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# Multi-objective optimization of green supply chain network designs for transportation mode selection

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design; Green supply chain; Transportation mode; Multi-objective optimization. Abstract. This research considers both cost and environmental protection to design a multi-objective optimization model. With multi-period customer demands, the model can solve a multi-plant resource allocation and production planning problem by focusing the decisions on supplier selection, facility selection, production batches, transportation mode selection, and distribution of the materials and commodities of a green supply network. In this paper, four transportation modes, namely, road, rail, air, and sea, have their corresponding transportation time, costs, and CO<sub>2</sub> emissions. Based on multiple planning periods, this research calculates the minimal total cost and total CO<sub>2</sub> emissions based on production and transportation capacity. Using numerical analyses, the results show that, when the budget is sufficient, only production capabilities with  $\alpha = 1.5$  and 2.0 are beneficial for improving environmental protection; carbon dioxide emissions of both production capacities are not significantly different. Furthermore, when the production batch size increases, total cost increases. Regarding transportation quantity limits will be slightly beneficial for improving environmental protection.

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## 1. Introduction

Global climate change has become a key topic and international trends have shifted toward increased regulation of greenhouse gas emissions. In addition, economic globalization has linked the environment closely to global supply chains. Production activities consume tremendous energy, with the manufacturing and transportation industries producing the most carbon dioxide. Thus, corporations that wish to reduce greenhouse gas emissions in their supply chain should begin with their manufacturing and transportation methods [1].

Beamon [2] defined a supply chain as "the network structure of raw material suppliers, manufacturers, wholesalers, retailers, and end customers involved in the production and transportation of a product formed through integration." To enable effective, long-term operations of the entire supply chain, the design of Supply Chain Management (SCM) networks frequently involves strategic policy concerns that encompass material sources, plant location selections, plant production capabilities, and inventory management [3]. SCM

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networks also involve the selection of transportation routes, which include raw material supply and transportation modes that begin at the supply end and finish with the customers [4-6]. Melo et al. [7] divided SCM network design according to the nature of product demand and supply chain complexity into the following four categories: (a) single-stage or multi-stage supply chains; (b) single-product or multi-product supply chains; (c) single-period or multi-period planning; and (d) fixed demand or random demand.

Since 2000, SCM research topics have shifted toward multiple products. Rizk et al. [8] examined the dynamic production and transportation problems involving multiple products using a single plant location and distribution center to plan production, transportation, and inventory within a limited cycle. The study contained different transportation times and costs to solve the values of decision variables with the objective of minimizing cost. Similar studies include Nishi et al. [9] who used Lagrangian decomposition to solve the multi-stage supply network problems of a single plant with multiple products. Kanyalkar and Adil [10] incorporated production capabilities and limited inventory space, and applied the heuristic method to maximize target profits. Hugo and Pistikopoulos [11] developed a multi-supplier and multi-plant production transportation network model of production investment choices to select production technology investments that achieved the target net present value and carbon emission minimization.

In practice, product movement cannot be achieved by relying on only one transportation mode. Suitable transportation modes must be selected on the basis of product weight, dimensions, product value, and urgency. Das and Sengupta [12] investigated numerous uncertain factors involved in international corporation strategies and operations, including investment in raw materials, transit costs, duties, and changes in demand and transportation time. This two-stage mathematical solution model used profit maximization as the strategic dimension target to obtain supply chain network decisions (e.g., whether plants should enter production, product types, and quantity produced by each plant). The results were then used in the operations dimension to explore cost minimization inventory strategies when transportation times fluctuated.

Sadjady and Davoudpour [13] discussed singlephase requirements and network planning of multiple products, and then used cost minimization to determine the location of plants and distribution warehouses and transportation modes. The Mixed Integer Programming (MIP) model proposed by Sadjady and Davoudpour incorporated transportation times, carrying costs, and facility setup costs of various transportation modes and used Lagrangian relaxation to obtain solutions.

Typically, supply chain network designs do not have single objectives; decisions must frequently balance different and even mutually exclusive objectives. Researchers have focused on multiple-objective programming problems because actual situations require fulfilling two or more objectives simultaneously. Multiple objectives require managers to balance numerous objectives and use this balance as the basis of decision making [14-16]. For example, cost is no longer the only objective in supply chain design; other economic objectives are responsiveness and service standards. As Melo et al. [7] indicated, in addition to the supply chain network design, which involves plant site selection, facility number and production capacity, and movement of raw materials and products between plants, increasing environmental social awareness has advanced environmental topics to the forefront in SCM.

Unlike typical supply chain design models, which emphasize cost minimization, numerous scholars have recently introduced environmental protection concepts into SCM to ensure that both economic and environmental protection factors are considered [14,17]. Wang et al. [18] used investment in equipment and plants combined with costs and carbon dioxide emissions to vield innovative designs of multiple-objective supply chains. Hugo and Pistikopoulos [11] included the product Life Cycle Assessment (LCA) into decision criteria and proposed a multiple-objective MIP. Ferretti et al. [19] used the aluminum supply chain in the aluminum industry as an example to evaluate the influence of the economy and environment. This mathematical model incorporated the supply capabilities of suppliers, equipment depreciation, costs, and carbon emissions during the production and transportation process. The objective was to balance minimal total cost and environmental protection requirements of producing the least amount of pollution. Cholette and Venkat [20] maintained that the design of supply chain networks had a direct correlation with energy consumption and carbon emissions. They considered the wine making industry to explore the influence of plant and warehouse location, transportation modes, and inventory management strategies on carbon dioxide emissions. Their results indicated that inventory management and plant location could effectively reduce carbon dioxide emissions. Paksoy [21] proposed a production-transportation MIP model for three-stage supply chain networks that considered the raw material sources, transportation quantity limitations of raw materials, and transportation modes. Paksoy added carbon emission quotas to the supply chain network plan. The results indicated that the design of supply networks could be used to reduce carbon dioxide emissions from industries. Chiu et al. [22] studied a 5-layer supply chain network problem with reverse logistics, which contained suppliers, manufacturers, wholesalers,

retailers, and end customers. The authors calculated total revenues and total cost of forward and reverse supply chain based on different scenarios and, then, applied fuzzy summation calculations to calculate the value of each scenario.

Tables 1(a) and 1(b) summarize relevant references. Studies related to supply chains are divided into: (a) supply chain types, namely, Traditional Supply Chain (TSC) in Table 1(a) or Green Supply Chain (GSC) in Table 1(b); (b) factors such as capacity, inventory, and production; (c) demands (deterministic or stochastic); (d) transportation modes (single or multiple) or product (single or multiple); (e) periods (single or multiple); and (f) other aspects.

In terms of the multi-transportation mode of the green supply chain network, Jamshidi et al. [23] considered multi-objective functions (minimal total cost and minimal gas emissions) of the green supply chain problem, which contained multiple customers, distribution centers, warehouses, manufacturers, suppliers, and transportation modes. Al-e-Hashem et al. [24] studied a stochastic green supply chain problem, which contained multi-product, multitransportation mode, multi-plant, multi-period, and limitations of  $CO_2$  emissions. They formulated a twostage stochastic optimization model and calculated its expected minimal total cost. Meanwhile, Fahimnia et al. [25] presented a green supply chain problem whose objective function was to minimize total costs. The authors considered multiple products, suppliers, manufacturers, retailers, transportation modes, and planning periods. They constructed an MIP model and applied CPLEX to obtain the optimal solution. Coskun et al. [26] studied a green supply chain network that consisted of stores, carriers, distribution centers, and manufacturers. They considered demand, capacity, and greenness expectations of manufacturers, carriers, distribution centers, and retailers to construct an MIP model and applied goal programming to solve the proposed model. Enteraminia et al. [27] integrated collection and recycling centers into a green supply chain network; its features consisted of multi-period, multi-product, multi-transportation mode, and multisite factors. For the green concept, they added the limitations of  $CO_2$  emissions in both production and transportation as constraints and added one objective function. Although the studies discussed here considered transportation capacity and  $CO_2$  emissions of each transportation mode, they did not consider the transportation time of each transportation mode in their supply chain network and nor did they investigate the impact of transportation-mode selection decisions on the green supply chain network design. Addressing this limitation is a strong motivation of the current research.

Furthermore, the difference between Wang et

al. [18] and the current research is that Wang et al. [18] studied a supply chain network design problem, namely, a one-time decision, to determine the new locations and new investment levels of factories among potential alternatives, in order to minimize total costs and  $CO_2$  emissions simultaneously. In their model, they considered multiple products, suppliers, and customers, but they did not consider multiple transportation modes or multiple planning periods. Wang et al.'s [18] model is useful for helping companies, especially international/foreign companies, to decide on their factories' locations and investment levels prior to entering a new market, thereby creating a new supply chain network. However, the current research focuses on determining multi-period decisions about production batches produced by each factory and transportation modes used by each pair of supply chain partners. Although the objective functions (total cost and  $CO_2$  emissions) in both models (Wang et al. [18]) and the current research) are similar, the detailed items of the objective functions are different. In addition, the model in the current research is useful for enabling manufacturers to decide on their optimal production batch-size plans among factories and transportation plans (modes) for an existing supply chain network throughout the planning periods. For the constraints of both models, Wang et al. [18] considered flow conservation, supplier capacity, order fulfillment, production capacity, environmental level, and nonnegative and binary constraints whereas the current research considers flow conservation, supplier capacity, order fulfillment, production capacity and production batch size, manufacturing and transportation time of products, transportation capacity between suppliers and manufacturers and between manufacturers and customers, and non-negative and binary constraints. Although the methodologies used by both models (Wang et al. [18] and the current research) are the same, the decisions and constraints in both proposed models are somewhat different, leading to dissimilar observations and conclusions in the two studies. This analysis of the two models serves as the motivation behind the current research.

This study develops a green supply network model by taking into consideration supplier selection, plant batch production, inventory management, selection of multiple transportation modes, and product delivery to customers. The purpose of the study is to investigate the impact of production (plant batch sizes) and transportation capacity (transportation modes) on the multi-period green supply chain network model. The three contributions of this research are described as follows. First, when the budget is sufficient, only production capabilities with  $\alpha = 1.5$  and 2.0 are beneficial for improving environmental protection; carbon dioxide emissions of both production capacities are

Type	Author	Fact	ors	Dei	mand	Tra	nsportatio	n Pr	oduct	- Pe	riod	Other aspects
rype	Author	race	.012				mode		Julici			other aspects
TSC	Aliev et al. [4]	© ⊚	● ●	D	<u>S</u> ⊚	S	<u>M</u> ©	S	<u>M</u>	S	<u>M</u> ⊚	Fuzzy variables/parameters,
TSC	Rizk et al. [8]	00	۲	۲		٢			۲		۲	Machines, production sequence, setup time, and production lead-time
TSC	Kanyalkar and Adil [10]	00	۲	۲		۲			۲		۲	Shorter and longer time periods, storage space, and raw material availability
TSC	Das and Sengupta [12]	0 0	٢		٢	۲			۲		۲	Strategic and operational planning models, minimum breakeven level capacity, demands with normal distributions, service level, and safety stock
$\operatorname{TSC}$	Sadjady and Davoudpour [13]	00	۲	۲			۲		٢	٢		Capacity levels of each plant and warehouse
$\operatorname{TSC}$	Pyke and Cohen [35]	00	٢		۲	٢		۲			٢	Batch size and reorder point
$\operatorname{TSC}$	Melkote and Daskin [36]	۲	٢	۲		٢		۲		٢		Facility location
$\operatorname{TSC}$	Eksioglu et al. [37]	۲	٢	۲		٢		۲			۲	None
TSC	Farahani and Elahipanah [38]	00	٢	۲		٢			۲		۲	Multi-objective function (total cost and total just-in-time delivery), backorder, and storage capacity
TSC	Selim et al. [39]	0 0	٢	۲		٢			۲		۲	Fuzzified aspiration level, workstations, overtime, backorder, storage capacity, and transportation capacity
TSC	Liang [40]	0 0	۲		۲	٢			۲		۲	Fuzzy multi-objective function (total cost and total delivery time), backorder, labor level, storage capacity, and total budget
TSC	Al-E-Hashem et al. [41]	00	۲	۲		۲			۲		۲	Multi-objective function (total cost and total customer satisfaction), worker skill levels, subcontractor, storage capacity, and worker training
TSC	Rezaei and Davoodi [42]	00	۲	۲		٢			۲		۲	Multi-objective function (total cost, total quality level, and total service level), with/without backorder, safety stock, and storage capacity
TSC	Liu and Papageorgiou [43]	0 0	۲	٥		٢			۲		٢	Multi-objective function (total cost, total flow time, and total lost sales), proportional and capacity utilization

Table 1	(a)	. Summary	of	papers c	of traditional	supply	chain	network	models.
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expansions, and capacity utilization Note: Factors: Supplier/plant capacity (C), Inventory constraints/variables (I), and Production constraints/variables (P). Demand: Deterministic (D), and Stochastic (S). Transportation mode, Product, and Period: Single (S), and Multiple (M).

Туре	e Author	Fact	tors	De	mano	d Tra	nsportation	<sup>1</sup> Pro	oduc	t Pe	erioc	d Other aspects
		CI	D	D	G	- <del>C</del>	M	<u> </u>	М	G	М	_
GSC	Hugo and Pistikopoulos [11]	•	•	©		۲	1V1		•	2	•	Multi-objective function (total cost and total gas emission), capacity expansions at each time period, plant capital investment correlation, and environmental impact assessment
GSC	Cruz [17]	٢			۲	۲		۲		٢		Multi-objective function (total cost and total gas emission), social responsibility, demand market price dynamics, and physical transaction level
$\operatorname{GSC}$	Wang et al. [18]	00	٢	۲		٥			۲	۲		Multi-objective function (total cost and total gas emission) and invest environmental level
GSC	Ferretti et al. [19]	00	٢	۲		۲		٢			۲	Pollution level of each pollutant and maximum allowed pollution level
GSC	Paksoy [21]	۲	۲	۲			۲	۲			۲	$\mathrm{CO}_2$ cost, emission quota penalty, and transportation capacity
GSC	Chiu et al. [22]	00	۲	۲		۲		۲			۲	Minimization total profit of forward and reverse logistics; return resource constraints: most pessimistic, most likely, and most optimistic values
GSC	Jamshidi et al. [23]	0 0		۲			۲		۲	۲		Multi-objective function (total cost and total gas emission), backorder, inventory level that consists of demands of customers with mean and standard deviation, and production lead-time
GSC	Al-e-Hashem et al. [24]	00	٢		۲		۲		٢		۲	Backorder, overtime, CO <sub>2</sub> limit, quantity discount function, and transportation lead-time
GSC	Fahimnia et al. [25]	] ()	۲	۲			۲		۲		۲	Minimization of total cost, $CO_2$ limit, and vehicle speed constraints
GSC	Coskun et al. [26]	٢	۲	۲			٢		۲	۲		Multi-objective function (total income, total cost, total market penalty, total market bonus, and total lost sales), lost sales, and greenness expectation
GSC	Entezaminia et al. [27]	00	۲	۲			٢		۲		۲	Multi-objective function (total cost and total score of environmental criteria), recycling products, overtime, and $CO_2$ limit
GSC	This research	00	٢	۲			٢		۲		۲	Multi-objective function (total cost and gas emission), lot-size, transportation lead-time, and transportation capacity

Table 1(b). Summary of papers of green supply chain network models.

Note: Factors: Supplier/plant capacity (C), Inventory constraints/variables (I), and Production constraints/variables (P). Demand: Deterministic (D), and Stochastic (S). Transportation mode, Product, and Period: Single (S), and Multiple (M). not significantly different. Second, when the production batch size increases, total cost increases. Third, regarding transportation capacity, when the budget is sufficient, increasing transportation quantity limits will be slightly beneficial for improving environmental protection.

### 2. Problem description

This study considers the electronics industry as the subject to investigate a three-stage multiple-product production-transportation network design that incorporates suppliers, plants, and customers. Upstream suppliers are component or material vendors representing different supplier locations, production capabilities, and ordering costs. Midstream plants are primarily responsible for product manufacturing. Because plant manufacturing capabilities are limited, plant selection is required to ensure sufficient production and satisfy customer demand. Downstream represents demand where customers present different product demands at different times. After incorporating the transportation model, the final model structure is shown in Figure 1.

Plants are the core of the production transportation network. The objective of this study is to determine the optimal production batches of a product for each period, component's ordering quantity from each supplier, transported product quantity, product inventory, and transportation quantity corresponding to each transportation mode.

Plants must order components from suppliers based on product requirements. However, suppliers have an upper limit to their supply capability for each period. Suppliers are selected by considering the upper limit of transportation quantity, ordering costs, component carrying costs, and carbon emissions for various transportation combinations.

This study only considers existing plants for plant selection. Electronic product production frequently requires multiplied amounts of fixed production batch size because of production technology or equipment reasons. Thus, in a limited production situation, decision selection involves whether plants should engage in production and when to setup and begin production to fulfill the requirements. Because plants are in batch production, unsold products in each period are converted to inventory and sold in the following period.

Consumer electronic products are usually manufactured using core components and the general components, which can be easily substituted or are similar. This study uses the Bill Of Materials (BOMs) concept to describe product and component relationships. Because customer demands change in each period, so does the quantity ordered by each plant from suppliers. Thus, this study assumes that plants order components from suppliers in a lot-for-lot policy; consequently, component inventory or shortages are not considered.

Regarding the transportation dimension, freight forwarders typically assist in the planning of transportation mode selection and the delivery of transport components and products. Sea and air transportation are the primary international transportation modes; road and rail are the main land transportation modes. Transportation departure points and endpoints are suppliers to plants or plants to customers. The entire transportation process (e.g., road, rail, air, or sea) can have different types of sequences to form compounded transportation modes. For example, a supplier in Fukushima, Japan, uses road (or rail) to ship parts to the Fukushima airport or harbor. The parts are



Figure 1. Problem model diagram.

Combinations of	$\mathbf{Cost}$	Carbon emissions
transportation modes	(\$/unit)	(kg/unit)
Road-air-road	14.88	1.7117
Road-air-rail	10.817	1.5951
Road-sea-road	1.929	0.4043
Road-sea-rail	1.336	0.18221
Rail-air-road	14.76	1.5527
Rail-air-rail	10.697	1.4361
Rail-sea-road	1.831	0.27445
Rail-sea-rail	1.238	0.05236

Table 2. Combinations of transportation modes between Fukushima and Wuhan.

then shipped by plane or ship to the Wuhan airport or harbor in China and then transported by road (or rail) to a Wuhan plant for manufacturing into the final product.

When selecting compound transportation modes, transportation costs and carrying costs are primary considerations. Long transportation distances raise the transportation costs paid by corporations. Each type of transportation combination has its own transportation quantity upper limit. The eight possible transportation combinations, which are applied in this study, cover a range of transportation times, costs, and carbon emissions. Example parameters for the transportation combinations from Fukushima (Japan) to Wuhan (China) are presented in Table 2. Generally, transportation that requires a long time (e.g., maritime shipping) has reduced unit transportation cost and unit carbon emission. These eight transportation combinations will be incorporated in the analyses in Section 4, which entail calculating and converting the transportation distances to obtain the transportation times. Each combination corresponds to the transportation time, cost, and carbon emission parameters of one specific group. The combination formation reduces the symbol complexity of the variables as described in the following sections.

#### 3. Mathematical model and approach

#### 3.1. Symbol definitions

Given that supply chain network, G = (N, A), is composed of numerous nodes and arcs, N represents the nodes in the network: Nodes are divided into suppliers S, plants F, and customers C; thus, N = $S \cup F \cup C$ . The connection between two nodes is called an arc, and represents one shipping lane candidate for product flow. Each shipping lane consists of multiple transportation combinations. Let  $\varphi(i, j)$ be the transportation combinations from node i to node j. For example,  $\varphi(i, j) = 1$  indicates that i to *j* uses transportation combination 1 to transportation cargo and  $\psi = \{\varphi(i, j) : (i, j) \in A\}$ . If the original G(N, A) from the shipping line perspective is converted to the transportation combination perspective, then the supply chain network can be represented by  $G(N, \psi)$ . Detailed parameter and variable definitions are provided in the following:

#### Notations:

## Indices:

t	The index of time periods,	$\operatorname{and}$
	t = 0, 1, 2, 3,, T'	

r The index of components, and  

$$r = 1, 2, 3, ..., R'$$

$$p$$
 The index of products, and  $p = 1, 2, 3, ..., P'$ 

#### Sets:

- $\psi$  The set of transportation combinations
- S The set of suppliers
- F The set of facilities
- C The set of customers
- R The set of components
- P The set of products
- T The set of time periods

#### Parameters:

- $fc_i^t$  The occurring cost when supplier *i* is selected at time period *t*
- $fc_j^t$  Setup cost of manufacturing products at plant j at time period t
- $\begin{array}{ll} pc_{jp}^{t} & \quad \text{Unit manufacturing cost of product } p \\ & \quad \text{at plant } j \text{ at time period } t \end{array}$
- $\begin{array}{ll}tc^t_{\varphi(i,j)r} & \quad \text{Unit transporting cost of component}\\r \text{ from supplier } i \text{ to plant } j \text{ using}\\\text{transportation combination } \varphi(i,j) \text{ at}\\\text{time period } t\end{array}$

- Unit transporting cost of product  $tc_{\varphi(j,k)p}^t$ p from plant j to customer k using transportation combination  $\varphi(i,k)$  at time period t $hc_{in}^t$ Unit holding cost of product p at plant j at time period t $b_{rp}$ Amount of component r required by one unit of product pAmount of product p required by  $d_{kn}^t$ customer k at time period tSupply capacity of supplier i at time  $us_i^t$ period t $uf_i^t$ Production capacity of plant j at time period t $usf_{\varphi(i,j)}^t$ Transportation capacity of transportation combination  $\varphi(i, j)$ from supply i to plant j at time period t  $ufc_{\varphi(j,k)}^t$ Transportation capacity of transportation combination  $\varphi(j,k)$ from plant j to customer k at time period tBatch size of product p at plant j $q_{ip}$  $t_{\varphi(i,j)}$ Transporting time from supplier i to plant j using transportation combination  $\varphi(i, j)$ Transporting time from plant j to  $t_{\varphi(j,k)}$ customer k using transportation combination  $\varphi(j,k)$ Required production capacity to make  $g_{jp}$ one unit of product p at plant jRequired transportation capacity to  $\nu_r$ deliver one unit of component r
- Required transportation capacity to  $\nu_p$ deliver one unit of product p
- Unit holding cost of component r per  $h_r$ period during transportation
- Unit holding cost of product p per  $h_{p}$ period during transportation
- $e_{jp}^t$  $CO_2$  emissions of manufacturing one unit of product p at plant j at time period t
- $CO_2$  emissions of transporting one unit  $e_{\varphi(i,j)r}^t$ of component r from supplier i to plant j using transportation combination  $\varphi(i,j)$  at time period t
- $e_{\varphi(j,k)p}^t$  $CO_2$  emissions of transporting one unit of product p from plant j to customer k using transportation combination  $\varphi(j,k)$  at time period t

# Decision variables:

$X_{jp}^t$	Batches of product $p$ manufactured at
51	plant $i$ at time period $t$

- $X^{t,t+t_{\varphi(i,j)}}_{\varphi(i,j)r}$ Transportation quantities of component r using transportation combination  $\varphi(i, j)$  from supplier *i* at time period t to plant j at time period  $t + t_{\varphi(i,j)}$
- $X_{\varphi(j,k)r}^{t,t+t_{\varphi(j,k)}}$ Transportation quantities of product p using transportation combination  $\varphi(j,k)$  from plant j at time period t to customer k at time period  $t + t_{\varphi(j,k)}$
- $Y_i^t = 1,$ If supplier i takes orders at time period t;  $Y_i^t = 0$ , otherwise
- $Y_{i}^{t} = 1,$ If plant j operates at time period t;  $Y_i^t = 0$ , otherwise

#### Dependent variables:

Inventory of product p kept at plant j $I_{ip}^t$ at time period t

#### 3.2. Mathematical model

Objective function 1:

Minimize cost

$$\begin{split} \sum_{i \in S} \sum_{t \in T} f c_i^t Y_i^t + \sum_{j \in F} \sum_{t \in T} f c_j^t Y_j^t \\ &+ \sum_{j \in F} \sum_{p \in P} \sum_{t \in T} p c_{jp}^t q_{jp} X_{jp}^t \\ &+ \sum_{\varphi(i,j) \in \psi} \sum_{r \in R} \sum_{t \in T: t + t_{\varphi(i,j)} \leq T'} t c_{\varphi(i,j)r}^t X_{\varphi(i,j)r}^{t,t+t_{\varphi(i,j)}} \\ &+ \sum_{\varphi(j,k) \in \psi} \sum_{p \in P} \sum_{t \in T: t + t_{\varphi(j,k)} \leq T'} t c_{\varphi(j,k)p}^t X_{jkp}^{t,t+t_{\varphi(j,k)}} \\ &+ \sum_{\varphi(i,j) \in \psi} \sum_{r \in R} \sum_{t \in T: t + t_{\varphi(i,j)} \leq T'} h_r t_{\varphi(i,j)} X_{\varphi(i,j)r}^{t,t+t_{\varphi(j,k)}} \\ &+ \sum_{\varphi(j,k) \in \psi} \sum_{p \in P} \sum_{t \in T} \sum_{t \in T: t + t_{\varphi(j,k)} \leq T'} h_p t_{\varphi(j,k)} X_{\varphi(j,k)p}^{t,t+t_{\varphi(j,k)}} \\ &+ \sum_{j \in F} \sum_{p \in P} \sum_{t \in T} h c_{jp}^t I_{jp}^t. \end{split}$$

Eq. (1) consists of ordering cost charged by suppliers, setup cost at plants, production cost at plants, transportation cost of components and products, holding cost while transporting components and products, and holding cost at plants.

 $j \in F \ p \in P \ t \in T$ 

D.-C. Gong et al./Scientia Iranica, Transactions E: Industrial Engineering 24 (2017) 3355-3370

Objective function 2:

Minimize  $CO_2$  emissions:

$$\sum_{j \in Fp \in P} \sum_{t \in T} e_{jp}^{t} q_{jp} X_{jp}^{t}$$

$$+ \sum_{\varphi(i,j) \in \psi} \sum_{r \in R} \sum_{t \in T: t + t_{\varphi(i,j)} \leq T'} e_{\varphi(i,j)r}^{t} X_{\varphi(i,j)r}^{t,t+t_{\varphi(i,j)}}$$

$$+ \sum_{\varphi(j,k) \in \psi} \sum_{p \in P} \sum_{t \in T: t + t_{\varphi(j,k)} \leq T'} e_{\varphi(j,k)p}^{t} X_{\varphi(j,k)p}^{t,t+t_{\varphi(j,k)}}.$$
(2)

Eq. (2) represents  $CO_2$  emissions incurred by production at plants, transportation from suppliers to plants, and transportation from plants to customers.

Subject to:

$$\sum_{j \in \varphi(i,j)} X_{\varphi(i,j)r}^{t,t+t_{\varphi(i,j)}} \leq u s_i^t Y_i^t, \quad \forall i \in S, \forall r \in R,$$

for 
$$\{t: t+t_{\varphi(i,j)} \le T'\},$$
 (3)

$$\left(\sum_{i\in\varphi(i,j):t-t_{\varphi(i,j)}\geq 0} X_{\varphi(i,j)r}^{t-t_{\varphi(i,j)},t}\right)/b_{rp} = q_{jp}X_{jp}^{t},$$

$$\forall j \in F, \forall r \in R, p \in P, \forall t = T,$$
(4)

$$I_{jp}^{0} = 0, \quad \forall j \in F, \forall p \in P,$$
(5)

$$I_{jp}^{t-1} + q_{jp} X_{jp}^t - \sum_{k \in \varphi(j,k): t + t_{\varphi(j,k)} \le T'} X_{\varphi(j,k)p}^{t,t+t_{\varphi(j,k)}} = I_{jp}^t,$$

$$\forall j \in F, \forall p \in P, \forall t = \{1, 2, 3, ..., T'\},$$
(6)

$$\sum_{p \in P} g_{jp} q_{jp} X_{jp}^t \le u f_j^t Y_j^t, \quad \forall j \in F, \forall t \in T,$$
(7)

 $\sum_{\substack{j \in \varphi(j,k): t - t_{\varphi(j,k)} \ge 0}} X_{\varphi(j,k)p}^{t - t_{\varphi(j,k)}, t} = d_{kp}^t,$ 

$$\forall k \in C, \forall p \in P, \forall t \in T, \tag{8}$$

where  $d_{kp}^t = 0$ , if  $t < \min_{i \in S, j \in F} \{t_{\varphi(i,j)} + t_{\varphi(j,k)}\}.$ 

$$\sum_{r \in R} \nu_r X_{\varphi(i,j)r}^{t,t+t_{\varphi(i,j)}} \le us f_{\varphi(i,j)}^t,$$
  
$$\forall \varphi(i,j) \in \psi : t + t_{\varphi(i,j)} \le T', \qquad \forall t \in T, \qquad (9)$$

$$\sum_{p \in P} \nu_p X_{\varphi(j,k)p}^{t,t+t_{\varphi(j,k)}} \le uf c_{\varphi(j,k)}^t,$$
$$\forall \varphi(j,k) \in \psi : t + t_{\varphi(j,k)} \le T', \qquad \forall t \in T, \quad (10)$$

$$X_{jp}^t \in \text{Integer}, \quad \forall j \in F, \forall p \in P, \forall t \in T,$$
 (11)

$$X_{\varphi(i,j)r}^{t,t+t_{\varphi(i,j)}} \ge 0, \forall \varphi(i,j) \in \psi : i \in S, j \in F, \quad \forall r \in R,$$
$$\forall t \in T : t + t_{\varphi(i,j)} \le T', \tag{12}$$

$$\begin{split} X^{t,t+t_{\varphi(j,k)}}_{\varphi(j,k)p} &\geq 0, \\ &\forall \varphi(j,k) \in \psi: j \in F, k \in C, \forall p \in F \\ & \cdot \\ & \cdot \\ \end{split}$$

$$\forall t \in T : t + t_{\varphi(j,k)} \le T', \tag{13}$$

$$I_{jp}^t \ge 0, \quad \forall j \in F, \forall p \in P, \forall t \in T,$$
(14)

$$Y_i^t \in \{0, 1\}, \quad \forall i \in S, \forall t \in T,$$
(15)

$$Y_j^t \in \{0, 1\}, \quad \forall j \in F, \forall t \in T.$$

$$(16)$$

Eq. (3) represents the quantities of transporting components to plants being less than or equal to the quantities provided by each supplier at each time period. Eq. (4) represents the number of components ordered from suppliers being equal to the number of products manufactured by each plant at each time period. Eq. (5) represents the inventory at plant jbeing zero at time period 0. Eq. (6) represents flow conservation of each product at each plant at each time period. Eq. (7) represents production capacity at each plant at each time period. Eq. (8) represents the quantities transported to each customer being equal to the demand of each customer at each time period. Since this research assumes that there is no backorder for each customer, the initial demands of each customer are set to 0. Eq. (9) represents the quantities of components transported from suppliers to plants being less than or equal to the capacities of each transportation mode between suppliers and plants at each time period. Eq. (10) represents the quantities of products transported from plants to customers being less than or equal to the capacities of each transportation mode between plants and customers at each time period. Eq. (11) represents the batch size of each product at each plant at each time period, and must be an integer. Eqs. (12) and (13) represent transporting quantities from suppliers to plants and from plants to customers, and the values are non-negative. Eq. (14) represents the amount of inventory, and the value is non-negative. Eqs. (15) and (16) represent the operating status of each supplier and each plant, and the values are binary variables.

3364

#### 3.3. Normalized normal constraint method

The solution to multiple-objective decision problems require determining the optimal solution set, not simply a single optimal solution. The Normalized Normal Constraint (NNC) method is a highly effective method of multiple-objective decision optimization that can be used to produce evenly distributed Pareto solutions. This study applies evenly distributed Pareto-optimal fronts to provide managers with improved decisions. The NNC method proposed by Messac et al. [28] is used to calculate a multiple-objective model. This method does not require the calculation of the initial weight of each objective to produce an evenly distributed Pareto-optimal front. Figure 2 illustrates the multiple-objective Pareto-optimal front and utopia line. When using the optimized solutions method of the secularization techniques, both local and global solutions are typically produced, thereby forming nonconvex Pareto and discontinuous Pareto solutions [29]. However, the NNC calculation method also produces local and global solutions and exhibits non-convex and discontinuous Pareto solutions [28,30]. Therefore, this study adopts the Pareto filter algorithm proposed by Messac et al. [28] to filter non-optimal solutions on the Pareto curve and obtain the optimal global Pareto solutions. Because of space, constraints please references Messac et al. [28] and Martinez et al. [31] for detailed discussions on Pareto solution procedures and Pareto filters.

The NNC method consists of seven steps [28]:

- Step 1: Two anchor points,  $\overline{\mu}^{1*} = (\mu_{11}, \mu_{12})$  and  $\overline{\mu}^{2*} = (\mu_{21}, \mu_{22})$ , are calculated (see Figure 2). In Figure 2, Objective 1 refers to total cost whereas Objective 2 refers to CO<sub>2</sub> emissions.  $\mu_{11}$  is the minimal total cost of the problem (P1) with the objective function in Eq. (1) subject to Eqs. (3) to



Figure 2. Utopia line and Pareto efficiency frontier curve.

(16);  $\mu_{12}$  is the corresponding CO<sub>2</sub> emissions calculated by the same solution.  $\mu_{22}$  is the minimal CO<sub>2</sub> emissions of the problem (P2) with the objective function in Eq. (2) subject to Eqs. (3) to (16);  $\mu_{21}$  is the corresponding total cost calculated by the same solution.

- Step 2: A normalization based on  $(\overline{\mu}^{1*}, \overline{\mu}^{2*})$  is performed because of the different units (NT dollars and kg) of Objectives 1 and 2. After running the normalization,  $\overline{\mu}$  is calculated by using Eq. (17):

$$\overline{\mu} = \left\{ \frac{\mu_1(x) - \mu_1(x^{1*})}{\mu_1(x^{2*}) - \mu_1(x^{1*})}, \frac{\mu_2(x) - \mu_2(x^{2*})}{\mu_2(x^{1*}) - \mu_2(x^{2*})} \right\},$$
(17)

where the Euclidean distance between  $\overline{\mu}^{1*} = (0, 1)$ and the origin = (0, 0) is 1; similarly, the Euclidean distance between  $\overline{\mu}^{2*} = (1, 0)$  and the origin = (0, 0) is 1.

- Step 3: The utopia line vector  $(\overline{N} = \overline{\mu}^{2*} \overline{\mu}^{1*})$ , which is the direction from  $\overline{\mu}^{1*}$  to  $\overline{\mu}^{2*}$ , is calculated.
- Step 4: A normalized increment *m* is calculated. In this study, *m* is 30.
- Step 5: Utopia line points,  $\overline{X}_j$ , using Eq. (18) are generated:

$$\overline{X}_j = \left(\frac{1}{m-1} \times \overline{\mu}^{1*}, (1 - \frac{1}{m-1}) \times \overline{\mu}^{2*}\right),$$
  
for  $j = 1, 2, \cdots, m-1.$  (18)

- Step 6: Each Pareto-point problem, which is the problem (P2), is solved with the objective function in Eq. (2) subject to Eqs. (3) to (16) and the corresponding Eq. (19):

$$\overline{N}(\overline{\mu}_2 - \overline{X}_j)^T \le 0, \tag{19}$$

 $\overline{\mu}_2$  is a point within the feasible region of P2, and the optimal solution of P2 is the point of  $\overline{\mu}_2^*$ .

- Step 7: The real value  $(\mu)$  of each Pareto point,  $\overline{\mu}_2^*$ , is calculated by calculating the inverse of the normalization in Eq. (20):

$$\mu = [\overline{\mu}_1(\mu_1(x^{2*}) - \mu_1(x^{1*})) + \mu_1(x^{1*}), \overline{\mu}_2(\mu_2(x^{1*}) - \mu_2(x^{2*})) + \mu_2(x^{2*})]^T.$$
(20)

#### 4. Case study and numerical analysis

This section presents how the study substitutes data into the mathematical programming model to examine the network design issues in green supply chains. Parameter value changes are used to observe the response status of the entire supply chain. The solution process uses ILOG CPLEX 12.4 to conduct calculations (using an Intel Core i5-2400 CPU with a 3.10 GHz central processor, 8 GB of memory, and the Windows 7 Professional Edition operating system).

#### 4.1. Case study

This study extends the case company background used by Wang et al. [18] and obtains the supplier sources, current plant locations, and customer locations by reviewing references (Figure 3). Assuming that the main sources for components are South Korea, Japan, and Thailand and the assembly plants are distributed in several cities in Taiwan and China, the assembly plants would provide products to local customers.

The case supply chain network comprises three suppliers, four plants, and four customers. To simplify analysis, three products and 12 planning horizon periods are used in this study. Relevant data, such as the product carbon emission coefficients produced by the plants, are obtained from sustainable development reports on products similar to the case company products. The carbon emission coefficients produced by the transportation tools are collected using SimaPro 7.3. software. Transportation distances are measured according to Google Maps. Detailed numerical definitions for the parameters are presented in Table 3. These data are used to obtain the optimal component order quantity, production batch, product delivery quantity, and plant location for various transportation combinations and periods. The data in this example are used to set the demand for the first two periods at zero to ensure that supply shortages do not occur. A set amount of initial product inventory can also be assumed to satisfy initial demand.

Because the ILOG CPLEX 12.4 involves using a branch-and-bound search method in the internal settings during the integer solution process, excessive factors and data in the integer-programming model can overload the memory, resulting in lacking solutions. Therefore, a 1% tolerance deviation is set when searching for the optimal integer solutions. Cordeau et al. [32] asserted that, in practice, a deviation exceeding 1%



Figure 3. Supply chain network of the case company.



Figure 4. Pareto efficiency frontier curve.

frequently occurred in company data sources (e.g., estimations of costs, demands, and production capability); thus, a 1% variation is within the allowable range.

The optimal total cost and carbon emission combinations in the Pareto-optimal front curve are The two terminal points are shown in Figure 4. NT\$862,269,800 and 4,985,400 kg, and \$1,398,400,000 and 4,738,968 kg, respectively. The figure shows the balance between total cost and carbon dioxide emissions. From a marginal utility perspective (e.g., using the farthest left point as the benchmark), the supply chain network design combination corresponding to NT\$941,860,000 and 4,750,100 kg is recommended to corporations. Increasingly stringent restrictions on carbon dioxide generate rapidly increasing cost; however, these effects, which are produced by various factors, are difficult to observe. Thus, in the next section, sensitivity analysis of several main factors is shown to understand how alterations in a variety of factors influence the supply chain network, and this research examines corporate-response decisions.

#### 4.2. Sensitivity analysis

#### 4.2.1. Change in plant production capability

To understand how changes in plant production capability affect decisions, this study adjusts the upper production limit  $\alpha$  according to three values ( $\alpha = 1.25$ , 1.5, and 2.0) to obtain three groups of Pareto-optimal fronts. These three Pareto-optimal fronts are compared with those obtained using the original  $\alpha = 1$ . Figure 5 shows that when production capability increases, costs decrease, resulting in a shift of the entire curve toward the initial point. This indicates that, at the same cost, increased production capacities generate fewer carbon dioxide emissions. In a fixed carbon dioxide emission situation, high production capacity reduces the total cost because increasing plant production capability reduces the required number of transports, thereby reducing transportation costs and concurrent carbon dioxide emissions. Fewer transports reduce the overall

	Parameters	Descriptions
Demand	$d_{kp}^t$	= uniform $(1d, 1.2d)$ , and d is demand ratio
$\operatorname{Cost}$	$egin{aligned} & fc_i^t \ fc_j^t \ pc_{jp}^t \ hc_{jp}^t \end{aligned}$	= uniform $(0.9\tau, 1.1\tau)$ , and $\tau$ is the ordering cost = uniform $(0.9\mu, 1.1\mu)$ , and $\mu$ is the setup cost = product price $\times \omega$ , $\omega$ is a ratio $\leq 1$ = product cost $\times \delta$ = product price $\times \omega \times \delta$ = product cost $\times \theta$ , and $\theta = \omega \times \delta$ is a ratio $\leq 1$
вом	$b_{rn}$	The number of required components of products 1, 2, and 3: $(1, 2)$ , $(1, 2)$ , and $(1, 2)$
	$g_{jp}$	The consumed production capacity of products 1, 2, and 3 is uniform (4, 5)
Consumed capacity	$\nu_r$	The consumed transportation capacity of components 1 and 2 is $(2, 2)$
	$\nu_p$	The consumed transportation capacity of products 1, 2, and 3 is $(3, 3, 3)$
Capacity	$egin{aligned} us_i^t \ uf_i^t \ usf_{arphi(i,j)}^t \ uf_{arphi(j,k)}^t \end{aligned}$	= uniform $(0.8\lambda, 1.2\lambda)$ , and $\lambda$ is a constant = uniform $(0.8\alpha, 1.4\alpha) \times U$ , and $\alpha$ production utilization; $U$ is a constant = uniform $(0.8\beta, 1.4\beta) \times A_{\varphi(i,j)}$ , $\beta$ is the flow utilization; $A_{\varphi(i,j)}$ is a constant = uniform $(0.8\beta, 1.4\beta) \times A_{\varphi(i,j)}$ , and $A_{\varphi(j,k)}$ is a constant
CO <sub>2</sub> emissions	$e_{jp}^t$	= uniform $(0.9e, 1.2e)$ , and e is the CO <sub>2</sub> emissions for producing one product $p$ = uniform $(0.9w_r, 1.2w_r)$ , and $\varphi(i, j)$ is the CO <sub>2</sub> emissions for
	$e^t_{\varphi(i,j)r}$	transporting one component $r$ by using
		transportation mode $\varphi(i, j)$ ; $w_r$ is the weight of the component $r$
	t	= uniform $(0.9w_p, 1.2w_p)$ , and $\varphi(j, k)$ is the CO <sub>2</sub> emissions for
	$e^{\circ}_{\varphi(j,k)p}$	transporting one product p by using transportation mode $\varphi(j, k)$ ; $w_p$ is
		the weight of the product $p$

Table 3. Parameter data set.



**Figure 5.** Pareto efficiency frontier curves of different production capacity ratios.

transportation time; consequently, increased production yields a reduction in carbon dioxide emissions and thereby causes less harm to the environment. This phenomenon is similar to that described by Wang et al. [18]. Reduction in plant production capacity signifies that customer product demand must be supported by production from other plants or additional setup of production lines, thereby raising transportation costs and carbon dioxide emissions produced during transportation.

Further, Figure 5 shows that when the budget is sufficient (greater than 1 billion), only production capabilities with  $\alpha = 1.5$  and 2.0 are beneficial for improving environmental protection, but carbon dioxide emissions of both production capacities are not significantly different. When the budget is limited (less than 0.85 billion), increasing production capacity to  $\alpha = 2.0$  does improve environmental protection. Therefore, when international laws or the government set carbon dioxide emission limitations and the budget is limited, increasing the production capability is a favorable decision.

# 4.2.2. Change in the upper limit of transportation quantity

Different transportation tools have different transportation quantity limits. To understand how transportation quantity changes influence decisions, this study adjusts the production capability rate  $\beta$  and sets three values as the upper limit of the transportation quantity rate (i.e.,  $\beta = 1.25$ , 1.5, and 2.0) to obtain three groups of Pareto-optimal fronts. These three



**Figure 6.** Pareto efficiency frontier curves of different upper bound ratios of transportation capacities.

Pareto-optimal fronts are compared with that obtained using the original  $\beta = 1$ . Figure 6 shows that, except for the  $\beta = 2.0$  curve, the other three curves are the same in the high carbon emission stage. Furthermore, both carbon emissions and total cost decrease when transportation quantity increases. The researchers learnt that when transportation quantity was limited, the limits of corporate component or product transportation raised because variations in transportation costs resulted in high carbon dioxide emissions. Thus, raising the transportation improves the flexibility of the entire supply chain.

Figure 6 shows that when the budget is sufficient (greater than 1 billion NT dollars), increasing transportation quantity limits will be slightly beneficial for improving environmental protection. When the budget is limited (less than 0.9 billion NT dollars), increasing transportation quantity limits is not beneficial for improving environmental protection. Therefore, transportation quantity limits is not a sensitive parameter.

#### 4.2.3. Changes in production batch size

To understand the influence of the size of plant production batches, this study adjusts production batch size ratio  $\rho$  to compare  $\rho = 1.5$  and  $\rho = 2.0$  with the original  $\rho = 1$ . Figure 7 shows that when the carbon dioxide limit is 490,000 kg, plants with the small production batch size reduce the total cost. Figure 7 also shows that when the production batch size increases, total cost increases. However, total costs are not significantly different for the production batch sizes  $\rho = 1.5$  and  $\rho = 2.0$ . The possible reason may be that when customer demands are known and fixed, plants must produce more products due to large production batch sizes. Therefore, when the



**Figure 7.** Pareto efficiency frontier curves of different production batch size ratios.

production batch sizes increase, ordering component, transportation, carrying, and total costs also increase.

In practice, companies prefer the large production batch sizes to small ones, because large production batch sizes can shorten the setup time of machines and be easily scheduled in the production lines. Further, surplus products can be stored for the next-period customer demands. However, the large production batch sizes will increase the transportation and carrying costs and carbon dioxide emissions. There is a trade-off between production preference (large production batch sizes) and total cost (small production batch sizes). Therefore, companies should determine appropriate production batch sizes based on their product characteristics, cost, and environmental factors. This topic merits further research.

#### 5. Conclusion

This study proposed a green supply chain network model that involved calculating multi-phase, multipleobjective integer programming models. The supply chain network model also incorporated carbon emissions, including those produced during the transportation process. The model used the selection of transportation type to reduce carbon emissions during the transportation process. This model can be used by corporations when considering localized environmental influences or globalized supply chain network designs.

Section 3 introduced the mathematical model developed in this study. Section 4 provided examples, sensitivity analysis results, and a discussion of management implications. Figure 5 indicated that production capability increases were beneficial for improving environmental conditions. However, additional costs were required to increase production capability. When carbon dioxide emissions were high, increasing production capability only slightly reduced the total cost. The Pareto curve trends can serve as a reference for decision makers when determining the benefits for companies generated by increasing production capability.

Lowering the upper transportation quantity limit required plants to order the necessary productassembly components from additional suppliers (increasing the number of suppliers), thereby raising the ordering costs. Similarly, the number of times the plant set up production also increased, generating setup production costs. Ordering components and transporting manufacturing products became complex, causing fluctuations in transportation costs and increasing total costs. Figure 6 can be used as a reference for decision makers when determining whether increasing the upper transportation quantity limit would benefit the company.

Total costs rose when the production batch sizes increased, because this production process required the ordering of additional components. Thus, each time components were ordered represented an increase in transportation and carrying costs. When production managers plan multi-phase production activities, the manufactured multi-phase products from each production batch are stored in inventory to ensure that customer demand in the following period is satisfied. A large production batch size from the plant signifies that numerous products are available for storing into inventory and fulfilling multi-period customer demand. Reducing the number of production setups reduces setup costs. However, the transportation and carrying costs produced by the components raised costs. There is a trade-off between production batch size and total cost. Therefore, determining appropriate production batch sizes remains a challenging research topic.

Although this study used the electronics industry as the core, numerous factors were excluded from consideration when exploring overall supply chain planning in the production and delivery model. These factors can be considered in future studies:

- 1. This study considered transportation time, but not the product shortage costs resulting from delayed deliveries subsequent to insufficient production capability or transportation delays [3]. Therefore, future studies should discuss the influence of these factors on supply chain production and delivery;
- 2. This study also did not consider fluctuating customer product demands [33,34]. Thus, product demand uncertainty should be added to the model to conform to actual situations.

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#### **Biographies**

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