0,$ $x_{n+1} = x_n + h$ and we are to use h = 0.2. Using these quantities, we calculated, successively, k_1 , k_2 , k_3 , k_4 and K_0 defined by:

$$k_{1} = hg(y_{0}, x_{0}),$$

$$k_{2} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{1}}{2}),$$

$$k_{3} = hg(y_{0} + \frac{h}{2}, x_{0} + \frac{k_{2}}{2}),$$

$$k_{4} = hg(y_{0} + h, x_{0} + k_{3}),$$

1 - - - /

and $K_0 = \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)y_{n+1} = y_n + K_0$. Thus we find k_1, k_2, k_3 and k_4 for n = 0, as:

$$k_{1} = hF(x_{0}, y_{0}) = 0.00000000,$$

$$k_{2} = hF(x_{0} + \frac{h}{2}, y_{0} + \frac{k_{1}}{2}) = 0.04,$$

$$k_{3} = hF(x_{0} + \frac{h}{2}, y_{0} + \frac{k_{2}}{2}) = 0.0408,$$

$$k_{4} = hF(x_{0} + h, y_{0} + k_{3}) = 0.083264.$$

So, $y_1 = 0.040810666$ is obtained for $x_1 = 0.2$.

On the other hand, we calculated k_1 , k_2 , k_3 and k_4 for n = 1 as:

$$k_{1} = hF(x_{1}, y_{1}) = 0.083264853,$$

$$k_{2} = hF(x_{1} + \frac{h}{2}, y_{1} + \frac{k_{1}}{2}) = 0.129893171,$$

$$k_{3} = hF(x_{1} + \frac{h}{2}, y_{1} + \frac{k_{2}}{2}) = 0.13269087,$$

$$k_{4} = hF(x_{1} + h, y_{1} + k_{3}) = 0.187760245.$$

Hence, $y_2 = 0.173509529$ is calculated for $x_2 = 0.4$ Finally, we get k_1 , k_2 , k_3 , k_4 for n = 2, as:

$$k_{1} = hF(x_{2}, y_{2}) = 0.187761524,$$

$$k_{2} = hF(x_{2} + \frac{h}{2}, y_{2} + \frac{k_{1}}{2}) = 0.253478058,$$

$$k_{3} = hF(x_{2} + \frac{h}{2}, y_{2} + \frac{k_{2}}{2}) = 0.260049711,$$

$$k_{4} = hF(x_{2} + h, y_{2} + k_{3}) = 0.344054217.$$

Hence, $y_3 = 0433321409$ is obtained for $x_3 = 0.6$.

After the necessary calculations done above, the comparison is shown schematically in Figure 3.

We may present the results given in Tables 5 and 6.

	Modified Krasnoselskii iteration								
		$\lambda = 0$.01	$\lambda=0.5$	i	$\lambda =$	0.9		
		$y_1 = 0.04$		$y_1 = 0.04$		$y_1 = 0.0$	4		
		$y_2 = 0.0408$		$y_2 = 0.040$)8	$y_2 = 0.0$	408		
	x = 0.2	$y_3 = 0.040792$		$y_3 = 0.0404$		$y_3 = 0.04008$			
	x = 0.2	$y_4 = 0.04079208$		$y_4 = 0.0406$		$y_4 = 0.040728$			
		$y_5 = 0.040792079$		$y_5 = 0.040$)5	$y_5 = 0.0$	401448		
		$y_6 = 0.040$	792079	$y_6 = 0.040$)55				
		$y_1 = 0.16$		$y_1 = 0.16$		$y_1 = 0.1$	6		
		$y_2 = 0.172$	$y_2 = 0.1728$ y		28	$y_2 = 0.1$	728		
	x = 0.4	$y_3 = 0.172$	2672	$y_3 = 0.166$	54	$y_3 = 0.1$	6128		
	<i>x</i> = 0.4	$y_4 = 0.172$	67328	$y_4 = 0.169$	$y_4 = 0.1696$ $y_4 = 0.1$		171648		
		$y_5 = 0.172$	673267	$y_5 = 0.168$	3	$y_5 = 0.1$	623168		
		$y_6 = 0.172$	673267	$y_6 = 0.168$	38				
	x = 0.6	$y_1 = 0.36$		$y_1 = 0.36$		$y_1 = 0.3$	6		
		$y_2 = 0.424$	8	$y_2 = 0.424$	$0.4248 y_2 = 0.4$		248		
		$y_3 = 0.424152$		$y_3 = 0.3924$ y		$y_3 = 0.36648$			
		$y_4 = 0.42415848$		$y_4 = 0.4086$ g		$y_4 = 0.4$	18968		
		$y_5 = 0.424$	158415	$y_5 = 0.400$)5	$y_5 = 0.3$	717288		
		$y_6 = 0.42415845$		$y_6 = 0.40455$					
	Pic	ard	Runge	e-Kutta	\mathbf{E}_{1}	uler	Exact s	olution	
	$y_1 = 0.04$:							
x = 0.2	$y_2 = 0.04$.08	$u_1 = 0.0$	40810666	$u_1 =$	= 0	y = 0.040810774		
	$y_3 = 0.040810666$		$g_1 = 0.040010000$ $g_1 =$		91	0 <i>y</i> 0.0100		0010111	
	$y_4 = 0.040810772$								
	$y_1 = 0.16$ $y_2 = 0.1728$ $y_3 = 0.173482666$								
x = 0.4			$y_1 = 0.1$	81332873	$u_1 =$	= 0.08	y = 0.173510871		
			$g_1 = 0.101332013$ g_1		91	0.00 9 0.1			
	$y_4 = 0.173509972$								
	$y_1 = 0.36$	= 0.36							
x = 0.6	$y_2 = 0.4248$ $y_3 = 0.432576$ $y_4 = 0.43327584$		$y_1 = 0.44287682$ $y_1 =$		$u_1 = 0.252$		u = 0.433329414		
					σ±	1 0.222 9 0.222			

Table 5. Comparison of the solutions obtained by the modified Krasnoselskii iteration method, Picard iteration method, Runge-Kutta method, Euler method with the exact solution for different values of λ .

Corollary 6. If the approximate solution compares with the different values of λ , then the conclusion may be given using Table 5.

X

The best approximation may be obtained for different values of λ , such as $\lambda = 0.9$, $\lambda = 0.5$ and $\lambda = 0.01$, respectively, using the modified Krasnoselskii iteration method for x = 0.2, x = 0.4 and x = 0.6, in accordance with the solution, using the Picard iteration method Runge-Kutta method, Euler method and the exact solution.

As seen in Table 5, if numerical methods, such as the Runge-Kutta method, Euler method, Picard iteration method and modified Krasnoselskii iteration method are used in order to get the best approximation of each for different values of λ such as $\lambda = 0.9$, $\lambda = 0.5$ and $\lambda = 0.01$, respectively, then it is concluded that the modified Krasnoselskii iteration method is more effective than the Picard iteration method and Runge-Kutta method, but not the Euler method, in accordance with the exact solution.

Corollary 7. The absolute error of the modified Krasnoselskii iteration method is computed for different values of λ and is found to be more effective than



Figure 3. Comparison of the exact solution with the approximation solution of Example 3 for different values of λ .

Table 6. Absolute error of Example 3 for different values of λ (x = 0.2, x = 0.4 and x = 0.6, respectively).

Absolute error table								
Modified Krasnoselskii iteration								
$\lambda = 0.01$	$\lambda=0.5$	$\lambda=0.9$						
$x = 0.2 \ 1.9984 \times 10^{-5}$	2.60774×10^{-4}	$6.65974 imes 10^{-4}$						
$x = 0.4 \ 8.37604 \times 10^{-1}$	4 4.710871×10 ⁻³	3 1.1194071×10 ⁻²						
$x = 0.6 \ 9.13569 \times 10^{-1}$	$x = 0.6 \ 9.13569 \times 10^{-3} \ 2.874414 \times 10^{-2} \ 6.156534 \times 10^{-2}$							
Picard	Runge-Kutta	Euler						
$x = 0.2 \ 2 \times 10^{-9}$	1.08×10^{-7}	4.0810774×10^{-2}						
$x = 0.4 \ 8.99 \times 10^{-7}$	1.342×10^{-5}	9.3510871×10^{-2}						
$x = 0.6 \ 1.83 \times 10^{-5}$	0.8005×10^{-5}	1.8049414×10^{-1}						

the Euler method, but not better than the Runge-Kutta method and the Picard iteration method, in accordance with Table 6.

4. Conclusion

In this paper, we applied Picard iteration and modified Krasnoselskii iteration methods, selecting different types of example and also compared the results using the Runge-Kutta method and the Euler method, with the exact solution. In the conclusion, the comparisons indicate that there is very good agreement between the numerical solution and the exact solution in terms of accuracy.

The result shows that the modified Krasnoselskii iteration method is very effective and convenient for solving different types of equations having initial conditions, with respect to other methods in the literature.

References

- Buong, N. and Land, N.D. "Iteration methods for fixed point of a nonexpansive mapping", *International Mathematical Forum*, 6(60), pp. 2963-2974 (2011).
- 2. Marino, G., Colao, V. and Yao, Y. "Krasnoselski-Mann iteration for hierarchical fixed point and equilib-

rium problem", Bull. Aust. Math. Soc., **79**, pp. 187-200 (2009).

- Chang, S.S., Cho, Y.J. and Kim, J.K. "The equivalence between the convergence of modified Picard, modified Mann, and modified Ishikawa iterations", *Mathemati*cal and Computer Modelling, 37, pp. 985-991 (2003).
- Ahmed, A.E.-S. "Convergence of some doubly sequences iterations with errors in Banach spaces", *Global Journal of Science Frontier Research*, 10(5), pp. 65-69 (2010).
- Krasnoselskii, A.M. "Two remarks about the method of successive approximation", Uspehi Math. Nauk., 63, pp. 123-127 (1955).
- Brouwer, L.E.J. "On continious one-to-one transformations of surfaces into themselves", *Proc. Kon. Nederl. Akad. Wetensch*, pp. 788-798 (1909); **12**, pp. 286-297(1910); **13**, pp. 767-774 (1911); **14**, pp. 300-310 (1912); **15**, pp. 352-360 (1913); **22**, pp. 811-814 (1920); **23**, pp. 232-234 (1921).
- Bugajewski, D. "Fixed-point theorems in hyperconvex spaces revisited", Mathematical and Computer Modelling, 32, pp. 1457-1461 (2000).
- Kirk, W.A. "Krasnoselskii's iteration process in hyperbolicspace", Numerical Functional Analysis and Optimization, 4(4), pp. 371-381 (1981-1982).
- Yao, Y. and Cho, Y.J. "A strong convergence of amodified Krasnoselskii-Mann method for non-expansive mappings in Hilbert spaces", *Mathematical Modelling* and Analysis, 15(2), pp. 265-274 (2010).
- Zhang. Y. and Zhao, X.-Q. "Bistable travelling waves in competitive recursion systems", J. Differential Equations, 252, pp. 2630-2647 (2012).
- Ding, L. and Li, Z. "Periodicity and stability in neutral equations by Krasnoselskii's fixed point theorem", *Nonlinear Analysis: Real World Applications*, **11**, pp. 1220-1228 (2010).
- Liu, M. and Guo, Z. "Global solvability and Mann iteration methodwith error for a third order nonlinear neutral delay differential equation", *Bulletin of Mathematical Analysis and Applications*, 3(3), pp. 253-272 (2011).
- Sun, B. "Existence and successive iteration of positivesolutions to a third-order three-point boundary value problem", *Energy Procedia*, 13(3), pp. 6091-6096 (2011).
- He, J.-H. "Homotopy perturbation technique", Computer Methods in Applied Mechanics and Engineering, 178(3-4), pp. 257-262 (1999).
- He, J.-H. "Homotopy perturbation method with in auxiliary term", Abstract and Applied Analysis, Article ID 857612, 7 pages, doi:10.1155/2012/857612 (2012).

1804

- 16. Boyce, W.E. and Diprima, R.C., *Elementary Differential Equations and Boundary Value Problems*, John Wiley & Sons, Inc., Third Edition, USA (1976).
- Ross, S.L., Differential Equations, John Wiley & Sons, Inc., 3rd Ed., Canada (1984).
- Ponalagusamy, R., Alphonse, P.J.A. and Chandru, M. "Development of new fifth-order fifth-stage Runge Kutta method based on Heronian mean", *International* Journal of Engineering Science, Advanced Computing and Bio-Technology, 2(4), pp. 162-197 (2011).
- Ponalagusamy, R. and Senthilkumar, S. "A new fourth order embedded RKAHeM(4,4) method with error control on multi layer raster cellular neural network", *Signal Image and Video Processing*, 3, pp. 1-11 (2009).
- Ponalagusamy, R. and Senthilkumar, S. "A new method of embedded fourth order with four stages to study raster CNN simulation", *International Journal* of Automation and Computing, 6, pp. 285-294 (2009).
- Liu, L. "Fixed points of local strictly pseudocontractive mappings using Mann and Ishikawa iteration with errors", *Indian J. Pure Appl. Math.*, 26(7), pp. 649-659 (1995).
- Ahmed, E-S.A. and Kamal, A. "Fixed point theorems for asymptotically nonexpansive mappings in uniformly convex Banach spaces", *Mathematica Tome*, 50(73)(2), pp. 103-118 (2008).
- Ahmed, E-S.A. and Kamal, A.A. "Strong convergence of Mann type doubly sequence iterations with applications", Southeast Asian Bulletin of Mathematics, 33(1), pp. 1-11 (2009).
- 24. Granas, A. and Dugundji, J., *Fixed Point Theory*, Springer Monographs in Mathematics, USA (2000).

- Berinde, V. "Iterarative approximation of fixed points", North University of Baia Mare, Romania, 18 Juin (2007).
- Berinde, V., Iterative Approximation of Fixed Points, 2nd Revised and Enlarged Ed., Lecture Notes in Mathematics Berlin, Springer (1912).

Biographies

Necdet Bildik was born in Sivas, Turkey in 1951. He obtained a BSc degree from Faculty of Science, the Department of Mathematics at Ankara University Turkey, in 1974, his MSc degree form the University of Louisville, USA, in 1978, and his PhD degree from Oklahoma State University in 1982. He became Professor in 2003. His research interests include numeric analysis, ordinary and partial differential equations, real and complex dynamical systems, ergodic and stability theory. He has published over than a hundred papers in national and international journal and conferences.

Yasemin Bakir was born in İzmir, Turkey in 1987. She received her BSc degree in Mathematics and her MSc degree in Applied Mathematics, in 2008 and 2011, respectively. She is currently a PhD student at Yıldız Technical University, Turkey.

Ali Mutlu was born in Kayseri, Turkey in 1969. He received his BSc degree in Mathematics in 1991 and his MSc degree in Analysis and Functions Theory in 1993 from Erciyes University, Turkey. He obtained his PhD degree in 1994 from the University of Wales, Bangor in United Kingdeom and is currently Associate Professor in the Department of Mathematics at Celal Bayar University, Turkey. His research interests include Algebraic Topology, especially simplicial objects, digital topology, fixed point theory and functional analysis.