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A new nonparametric composite exponentially weighted moving average sign control chart

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Average run length; Binomial distribution; EWMA statistic; Nonparametric control charts; Statistical process control. **Abstract.** This study proposed a dual Exponentially Weighted Moving Average (EWMA) statistics based nonparametric sign control chart to monitor the process deviation from the targeted value. The performance of the proposed chart is compared with the existing nonparametric version of the EWMA sign and Cumulative Sum (CUSUM) mean control charts by using out-of-control average run length for various shifts in the process. The simulation study showed the superiority of the suggested chart over the existing counterparts. A real dataset is also considered for the application of the proposed chart.

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1. Introduction

Statistical Process Control (SPC) plays an essential role in monitoring and identifying the changes in the process by using well-established statistical tools. These changes are measured in terms of variations, which can be classified into common and assignable causes of variations. The common causes of variations represent an inherent part of the process, leading to the state of statistical in-control [1]. The SPC has gained a considerable progress after the development of the Shewhart control chart [2]. Subsequently, the Cumulative Sum (CUSUM) control chart [3] and the Exponentially

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Weighted Moving Average (EWMA) control chart [4] have made a considerable improvement. The Shewhart control chart is useful in detecting larger shifts in the process as it is based on current sample information only, whereas the CUSUM and EWMA control charts utilize both the current and previous observations and, therefore, are more sensitive to identifying small to moderate shifts.

In order to combine the advantages of the Shewhart control charts in detecting larger shifts and the CUSUM control charts in detecting smaller shifts, the combined Shewhart-CUSUM chart was developed by adding Shewhart limits in the CUSUM chart [5]. A similar scheme was proposed by Lucas and Saccucci [6] by combining the Shewhart scheme with the EWMA control chart. Moreover, Abbas et al. [7] proposed a mixed EWMA-CUSUM control chart to enhance the sensitivity of the conventional memory control charts for smaller shifts. In the same context, Haq [8,9] developed a Hybrid Exponentially Weighted Moving Average (HEWMA) control chart by using dual EWMA charting statistics. This methodology of combining charts allows dealing with a range of shift values effectively. To be more precise, these charts detect shifts more quickly than the classical CUSUM, EWMA, and traditional Shewhart control charts.

In the aforementioned control charts, the critical quality characteristic of the process is assumed to be normally distributed. However, in many practical situations, the distribution of the underlying process is either unknown or non-normal. This, as a result, seriously affects the efficiency of the typical control charts [10]. One of the possible alternatives in this scenario is the use of the distribution-free or nonparametric control charts which are generally robust, flexible, and more effective. According to Chakraborti and Graham [11], the In-Control (IC) average runlength of all continuous distributions remains the same in distribution-free or nonparametric control charts.

In the context of nonparametric control charts, a new idea was proposed by Yang and Cheng [12] by introducing the process proportion, and a nonparametric CUSUM mean chart was suggested. Subsequently, Yang et al. [13] designed the nonparametric EWMA sign control chart and indicated that their suggested chart was capable of detecting small shifts in the target process when the underlying distribution is either non-normal or unknown. The adaptive Phase-II nonparametric EWMA control chart was proposed by Liu et al. [14] to detect a range of shifts in the location parameter. Lu [15] developed a nonparametric extension of the EWMA control chart called Generally Weighted Moving Average (GWMA) sign control chart to enhance the detection ability for small process shifts. Abbasi et al. [16] investigated the performance of the nonparametric EWMA control chart by using asymptotic, time-varying, and fast initial response based control limits. A mixed version of the EWMA-CUSUM sign chart was proposed by Abbasi et al. [17] using arcsine transformation and they demonstrated that the performance of their chart outperformed other counterparts in terms of shift detection. The synthetic version of the EWMA sign control chart was proposed by Haq [18] by integrating the existing EWMA sign control chart with the conforming run length. Recently, Raza et al. [19] proposed the nonparametric homogeneously weighted moving average control charts based on sign and signed-rank statistics. For more details of nonparametric control charts, we refer the interested readers to, for example, Altukife [20,21], Amin et al. [22], Aslam et al. [23], Bakir [24–26], Chowdhury et al. [27], Graham et al. [28–31], Koutras and Triantafyllou [32], Mahmood et al. [33], Raza et al. [34], and the references cited therein.

In this paper, a nonparametric Composite Exponentially Weighted Moving Average (CEWMA) control chart was proposed by combining two EWMA statistics that enhance the sensitivity of the chart. Note that Haq [8,9] designed an HEWMA control chart using two EWMA statistics under the assumption that the underlying distribution of the quality characteristic is normal. However, this chart is not effective in case of violation of normality assumption or when the distribution is unknown which happens to be the most practical situation. Furthermore, the variance expression derived by Haq [8,9] becomes undefined when $\lambda_1 =$ λ_2 . The nonparametric version of a double EWMA control chart was proposed by Riaz and Abbasi [35] using arcsine transformation, and the same value of smoothing constant λ was assumed for both EWMA statistics. This makes the use of their chart limited for practitioners if they want to use different values for smoothing parameters. On the contrary, our proposed chart is simple as it considers a sign test without any transformation to define a composite EWMA charting statistic. Furthermore, the CEWMA chart provides greater flexibility than the one proposed by Riaz and Abbasi [35] by allowing practitioners to consider all possible combinations of smoothing parameters λ_1 and λ_2 . Besides, we have evaluated the performance of the proposed control chart under various distributions, which had not been considered by Riaz and Abbasi [35].

The rest of this paper is organized as follows. The design structure of the proposed CEWMA sign control chart is given in Section 2. Performance evaluations of the proposed charts are given in Section 3. Section 4 reports comparisons with the existing control charts using out-of-control average run length for various shifts as well as simulated real-life data examples. Finally, some conclusions are drawn in Section 5.

2. The proposed nonparametric CEWMA sign chart

Suppose that in a production process, a certain quality characteristic Y has a median η as a target value. Moreover, assume that $Z = Y - \eta$ denotes the process deviation from the target value with probability p = P(Z > 0). The proposed chart is based on the sign test in which we test the hypothesis that the probability of a plus sign of Z equals the probability of a minus sign, which is equivalent to the test hypothesis that the process has a specific target value, say η . Therefore, the process is said to be IC if $p = p_0 = 0.5$; otherwise, the process is deemed to be Out-Of-Control (OOC), i.e., $p = p_1 \neq p_0$. Let $\{Y_{it}, 1 \leq i \leq n\}$ be an independently and identically distributed sample taken at time t from Y to investigate the variation from the process target value η . Then, we define:

$$Z_{it} = Y_{it} - \eta \quad \text{and} \quad I_{it} = \begin{cases} 1, & \text{if } Z_{it} > 0\\ 0, & \text{otherwise} \end{cases}$$

for $i = 1, 2, \cdots$ and $t = 1, 2, \cdots$

Let S_t be the number of observations for which Z_{it} , $i = 1, 2, \dots, n$, is greater than zero; then, the statistic $S_t = \sum_{i=1}^{n} I_{it}$ follows the binomial distribution with parameters (n, 0.50) for an IC process. Based on this assumption, the CEWMA sign chart is proposed by combining the two EWMA statistics as follows:

$$HE_{S_{t}} = \lambda_{1}E_{S_{t}} + (1 - \lambda_{1})HE_{S_{t-1}} \qquad 0 < \lambda_{1} \le 1, \quad (1)$$

$$E_{S_t} = \lambda_2 S_t + (1 - \lambda_2) E_{S_{t-1}} \qquad 0 < \lambda_2 \le 1, \quad (2)$$

where S_t is the *t*th successively recorded number of $Z_t(> 0)$. Note that the mean value of S_t is taken as the initial value of the EWMA statistics, i.e., $HE_{S_0} = E_{S_0} = \mu = np_0 = n/2$ and HE_{S_t} is the monitoring statistic of the proposed CEWMA control chart. By expanding Eqs. (1) and (2), we obtain:

$$HE_{S_t} = (1 - \lambda_1)^t HE_{S_0} + \lambda_1 \sum_{i=0}^{t-1} (1 - \lambda_1)^i E_{S_{t-i}}, \quad (3)$$

$$E_{S_t} = (1 - \lambda_2)^t E_{S_0} + \lambda_2 \sum_{j=0}^{t-1} (1 - \lambda_2)^j S_{t-j}, \qquad (4)$$

and then by substituting Eq. (4) into Eq. (3), we get:

$$HE_{S_{t}} = (1 - \lambda_{1})^{t} \mu + \lambda_{1} \sum_{i=0}^{t-1} (1 - \lambda_{1})^{i} (1 - \lambda_{2})^{t-i} \mu$$
$$+ \lambda_{1} \lambda_{2} \sum_{i=0}^{t-1} (1 - \lambda_{1})^{i} \sum_{j=0}^{t-i-1} (1 - \lambda_{2})^{j} S_{t-i-j}, \quad (5)$$
$$= (1 - \lambda_{1})^{t} (np_{0}) + \lambda_{1} \sum_{i=0}^{t-1} (1 - \lambda_{1})^{i} (1 - \lambda_{2})^{t-i} (np_{0})$$

$$+\lambda_1\lambda_2\sum_{i=1}^t \left((1-\lambda_2)^{t-i}\sum_{j=0}^{t-i}\left(\frac{1-\lambda_1}{1-\lambda_2}\right)^j\right)S_i.$$
(6)

After some algebraic computation of Eq. (6), we can obtain the mean of HE_{S_t} as:

$$E(HE_{S_t}) = np_0. (7)$$

Now, by definition, the variance of HE_{S_t} can be obtained as follows:

$$V(HE_{S_t}) = (\lambda_1 \lambda_2)^2 \sum_{i=1}^t (1 - \lambda_1)^{2(t-i)}$$

$$\left(\sum_{j=0}^{t-i} \left(\frac{1-\lambda_1}{1-\lambda_2}\right)^j\right)^2 V(S_i),$$

where $V(S_i) = np_0(1 - p_0)$. After some algebraic computation, we obtain the variance of HE_{S_t} as:

$$V(HE_{S_t}) = \left(\frac{\lambda_1 \lambda_2}{\lambda_1 - \lambda_2}\right)^2 \left[\sum_{i=1}^2 \frac{(1 - \lambda_i)^2 \left(1 - (1 - \lambda_i)^{2t}\right)}{1 - (1 - \lambda_i)^2} - \frac{2(1 - \lambda_1)(1 - \lambda_2)\{1 - (1 - \lambda_1)^t(1 - \lambda_2)^t\}}{1 - (1 - \lambda_1)(1 - \lambda_2)}\right]$$
$$\{np_0(1 - p_0)\}.$$
 (8)

For $\lambda_1 = \lambda_2 = \lambda$, Eq. (5) reduces to:

 $HE_{S_{\star}} = (1 + \lambda t)(1 - \lambda)^t (np_0)$

$$+\lambda^2 \sum_{i=1}^{t} (t-i+1)(1-\lambda)^{t-i} S_i.$$
 (9)

By definition of variance, we obtain:

$$V(HE_{S_t}) = \lambda^4 \sum_{i=1}^t (t-i+1)^2 (1-\lambda)^{2(t-i)} V(S_i),$$

which yields:

$$V(HE_{S_t}) = \lambda^4 \sum_{i=1}^t i^2 (1-\lambda)^{2(i-1)} \{ np_0(1-p_0) \},\$$

and after some algebraic work, we finally obtain Eq. (10) as shown in Box I for the variance of Eq. (9). Now, the center line and control limits of the CEWMA sign chart are computed as follows:

$$UCL = np_0 + k\sqrt{V(HE_{S_t})},\tag{11}$$

$$CL = np_0, (12)$$

$$LCL = np_0 - k\sqrt{V(HE_{S_t})},\tag{13}$$

where k denotes the distance of the control limits from the center line in multiples of the standard deviation of the CEWMA statistic (HE_{S_t}) . The three parameters λ_1 , λ_2 , and k are chosen in such a way that a specific IC Average Run Length (ARL) is achieved. Note that if any $HE_{S_t} \geq UCL$ or $HE_{S_t} \leq LCL$, the process is considered to be OOC. Furthermore, if we select $\lambda_1 = 1$ or $\lambda_2 = 1$, the CEWMA sign control chart reduces to the EWMA sign chart proposed by Yang et al. [13].

$$V(HE_{S_t}) = \lambda^4 \frac{\{1 + (1-\lambda)^2\} - (1-\lambda)^{2t} [(1+t)^2 - (-1+2t+2t^2)(1-\lambda)^2 + t^2(1-\lambda)^4]}{\{1 - (1-\lambda)^2\}^3} \{np_0(1-p_0)\}.$$
 (10)

3. Performance evaluation

The ARL is commonly used to assess the performance of a control chart. Recall that the ARL is the average number of points plotted on a control chart before an OOC signal is shown. In this study, the Monte Carlo simulation is employed to calculate the coefficient values k for various combinations of λ_1 and λ_2 after fixing $ARL_0 = 370$ and n = 10. To get the average results, we use 100,000 repetitions for each Monte Carlo simulation. Since the distribution of S_t in CEWMA sign statistic follows a binomial distribution, the exact $ARL_0 = 370$ is not always attained. We, therefore, find the k values such that the ARL_0 is approximately equal to 370 (i.e., $ARL_0 \approx 370$). Some choices of design parameters of the CEWMA sign chart under a nominal ARL_0 value of 370 are given in Table 1.

The control limits of the proposed chart depend on n, k, λ_1 , and λ_2 . It can be observed from Table 1 that the values of k are symmetrical with respect to λ_1 and λ_2 . There is an increasing trend in k by increasing either λ_1 , λ_2 or both, except for larger values of λ_1 and λ_2 . The same strategy can be applied to find the values of k for various n's. In addition to the ARL_0 , the OOC run length (ARL_1) is also calculated which is expected to be adequately small (for a fixed ARL_0) to detect the process shift quickly. Considering the IC process proportion $p_0 = 0.50$ and $\lambda_1 = \lambda_2 = \lambda =$ 0.05, the ARL_1 values of the CEWMA sign chart are computed in Table 2 by using different values of n and the expected OOC process proportion (p_1) . Besides, the performance of the CEWMA sign chat is also investigated for $\lambda_1 \neq \lambda_2$. In this scenario, the ARL values for smoothing constants ($\lambda_1 = 0.05, \lambda_2 = 0.10$) and $(\lambda_1 = 0.05, \lambda_2 = 0.20)$ under various n and p_1 are presented in Tables 3 and 4, respectively. When p = 0.50, the attained ARL_0 values are approximately equal to the desired value of 370. From Tables 2–4, it can be noticed that ARL_1 values are inversely related to $|p_1-0.50|$ and n. It can also be observed that k changes marginally as the sample size n increases. Moreover, for smaller shifts, the ARL_1 values increase marginally with increase in one of the smoothing constants λ_1 and λ_2 .

In the following, we further investigate the performance of the proposed CEWMA control chart under the assumption that the critical quality characteristic of a process follows some specific distribution. The performance of the proposed CEWMA control chart under various symmetrical and asymmetrical distributions is assessed by using different run-length characteristics such as ARL, median run length (MDRL), and Standard Deviation Run Length (SDRL). To be more precise, by setting $ARL_0 = 370$, the run length distribution for $\lambda_1 = \lambda_2 = 0.05$ and n = 10 is computed under the standard normal distribution, N(0,1); the Student's t distribution with 4 and 8 degrees of freedom; the heavy-tailed symmetric distributions that include the Laplace (or double exponential) distribution $Laplace(0, 1/\sqrt{2})$, the Logistic distribution $LG(0,\sqrt{3}/\pi)$, the Weibull distribution Weibull(2,1), the Gamma distribution Gamma(4,1), and the contaminated normal (CN) distribution. Recall that the CN distribution is obtained by combining two normal distributions $N(0, \sigma_1^2)$ and $N(0, \sigma_2^2)$ using the relation $(1 - \varphi)N(0, \sigma_1^2) + \varphi N(0, \sigma_2^2)$, where φ denotes the proportion of contamination. This distribution is generally used to evaluate the outlier resistance power of the control charts. In our study, we set $\sigma_1^2 = 4\sigma_2^2$ and the proportion of contamination $\varphi = 0.10$. To

							(0							
<u>)</u>	λ_2														
λ_2	0.05	0.10	0.20	0.25	0.30	0.40	0.50	0.60	0.70	0.80	0.90				
0.05	1.954	2.092	2.227	2.271	2.304	2.353	2.392	2.428	2.455	2.481	2.505				
0.10	2.092	2.245	2.387	2.429	2.468	2.526	2.562	2.598	2.629	2.66	2.682				
0.20	2.227	2.387	2.528	2.571	2.61	2.666	2.711	2.744	2.772	2.795	2.822				
0.25	2.271	2.429	2.571	2.619	2.655	2.71	2.751	2.784	2.809	2.832	2.852				
0.30	2.304	2.468	2.61	2.655	2.692	2.743	2.782	2.811	2.837	2.855	2.871				
0.40	2.353	2.526	2.666	2.71	2.743	2.792	2.825	2.853	2.871	2.878	2.883				
0.50	2.392	2.562	2.711	2.751	2.782	2.825	2.856	2.875	2.884	2.889	2.892				
0.60	2.428	2.598	2.744	2.784	2.811	2.853	2.875	2.884	2.89	2.893	2.885				
0.70	2.455	2.629	2.772	2.809	2.837	2.871	2.884	2.89	2.894	2.882	2.868				
0.80	2.481	2.66	2.795	2.832	2.855	2.878	2.889	2.893	2.882	2.868	2.855				
0.90	2.505	2.682	2.822	2.852	2.871	2.883	2.892	2.885	2.868	2.855	2.82				

Table 1. The k values with different combinations of (λ_1, λ_2) for $ARL_0 \approx 370$ and n = 10.

Table 2. The ARL values of the Composite Exponentially Weighted Moving Average (CEWMA) sign control chart for $\lambda_1 = \lambda_2 = \lambda = 0.05$.

n	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
${m k}$	1.956	1.954	1.962	1.955	1.953	1.961	1.958	1.966	1.956	1.955	1.963	1.957	1.964	1.957	1.955	1.964	1.957
0.05	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.10	1.3	1.3	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.15	1.6	1.6	1.3	1.3	1.4	1.2	1.2	1.1	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0	1.0
0.20	2.0	2.0	1.6	1.6	1.7	1.4	1.4	1.3	1.3	1.3	1.2	1.2	1.3	1.2	1.2	1.1	1.1
0.25	2.8	2.6	2.3	2.2	2.2	1.9	1.9	1.7	1.7	1.7	1.5	1.5	1.6	1.4	1.4	1.3	1.3
0.30	4.1	3.8	3.4	3.2	3.2	2.8	2.7	2.4	2.4	2.4	2.1	2.2	2.1	2.0	2.0	1.8	1.8
0.35	7.0	6.3	5.7	5.4	5.1	4.7	4.4	4.1	4.0	3.9	3.6	3.5	3.5	3.2	3.1	2.9	2.9
0.40	13.8	12.8	11.5	10.9	10.3	9.5	8.9	8.3	8.0	7.8	7.2	7.0	6.9	6.5	6.3	6.0	5.9
0.45	42.1	38.6	35.4	33.6	31.6	29.7	28.0	26.2	25.3	24.7	23.0	22.3	21.7	20.5	20.0	18.9	18.6
p 0.50	371.0	370.8	370.5	369.5	371.8	371.7	371.5	370.4	370.4	371.4	371.3	371.9	379.1	372.8	369.4	370.9	371.6
0.55	42.0	38.9	35.1	33.8	31.6	29.3	28.1	26.1	25.2	24.3	23.1	22.1	21.7	20.6	20.0	18.8	18.7
0.60	14.0	12.8	11.5	10.8	10.2	9.5	9.0	8.3	7.9	7.8	7.2	7.1	6.8	6.5	6.3	6.0	5.8
0.65	7.o	6.3	5.7	5.4	5.1	4.7	4.4	4.1	3.9	3.9	3.5	3.5	3.4	3.2	3.1	2.9	2.9
0.70	4.1	3.8	3.4	3.3	3.2	2.8	2.7	2.4	2.4	2.4	2.1	2.1	2.1	2.0	2.0	1.8	1.8
0.75	2.8	2.6	2.3	2.2	2.2	1.9	1.9	1.7	1.7	1.7	1.5	1.5	1.6	1.4	1.4	1.3	1.3
0.80	2.0	2.0	1.6	1.6	1.7	1.4	1.4	1.3	1.3	1.3	1.2	1.2	1.3	1.1	1.2	1.1	1.1
0.85	1.6	1.6	1.3	1.3	1.3	1.2	1.2	1.1	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0	1.0
0.90	1.3	1.3	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.95	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0

Table 3. The ARL values of the Composite Exponentially Weighted Moving Average (CEWMA) sign control chart for $\lambda_1 = 0.05$ and $\lambda_2 = 0.10$.

1	n	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
1	k	2.097	2.092	2.105	2.098	2.10	2.101	2.098	2.096	2.101	2.098	2.096	2.098	2.095	2.101	2.097	2.095	2.096
0.	05	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.	10	1.3	1.3	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.	15	1.6	1.6	1.3	1.3	1.3	1.2	1.2	1.2	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0
0.	20	2.1	2.1	1.7	1.7	1.7	1.4	1.4	1.5	1.3	1.3	1.4	1.2	1.2	1.1	1.2	1.2	1.1
0.	25	3.0	2.8	2.4	2.3	2.2	2.0	2.0	2.0	1.7	1.7	1.7	1.6	1.6	1.4	1.4	1.5	1.4
0.	30	4.4	4.1	3.6	3.4	3.3	2.9	2.9	2.8	2.5	2.5	2.4	2.3	2.2	2.0	2.0	2.0	1.9
0.	35	7.4	6.9	6.1	5.9	5.4	4.9	4.7	4.6	4.2	4.1	4.0	3.7	3.6	3.3	3.3	3.3	3.1
0.	40	14.7	13.4	12.3	11.6	10.8	10.0	9.6	9.2	8.6	8.2	7.9	7.5	7.2	6.8	6.6	6.5	6.2
0.	45	44.9	41.9	37.6	35.7	33.9	31.0	29.7	28.8	26.8	25.9	24.7	23.4	22.8	21.5	21.1	20.7	19.7
<i>p</i> 0.	50	372.5	370.9	371.0	370.9	370.9	370.1	371.5	369.7	370.7	371.2	371.3	370.3	369.9	371.5	371.9	370.7	370.4
0.	55	44.9	41.5	37.9	35.6	33.6	31.1	29.8	28.5	26.6	25.8	24.9	23.8	22.7	21.8	21.1	20.7	19.6
0.	60	14.6	13.5	12.2	11.6	10.9	10.0	9.6	9.2	8.6	8.2	7.9	7.5	7.3	6.8	6.6	6.5	6.2
0.	65	7.3	6.8	6.1	5.7	5.4	4.9	4.8	4.6	4.2	4.1	4.0	3.7	3.6	3.3	3.3	3.3	3.1
0.	70	4.5	4.2	3.6	3.5	3.3	2.9	2.9	2.8	2.5	2.5	2.4	2.2	2.2	2.0	2.0	2.0	1.9
0.	75	3.0	2.8	2.4	2.3	2.2	2.0	2.0	2.0	1.7	1.7	1.7	1.6	1.6	1.4	1.4	1.5	1.4
0.	80	2.1	2.1	1.7	1.7	1.7	1.4	1.4	1.5	1.3	1.3	1.4	1.2	1.2	1.1	1.2	1.2	1.1
0.	85	1.6	1.6	1.3	1.3	1.3	1.2	1.2	1.2	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0
0.	90	1.3	1.3	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
0.	95	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0

determine the OOC run length characteristics, the shift in the process mean is introduced in terms of process standard deviation (σ), i.e., $\mu_1 = \mu_0 + \delta \sigma$ where δ determines the magnitude of the shift. The results are reported in Table 5. It can be noticed from Table 5 that the ARL_0 values remain the same under all continuous symmetrical and asymmetrical distributions which validate the theory of nonparametric control charts. Furthermore, the ARL_1 values decline rapidly with increase in the size of the shift for all the distributions

Table 4. The ARL values of the Composite Exponentially Weighted Moving Average (CEWMA) sign control chart for $\lambda_1 = 0.05$ and $\lambda_2 = 0.20$.

	n	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25
	${m k}$	2.235	2.227	2.228	2.230	2.229	2.227	2.231	2.230	2.229	2.232	2.228	2.230	2.230	2.230	2.232	2.228	2.2
	0.05	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
	0.10	1.3	1.3	1.3	1.1	1.1	1.2	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
	0.15	1.6	1.6	1.6	1.4	1.4	1.4	1.2	1.2	1.2	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0
	0.20	2.2	2.1	2.0	1.7	1.7	1.7	1.5	1.5	1.5	1.4	1.4	1.2	1.2	1.3	1.2	1.2	1.2
	0.25	3.0	2.9	2.8	2.4	2.4	2.3	2.0	2.0	2.0	1.8	1.8	1.6	1.6	1.6	1.5	1.5	1.5
	0.30	4.6	4.3	4.0	3.6	3.5	3.3	3.0	2.9	2.8	2.6	2.5	2.3	2.3	2.3	2.1	2.1	2.1
	0.35	7.6	7.0	6.6	6.0	5.7	5.4	4.9	4.7	4.6	4.2	4.2	3.8	3.7	3.7	3.4	3.4	3.3
	0.40	15.1	13.9	12.9	11.8	11.2	10.6	9.9	9.4	9.0	8.6	8.2	7.7	7.5	7.3	6.9	6.7	6.6
	0.45	47.1	43.4	40.8	37.3	35.5	33.5	31.2	29.5	28.4	26.7	25.9	24.7	23.7	23.2	22.0	21.4	20.7
p	0.50	371.2	369.1	370.4	371.4	371.8	370.8	369.8	370.3	370.7	370.3	371.6	369.7	370.5	369.2	370.7	371.1	370.0
	0.55	47.8	43.8	40.8	37.4	35.6	33.0	31.3	29.7	28.5	27.0	25.9	24.3	23.9	23.0	22.0	21.2	20.8
	0.60	15.1	13.9	12.9	11.9	11.2	10.7	9.9	9.4	9.0	8.6	8.3	7.8	7.5	7.3	6.9	6.7	6.6
	0.65	7.6	7.0	6.5	6.0	5.7	5.4	5.0	4.7	4.6	4.3	4.2	3.8	3.7	3.7	3.4	3.4	3.3
	0.70	4.6	4.3	4.0	3.6	3.5	3.4	3.0	2.9	2.8	2.6	2.5	2.3	2.3	2.3	2.1	2.1	2.1
	0.75	3.0	2.9	2.8	2.4	2.4	2.3	2.0	2.0	2.0	1.8	1.8	1.6	1.6	1.6	1.5	1.5	1.5
	0.80	2.1	2.1	2.0	1.7	1.7	1.7	1.5	1.5	1.5	1.4	1.4	1.2	1.2	1.3	1.2	1.2	1.2
	0.85	1.6	1.6	1.6	1.4	1.4	1.4	1.2	1.2	1.2	1.1	1.1	1.1	1.1	1.1	1.0	1.0	1.0
	0.90	1.3	1.3	1.3	1.1	1.1	1.2	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0
	0.95	1.1	1.1	1.1	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0	1.0

considered in this study. However, the rate of decline in ARL_1 , $MDRL_1$, and $SDRL_1$ values varies with the distribution.

4. Performance comparison

In this section, the performance of the proposed chart is compared with those of the existing nonparametric EWMA sign and CUSUM mean control chart by using ARL_1 values for various shifts. Besides, two examples are presented in this section. Considering $n = 10, 15, 20, p_0 = 0.50$, and $ARL_0 = 370$, the ARL_1 curves of the nonparametric EWMA sign, CUSUM mean, and CEWMA sign control charts are shown in Figures 1–3 for various shifts in the process proportion.



Figure 1. ARL curves of the nonparametric CEWMA sign, EWMA sign, and CUSUM mean control charts at n = 10 and $ARL_0 \approx 370$.



Figure 2. ARL curves of the nonparametric CEWMA sign, EWMA sign, and CUSUM mean control charts at n = 15 and $ARL_0 \approx 370$.



Figure 3. ARL curves of the nonparametric CEWMA sign, EWMA sign, and CUSUM mean control charts at n = 20 and $ARL_0 \approx 370$.

Table 5. The run-length characteristic of the proposed Composite Exponentially Weighted Moving Average (CEWMA) chart under various distributions for $\lambda_1 = \lambda_2 = 0.05$, n = 10, and k = 1.954 at $ARL_0 \approx 370$.

Distribution	Characteristic	istic												
Distribution	Characteristic	0.00	0.05	0.10	0.25	0.50	0.75	1.00	1.50	2.00	2.5	3.0		
	ARL	370.8	141.9	54.2	12.9	4.1	2.2	1.6	1.1	1.0	1.0	1.0		
N(0,1)	SDRL	423.8	150.8	50.6	10.4	3.0	1.3	0.7	0.4	0.1	0.0	0.0		
	MDRL	235	97	42	10	3	2	1	1	1	1	1		
	ARL	371.3	99.3	35.4	8.2	2.8	1.7	1.4	1.1	1.0	1.0	1.0		
t(4)	SDRL	416.3	100.7	31.4	6.4	1.8	0.8	0.5	0.3	0.2	0.1	0.0		
	MDRL	239	71	28	7	2	2	1	1	1	1	1		
	ARL	371.1	126.4	45.7	10.9	3.5	2.0	1.5	1.1	1.0	1.0	1.0		
t(8)	SDRL	417.9	129.7	41.9	8.7	2.5	1.1	0.7	0.3	0.2	0.1	0.0		
× /	MDRL	237	88	36	9	3	2	1	1	1	1	1		
CN	ARL	370.3	128.1	47.2	11.1	3.6	2.1	1.5	1.1	1.0	1.0	1.0		
	SDRL	417.3	133.4	42.9	8.9	2.6	1.2	0.7	0.3	0.1	0.0	0.0		
	MDRL	234	88	37	9	3	2	1	1	1	1	1		
	ARL	368.4	123.2	45.0	10.6	3.4	2.0	1.5	1.1	1.0	1.0	1.0		
$LG(0,\sqrt{3}/\pi)$	SDRL	417.8	127.7	40.7	8.5	2.4	1.1	0.7	0.3	0.2	0.1	0.0		
	MDRL	235	86	36	9	2	2	1	1	1	1	1		
	ARL	369.2	69.8	25.1	6.4	2.6	1.7	1.4	1.1	1.0	1.0	1.0		
$Laplace(0, 1/\sqrt{2})$	SDRL	412.8	67.2	21.2	4.9	1.6	0.8	0.6	0.3	0.2	0.1	0.1		
	MDRL	237	52	20	5	2	2	1	1	1	1	1		
	ARL	371.6	132.7	50.5	12.4	4.1	2.3	1.7	1.2	1.0	1.0	1.0		
Gamma(4,1)	SDRL	415.9	140.3	46.4	10.0	3.0	1.4	0.8	0.4	0.2	0.1	0.0		
	MDRL	237	91	39	10	3	2	2	1	1	1	1		
	ARL	369.7	165.1	68.5	17.5	6.5	3.9	2.8	1.9	1.6	1.4	1.3		
Weibull(2,1)	SDRL	415.6	174.6	64.9	14.3	5.1	2.8	1.8	1.0	0.7	0.6	0.5		
	MDRL	237	113	52	14	5	3	2	2	1	1	1		

It can be observed that the nonparametric EWMA sign and CUSUM mean control charts produce almost similar results and the proposed CEWMA sign control chart remains on the lower side for all shifts. This shows that the proposed chart outperforms for all shifts of p_1 and for different sample sizes.

4.1. Example 1

To illustrate the shift detection ability of the CEWMA sign and EWMA sign control charts, the following example with description taken from Montgomery [36] is considered.

"The fill volume of soft-drink beverage bottles is an important quality characteristic. The volume is measured (approximately) by placing a gauge over the crown and comparing the height of the liquid in the neck of the bottle against a coded scale. On this scale, a reading of zero corresponds to the correct fill height".

In this example, we have 15 subgroups each which with size of 10 and the target value of 0. By choosing $\lambda = 0.05$ and k = 2.49 at $ARL_0 \approx 370$, we obtain 4.36 and 5.63 as the lower and upper control limits for the EWMA sign chart, respectively. The monitoring statistic E_{S_t} of the EWMA sign chart is computed and plotted against their respective control limits in Figure 4. We see that the nonparametric EWMA sign chart detects an OOC signal in sample 13. For rational evaluation of the EWMA sign chart is constructed by considering $\lambda_1 = \lambda_2 = \lambda = 0.05$ and k = 1.954, as shown in Figure 5. The last two columns of Table 6 show time-varying lower and upper control limits of



Figure 4. Nonparametric EWMA sign control chart for the fill height data using $\lambda = 0.05$ and k = 2.49 at $ARL_0 \approx 370$.



Figure 5. Nonparametric CEWMA sign chart for the fill height data using $\lambda_1 = \lambda_2 = 0.05$ and k = 1.954 at $ARL_0 \approx 370$.

the CEWMA sign chart. Here, we notice that the proposed chart has identified the OOC signal in sample 12. This shows that the nonparametric CEWMA sign chart performs better than the nonparametric EWMA sign chart regarding the quick detection of the process shift.

4.2. Example 2

To demonstrate the detection ability of the proposed CEWMA sign chart for the dataset from a skewed distribution, 40 samples of size 15 are generated separately from the gamma distribution. The first 30 samples are generated from a gamma distribution with shape parameter 4 and the rate parameter 1 (IC process). Assuming the shift in shape parameter to 4.25 and the rate parameter to 1 (OOC process), the next 10 samples are then generated from this shifted gamma distribution. The average values of the two different gamma-distributed samples are 3.91 and 4.3, respectively. Based on the aforementioned information, parametric and nonparametric control charts are constructed to assess the performance of the suggested chart.

Choosing $ARL_0 = 370$, we construct the Shewhart \overline{X} control chart as shown in Figure 6 and the time-varying EWMA control chart with $\lambda = 0.05$ and L = 2.492, as shown in Figure 7, with the assumption that the quality characteristic is normally distributed. Furthermore, we construct three nonparametric control charts, i.e., the EWMA sign chart with parameters $\lambda = 0.05$ and k = 2.49, the CUSUM mean control chart with parameters $K_1 = 0.75$ and $H_1 = \pm 11.30$, and the proposed CEWMA sign chart with parameters $\lambda_1 = \lambda_2 = \lambda = 0.05$ and k = 1.958, to guarantee that $ARL_0 \approx 370$. The results of the nonparametric control

Table 6. Existing nonparametric Exponentially Weighted Moving Average (EWMA) sign and the proposed nonparametric Composite Exponentially Weighted Moving Average (CEWMA) sign control charts for the dataset from Montgomery [36], the fill volume of soft-drink beverage bottle.

Sample	X_1	X_2	X_3	X_4	X_5	X_6	X_7	X_8	X_9	X_{10}	S_t	${oldsymbol E}_{St}$	HE_{S_t}	L CL	UCL
1	2.5	0.5	2	-1	1	-1	0.5	1.5	0.5	-1.5	7	5.1000	5.0050	4.9923	5.0077
2	0	0	0.5	1	1.5	1	-1	1	1.5	-1	6	5.1450	5.0120	4.9834	5.0166
3	1.5	1	1	-1	0	-1.5	-1	-1	1	-1	4	5.0878	5.0158	4.9733	5.0267
4	0	0.5	-2	0	-1	1.5	-1.5	0	-2	-1.5	2	4.9334	5.0117	4.9624	5.0376
5	0	0	0	-0.5	0.5	1	-0.5	-0.5	0	0	2	4.7867	5.0004	4.9510	5.0490
6	1	-0.5	0	0	0	0.5	-1	1	-2	1	4	4.7474	4.9878	4.9393	5.0607
7	1	-1	-1	-1	0	1.5	0	1	0	0	3	4.6600	4.9714	4.9274	5.0726
8	0	-1.5	-0.5	1.5	0	0	0	-1	0.5	-0.5	2	4.5270	4.9492	4.9156	5.0844
9	-2	-1.5	1.5	1.5	0	0	0.5	1	0	1	5	4.5506	4.9292	4.9038	5.0962
10	-0.5	3.5	0	-1	-1.5	-1.5	-1	-1	1	0.5	3	4.4731	4.9064	4.8922	5.1078
11	0	1.5	0	0	2	-1.5	0.5	-0.5	2	-1	4	4.4495	4.8836	4.8808	5.1192
12	0	-2	-0.5	0	-0.5	2	1.5	0	0.5	-1	3	4.3770	4.8582	4.8696	5.1304
13	-1	-0.5	-0.5	-1	0	0.5	0.5	-1.5	-1	-1	2	4.2581	4.8282	4.8588	5.1412
14	0.5	1	-1	-0.5	-2	-1	-1.5	0	1.5	1.5	4	4.2452	4.7991	4.8483	5.1517
15	1	0	1.5	1.5	1	-1	0	1	-2	-1.5	5	4.2830	4.7733	4.8381	5.1619



Figure 6. Shewhart \overline{X} chart for the simulated data set using $A_2 = 0.223$ at $ARL_0 \approx 370$.



Figure 7. Classical EWMA chart for the simulated data set using $\lambda = 0.05$ and L = 2.492 at $ARL_0 \approx 370$.



Figure 8. Nonparametric EWMA sign chart for the simulated data using $\lambda = 0.05$ and k = 2.49 at $ARL_0 \approx 370$.

charts are provided in Table 7 and displayed graphically in Figures 8–10. In these schemes, the statistic E_{S_t} is plotted against the control limits LCL = 6.7279and UCL = 8.2721 for the nonparametric EWMA sign chart, C_t^+ 's and C_t^- 's are plotted against the decision interval H_1 for the nonparametric CUSUM mean chart, and HE_{S_t} is plotted against time-varying control limits for the proposed CEWMA sign chart.

It is apparent from Figure 10 that the suggested control chart triggers OOC signals in samples 35– 40, whereas Figures 6–9 show that the Shewhart \overline{X} , classical EWMA, nonparametric EWMA sign, and nonparametric CUSUM mean control charts fail to identify this shift in the given dataset. This example



Figure 9. Nonparametric CUSUM mean control chart for the simulated data using $K_1 = 0.75$ and $H_1 = 11.30$ at $ARL_0 \approx 370$.



Figure 10. Nonparametric CEWMA sign control chart for the simulated data using $\lambda_1 = \lambda_2 = 0.05$ and k = 1.958at $ARL_0 \approx 370$.

points to the superiority of the proposed chart in identifying small shifts in the process over the four other competing parametric and nonparametric control charts.

5. Conclusion

In this study, a new nonparametric Composite Exponentially Weighted Moving Average (CEWMA) sign chart that represented the combination of two EWMA statistics was proposed. The proposed chart could be used to detect process shifts quickly, particularly smaller shifts, by using different combinations of the sensitivity parameters λ_1 and λ_2 . The suggested CEWMA sign chart could attract wider applicability as the performance of the CEWMA sign chart was superior to the existing nonparametric Exponentially Weighted Moving Average (EWMA) sign chart and the nonparametric CUSUM mean chart. Furthermore, the nonparametric EWMA sign chart is a special case of the proposed CEWMA chart when either λ_1 or λ_2 equals one. The practical implementation of our proposed chart was illustrated using a real-life example. Moreover, results based on the simulation study showed that the suggested chart completely dominated the

: itaset.	UCL	7.51	7.52	7.53	7.55	7.56	7.57	7.59	7.60	7.62	7.63	7.65	7.66	7.67	7.69	7.70	7.71	7.72	7.73	7.74	7.75	7.76	7.77	7.78	7.79	7.80	7.81	7.81	7.82	7.83	7.83	7.84	7.85	7.85	7.86	7.86	7.86	7.87	7.87	7.88	7.88
ametric ated da	LCL	7.49	7.48	7.47	7.45	7.44	7.43	7.41	7.40	7.38	7.37	7.35	7.34	7.33	7.31	7.30	7.29	7.28	7.27	7.26	7.25	7.24	7.23	7.22	7.21	7.20	7.19	7.19	7.18	7.17	7.17	7.16	7.15	7.15	7.14	7.14	7.14	7.13	7.13	7.12	7.12
nonpar; simula	HE_{S_t}	7.50	7.50	7.50	7.50	7.49	7.49	7.48	7.47	7.46	7.46	7.45	7.45	7.44	7.44	7.44	7.44	7.43	7.43	7.42	7.40	7.38	7.36	7.35	7.33	7.32	7.30	7.28	7.26	7.24	7.22	7.20	7.18	7.17	7.16	7.14	7.12	7.11	7.10	7.10	7.10
sign, r for the	E_{S_t}	7.48	7.45	7.58	7.45	7.43	7.31	7.29	7.38	7.31	7.34	7.32	7.36	7.39	7.47	7.35	7.43	7.36	7.34	7.22	7.06	6.96	7.01	7.06	7.01	7.06	6.90	6.91	6.91	6.87	6.77	6.89	6.89	7.00	6.80	6.81	6.87	6.92	6.93	7.03	6.98
NMA harts	C_t^+	0	0	2.5	0	0	0	0	0.75	0	0	0	0	0	0.75	0	0.75	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0.75	0	0.75	0	0	0	0	0	0.75	0
tric EV ntrol c	C_t^{-1}	0	0	0	-1.75	-1.5	-3.25	°-	-0.75	-1.5	-0.25	0	0	0	0	-1.75	0	-0.75	-0.5	-2.25	ي. ۲	-6.75	-5.5	-4.25	<u>-</u> ت	-3.75	-6.5	-6.25	9-	-6.75	-8.5	-6.25	-9	-3.75	-7.5	-7.25	-9	-4.75	-4.5	-2.25	-3
rame gn coi	S_t	4	7	10	S	7	5	7	6	9	×	7	×	×	6	2	6	9	7	5	4	5	×	×	9	×	4	2	2	9	5	6	7	6	ŝ	7	×	×	7	6	9
A), nonpa WMA) sig	EWMA	4.00	3.98	4.05	4.04	4.03	4.01	4.01	4.01	4.00	4.01	3.97	3.98	3.98	4.02	4.01	4.03	4.01	3.99	3.98	3.96	3.93	3.95	3.94	3.93	3.95	3.94	3.95	3.91	3.90	3.89	3.91	3.95	4.02	3.98	4.02	4.01	4.02	4.05	4.08	4.04
EWM. e (CE'	Y	4.04	3.61	5.31	3.88	3.90	3.57	4.04	3.88	3.98	4.16	3.27	4.00	4.07	4.84	3.83	4.35	3.64	3.68	3.70	3.51	3.49	4.19	3.86	3.77	4.28	3.84	3.99	3.16	3.81	3.64	4.30	4.80	5.25	3.33	4.68	3.83	4.27	4.58	4.61	3.38
age (] verag	Y_{15}	7.77	2.88	4.32	1.78	5.58	3.45	2.22	4.10	7.51	0.84	4.70	3.38	5.25	3.53	2.04	1.97	4.46	2.68	3.37	3.57	3.23	3.82	5.05	2.12	6.26	2.62	3.57	4.37	2.76	4.52	8.90	2.11	1.49	1.08	6.70	3.47	5.59	4.67	2.54	1.78
g Avei ving A	Ý14	.86	.12	.60	.66	.17	.52	.16	.82	.81	.77	.47	.42	.59	.45	.17	.70	.85	.62	00.	56	.00	.44	.46	.97	.51	.20	.57	.25	.86	.23	.15	.67	1.08	.29	.90	66.	.26	.14	.25	.41
doving d Mov	Y13	31 5	.54 4	.21 7	.84	.32 4	.63 2	.52 3	.67]	.73 5	.27 4	.02 4	88.	.19 2	.06	.49 3	.85	.07	.46 2	.73 5	.58 4	68.	.75 5	.43 4	.36 4	.44 4	:61	.16	.88	.01	.81 4	.14	.71 6	68.	.54	.50	.43]	.22 4	.67 7	.21 7	F 60.
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ric Ex] posite	8	33 1.	94 4.	.49 1.	17 3.	73 0.	64 3.	76 4.	95 1.	75 5.	33 3.	81 2.	20 5.	08 1.	54 5.	67 1.	64 5.	87 4.	42 5.	05 3.	33 2.	25 4.	89 4.	16 5.	59 3.	94 2.	44 6.	78 3.	68 1.	10 4.	78 3.	79 1.	60 3.	06 7.	87 2.	52 6.	78 4.	17 1.	09 2.	41 3.	09 2.
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on pai ietric	K	8 2.5	3 1.5	1 2.1	1 6.7	4 2.9	7 3.1	3 4.1	0 3.5	5 3.0	0 7.4	1 3.8	3 2.7	0 5.8	7 6.1	8 2.3	4 4.1	5 6.2	5 5.1	6.6	9 1.9	0 4.5	0 5.2	7 5.2	7 2.8	3 2.5	4 8.4	7 5.5	5 2.9	1 8.6	9 2.0	7 7.1	3 1.8	1 5.8	3 2.6	4 4.0	6 2.8	3 3.1	7 3.6	5 2.4	9 4.0
ing n param	Y_{θ}	1.8	3.3	6.7	8.9	1.9	2.2	1.6	5.2	6.2	6.1	2.9	4.7	4.6	4.3	5.7	4.1	2.2	5.6	3.9	2.8	3.5	8 1.8	4.3	4.4	3.7	2.5	2.3	5.0	1.6	2.4	3.7	5.9	3.1	3.7	3.0	1.0	3.9	5.9	4.5	2.7
l Exist d non	Y_5	5.70	2.18	6.65	3.14	6.30	6.22	1.33	2.45	2.34	1.31	1.47	2.15	3.91	4.79	0.77	6.35	2.36	5.67	3.05	2.50	2.72	10.13	3.16	3.52	3.78	4.47	4.38	0.40	5.59	5.63	5.09	6.80	6.93	3.00	9.55	2.35	3.14	7.39	8.67	5.39
assical an, and	Y_4	1.69	1.75	3.51	4.23	2.24	5.19	10.49	5.36	0.90	0.75	4.44	3.48	3.79	3.39	3.07	5.89	2.24	3.66	4.15	4.10	1.97	3.05	0.71	5.34	6.15	10.05	3.74	3.70	1.54	4.26	3.91	1.97	4.98	1.92	3.13	4.24	4.90	3.14	1.46	4.97
$(\overline{X}, c]$	Y_3	3.02	7.00	2.40	2.33	1.47	1.26	4.12	3.63	3.61	1.89	1.94	4.83	5.89	3.45	3.10	6.67	6.73	4.02	3.86	3.68	3.11	3.03	1.70	3.17	4.32	1.28	4.91	4.43	2.38	3.24	3.97	8.00	5.79	2.66	7.00	7.52	10.00	3.35	3.93	1.64
ewhart USUN	Y_2	4.35	1.58	6.39	1.43	4.53	3.02	4.76	5.17	2.54	3.53	0.69	5.34	2.47	5.70	5.46	2.08	2.53	1.31	3.24	3.33	8.24	3.98	3.81	6.32	3.84	3.10	1.39	6.81	3.95	1.23	5.03	3.45	5.26	3.29	3.43	2.13	3.58	7.89	6.32	3.96
ae She Sum (Y_1	2.20	4.33	1.42	3.49	6.42	5.98	2.07	5.32	2.60	5.50	4.22	1.17	5.59	3.27	3.36	5.35	4.40	4.31	2.04	3.97	3.94	3.38	3.13	3.90	8.20	2.79	5.79	4.12	3.85	3.15	6.33	8.72	5.27	3.02	2.76	4.89	3.10	3.04	4.13	2.21
Table 7. TlCumulative 5	Sample		2	က	4	5	9	7	8	6	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40

other competing parametric and nonparametric control charts in detecting smaller shifts. Hence, the use of CEWMA sign control chart is recommended for the practitioners, if complete knowledge about the underlying process distribution is not available. One can further extend this scheme by developing the CEWMA sign chart using other nonparametric tests such as the Mann-Whitney test.

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