



Sharif University of Technology
Scientia Iranica
Transactions A: Civil Engineering
www.scientiairanica.com



Seismic performance of reinforced concrete building in Guwahati city, northeast India

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Received 2 November 2015; received in revised form 1 March 2016; accepted 17 May 2016

KEYWORDS

Concrete building-frame;
Northeast India;
Ground motion simulation;
Nonlinear dynamic analysis;
Random pushover;
Seismic fragility.

Abstract. The seismic risk of reinforced concrete building frame located in the Guwahati City of northeast India is evaluated. To do so, we first conduct a site-specific probabilistic seismic hazard analysis to obtain hazard curve and implement proper selection of ground motion records for nonlinear time history analyses (NLTHA). Subsequently, the NLTHA of the building frame is performed to obtain the drift demand for any particular ground motion level. As the recorded accelerograms in the region are limited, the synthetic and artificial ground motion data are also generated to supplement the data base. Thereafter, the probabilistic structural capacity parameters at various limit states are obtained from random pushover analyses. Based on the knowledge of seismic hazard, demand, and capacity parameters, fragility curves are obtained corresponding to different structural performance levels. The annual probability of failure of the representative example frame is also estimated. The results of the seismic risk analysis indicate that a medium-rise reinforced concrete building frame in the study area with moderate fundamental period is most likely to perform beyond its elastic range. However, such structures designed according to the Indian codes are expected to be sufficient enough to prevent life-threatening risk and complete collapse.

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1. Introduction

A probabilistic framework is necessary to seismic performance assessment of structures to accommodate the inherent randomness in ground motion due to earthquake and uncertainty involved in structural parameters. The Performance-Based Earthquake Engineering (PBEE) for quantifying seismic risk of structures, considering the uncertainties in ground motion characteristics, structural response, physical damage, and economic and human losses, is worth mentioning in this regard [1]. The approach mainly consists of four successive stages: hazard analysis, structural analysis, damage analysis, and loss analysis. The damage analy-

sis is generally referred to as Seismic Fragility Analysis (SFA) where the structural damage levels are identified by constructing fragility curves. It basically represents the probability of exceeding a structural performance level of the demand parameter corresponding to a target hazard level. The loss analysis then computes the amount of economic losses and casualties due to an earthquake. Due to the increasing application of PBEE, the SFA is being accepted as an important tool to assess the performance of structures during future earthquakes.

The present study deals with performance-based seismic risk assessment of concrete building frame located in Guwahati City, northeast (NE) India: one of the six most seismically active regions of the world [2]. The region has experienced nineteen large earthquakes ($M \geq 7$) during the last hundred years [2] including the great Shillong Earthquake (1897, $M = 8.7$) and Assam-

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Tibet Earthquake (1950, $M = 8.7$), and it is placed in the highest hazard zone by the seismic zonation map of the country [3]. Furthermore, there has been a phenomenal increase in the population density and infrastructural developments in the region increasing the vulnerability of human population and structures to the earthquakes. Therefore, realistic seismic risk assessment of the existing structures in the region is imperative for any hazard mitigation measure. The present study deals with performance-based seismic risk assessment of the existing structures in the NE region of India.

Performance-based seismic risk assessment requires Probabilistic Seismic Hazard Analysis (PSHA) to obtain the hazard curve which provides the probability of exceeding various ranges of ground motion intensity measures. Seismic risk assessment also largely hinges on proper evaluation of structural demand parameters through nonlinear time history analyses (NLTHA). To do so, proper selection of ground motion records based on the most vulnerable magnitude distance combination for a specific hazard level is important. These are typically determined from the disaggregation of PSHA. Though some studies are available on PSHA of the region [4,5], site-specific information is not readily available. Moreover, these regional-level PSHA studies do not provide enough information for hazard disaggregation as required for the present study.

In the present study, seismic performance of a typical midrise building, i.e. seven-storey concrete frame building considered to be located in Guwahati city, NE India (Latitude 26.2, Longitude 91.7), is examined. Accordingly, to estimate the seismic hazard curve parameters for the location, a PSHA is first carried out, and the ground motion data necessary for NLTHA of the frame are then judiciously selected. Subsequently, the NLTHA are carried out to obtain the displacement demand parameters for the example frame using a set of selected ground motion records which corresponds to the estimated hazard level of the study area. The recorded accelerograms in the study region corresponding to the target hazard level are limited. To supplement this limitation, artificial and synthetic accelerograms are generated for statistically meaningful study. The deterministic choice of threshold drift capacity may result in an overestimation of the fragility curve [6]. Hence, the probabilistic structural capacity parameters at various limit states are obtained from the random pushover analysis of the considered building frame. Subsequently, with the knowledge of the seismic hazard, demand and capacity parameters, the analytical seismic fragility is obtained and fragility curves are generated corresponding to different structural limit states. The seismic risk, i.e. the annual probability of failure of the frame, is finally estimated.

2. Fundamentals of seismic risk analysis

In the context of the present study, the fundamental of seismic risk analysis is to estimate the probability of exceeding a structural limit state. It is basically a time-dependent reliability analysis problem in which the limit state of interest is the difference between seismic demand and structural capacity and can be mathematically expressed as follows:

$$Z(\mathbf{X}_C, \mathbf{X}_D, t) = C(\mathbf{X}_C, t) - D(\mathbf{X}_D, t), \quad (1)$$

where \mathbf{X}_C and \mathbf{X}_D are the variables governing capacity and demand, respectively, and t is the time parameter. The limit state function for seismic risk can be expressed as follows:

$$\begin{aligned} Z < 0 & \rightarrow \text{Failed} \\ Z = 0 & \rightarrow \text{Limiting} \\ Z > 0 & \rightarrow \text{Safe} \end{aligned} \quad (2)$$

Accordingly, the seismic risk estimate is the evaluation of the probability that the limit state function will be negative which is essentially the evolution of the following integral:

$$P_f = \int_{\Omega} f_Z(\mathbf{X}) d\Omega, \quad (3)$$

where \mathbf{X} is an ' n ' dimensional vector having variables involving seismic demand and capacity, $f_Z(\mathbf{X})$ is the joint probability density function (pdf) of the involved random variables, and Ω is the failure domain in the space of \mathbf{X} where the limit state function is negative. The exact computation of the above is often computationally demanding. In fact, $f_Z(\mathbf{X})$ is hardly available in closed form. Consequently, various approximations are usually adopted to obtain the probability of reaching/exceeding different limit states of damage concerning the given building response parameter under a specific seismic intensity measure.

An excellent state-of-the-art development focusing on the seismic performance of structures that includes modelling of seismic vibration and structural analysis in probabilistic manner is notable [7]. Two basic approaches in this regard can be identified: (i) analytical approach based on probabilistic seismic demand and capacity model; (ii) simulation-based approach based on non-linear PBEE using random field theory. A conceptually straightforward, but computationally demanding, methodology is based on Monte Carlo Simulation (MCS) technique. The validity and robustness of MCS-based approach is well known [8]. However, large numbers of nonlinear dynamic analyses coupled with different frame typologies make simulation-based approach more impractical. Thus,

the analytical seismic risk assessment, i.e. a balanced approach of accuracy and computational requirements, is more popular. The basic concept of analytical approach can be found in studies of Collins et al. [9] and subsequent ones [10,11]. The present work provides a comprehensive study on the analytical seismic risk assessment of concrete building frame located in the Guwahati city.

3. Analytical seismic risk analysis

The seismic risk of a structure at a site is given as the failure limit state probability, $P_{LS} = P[D \geq C]$, i.e. the exceedance of structural demand value (D) to its capacity (C). To determine P_{LS} analytically, the problem of evaluating the limit state probability is decomposed into parts using the total probability theorem and introducing ground motion intensity measure as an interface variable [11]. Here, the choice of ground motion intensity measure is crucial. Seismic demands are known to be strongly correlated with the elastic spectral acceleration (S_a) at the fundamental period of the structure, and the minimum numbers of records required to estimate the fragility parameters are also reduced when S_a is used as the intensity measure instead of Peak Ground Acceleration (PGA) [12]. Therefore, S_a is adopted as the intensity measure serving as interface variable. The decomposition is then obtained as follows:

$$P_{LS} = P[D \geq C] = \sum_x P[D \geq C | S_a = x] \cdot P[S_a = x] \\ = \int_x F_R(x) \cdot |d\lambda_{S_a}(x)|. \quad (4)$$

In the above integral, the first term denotes the fragility and the second term corresponds to the

hazard. Thus, calculating probability of the limit state requires solution of these two terms. The first one (i.e., the fragility) represents the probability of demand exceeding capacity for a target hazard (S_a herein). The target hazard level can be estimated from PSHA of the location under consideration. The demand parameters are obtained by NLTHA of the structure, while the capacity parameters are obtained from capacity analysis. The resulting fragility function is usually modeled by a lognormal Cumulative Distribution Function (CDF):

$$F_R(x) = \Phi \left[\frac{\ln(x/m_R)}{\beta_R} \right], \quad (5)$$

where $\Phi[\cdot]$ is the standard normal probability integral, m_R is the median fragility, and β_R is the logarithmic Standard Deviation (SD) or dispersion of the fragility. The second term in Eq. (4) is the spectral acceleration hazard (i.e., the probability that the hazard level will exceed a particular value) determined from PSHA. The seismic risk of the structure can be then readily obtained by multiplying the fragility function by hazard function and calculating the integral in Eq. (4). The computational procedure is depicted in Figure 1 and explained in the next subsections.

3.1. Estimation of spectral acceleration hazard

The spectral acceleration hazard is estimated from PSHA of the study region. The methodology proposed by Das et al. [13] is adopted here for PSHA. Seismicity within 300 km radius from the site is considered. In general, PSHA provides the probability of exceedance of a strong ground motion parameter at a site due to all the earthquakes expected to occur during a specified exposure period. Here, we have considered Pseudo-Spectral Velocity, PSV(T), as a function of time period, T , as the ground motion parameter. The annual

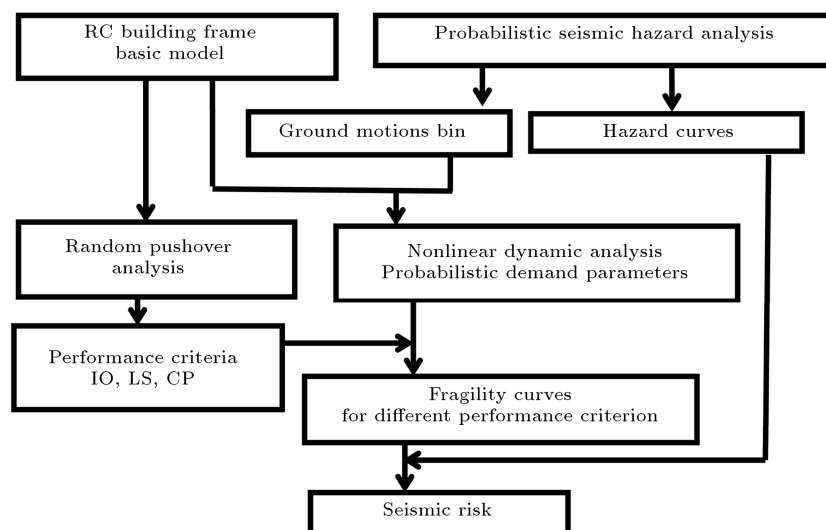


Figure 1. Overview of analytical seismic risk assessment.

average occurrence rate of earthquakes, $\lambda(z)$, is then obtained as follows:

$$\lambda(z) = \sum_{i=1}^I \sum_{j=1}^J q(z|M_j R_i) n(M_j R_i), \quad (6)$$

where $q(z|M_j R_i)$ denotes the probability that a given PSV(T) of amplitude 'z' at a site will exceed during an event of magnitude M_j occurring at a distance R_i . Computation of $q(z|M_j R_i)$ requires an attenuation model. There are several studies on attenuation model for this part of India and an excellent review for peak ground motion predictions for rock sites in India is worth mentioning [14] in this regard. For the present study, the attenuation model proposed by Das et al. [13] is adopted.

Quantity $n(M_j R_i)$ in Eq. (6) is the annual rate of occurrence of (M_j, R_i) event. As the magnitude and distance are both continuous variables, they are discretized into small intervals for practical applications. In the present study, the magnitudes ranging from 4.0 to 8.5 are discretized into nine intervals with $\Delta M = 0.5$. The epicentral distance within 300 km from the site is divided into 50 annular segments equally spaced in logarithmic scale. M_j and R_i denote the central values of each magnitude and distance range, respectively. We have estimated PSV(T) amplitudes for a particular combination of M_j and R_i as $\log[\text{PSV}'(T)] + \varepsilon(T)$, where $\varepsilon(T)$ is the error residual term obtained from the attenuation model. Assuming that the error residuals are normally distributed, the probability that the estimated value $\text{PSV}'(T)$ will be greater than specific value 'z' is obtained from the CDF of the error residuals:

$$p(\varepsilon(T)) = \frac{1}{\sigma(T)\sqrt{2\pi}} \int_{-\infty}^{\varepsilon(T)} e^{-\frac{1}{2}\left(\frac{z-\mu(T)}{\sigma(T)}\right)^2} dx. \quad (7)$$

Thus, the term $q(z|M_j R_i)$ is calculated as $1 - p(\varepsilon(T))$. Assuming that $\lambda(z)$ is the average occurrence rate of a Poisson process, the probability of exceeding z during

an exposure period of Y years is obtained from the following equation:

$$P[\text{PSV}(T) > z] = 1 - \exp\{-\lambda(z).Y\}. \quad (8)$$

In the present study, an exposure period of 50 years is considered to calculate the cumulative probability in Eq. (8). Based on the above outlined procedure, the PSV hazard curve is obtained. Now, to obtain the corresponding PSA hazard curve, we have multiplied the PSV ordinate by $2\pi/T$. The earthquake catalogue used to obtain $n(M_j R_i)$ values contains information on 3071 past earthquake events covering periods from 1458 to 2000 within the geographical area between 18° to 33° latitude, 85° to 100° longitude. The annual occurrence rate of earthquakes, $n(M_j R_i)$, is obtained by spatially distributing the seismicity calculated from Gutenberg-Richter relationship. The detail of the procedure followed here is well explained in Das et al. [13].

Figure 2(a) shows the PSA hazard curve (in terms of 'g'), thus obtained for horizontal motions, for $T = 1.0$ sec, and $Y = 50$ years. Following the same procedure, hazard curves of different time periods are obtained. Uniform Hazard Spectrum (UHS) is then readily obtained by plotting the spectral acceleration values corresponding to a particular probability of exceedance (10% herein) of the hazard curves for different time periods. Figure 2(b) shows the UHS obtained for Guwahati city for 10% probability of exceedance in 50 years. For analytical solution of fragility function, it is advantageous to approximate the hazard curve in the region of interest by a power law relationship [10]:

$$\lambda_{IM}(x) = P[IM \geq x] = 1 - \exp[-(x/u)^{-k}] \approx (x/u)^{-k} \approx k_0 x^{-k}, \quad (9)$$

where u is the scale parameter, k is the shape parameter, and constant $k_0 = u^k$. The slope and intercept of the tangent of the hazard curve (Figure 2(a)) at point corresponding to $p = 0.1$, $Y = 50$ years provide the values of parameters k_0 and k . Thus, the power-law

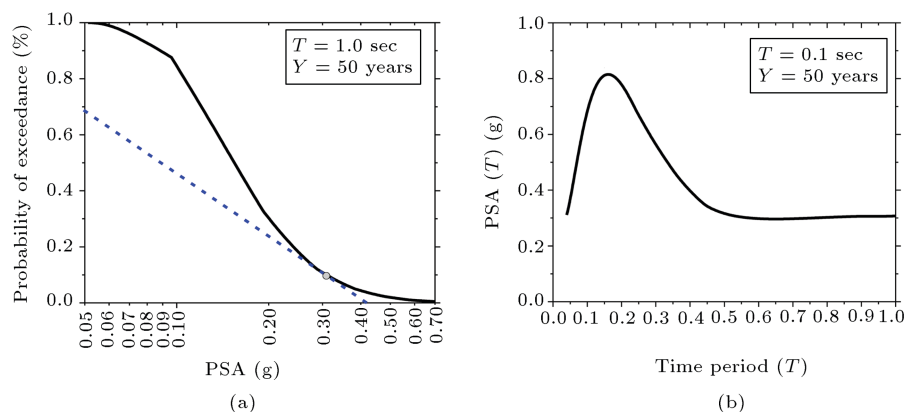


Figure 2. (a) Hazard curve for $T = 1.0$ sec and exposure period of 50 years. (b) Uniform hazard spectra for 10% probability of exceedance in 50 years for Guwahati City.

model of PSA hazard for Guwahati city is obtained as: $\lambda_{IM}(x) = 0.0004x^{-2.72}$ for $T = 1.0$ sec, $p = 0.1$, and $Y = 50$ years.

3.2. Fragility function for a given ground motion intensity

The fragility function can be developed by considering randomness in demand and capacity parameters. The conditional probability of seismic demand reaching or exceeding random structural capacity given a specific value of seismic intensity can be written as follows:

$$F_R(x) = P[D \geq C | S_a = x]. \quad (10)$$

For a given level of S_a , there will be variability in displacement-based demand due to randomness in the seismic excitation. A functional relationship between spectral acceleration and demand variable, specifically the median, m_D , of the demand, can be obtained. In general, the conditional median of D for $S_a = x$ can be expressed as follows [11]:

$$x_{D|S_a}(x) = g(x). \quad (11)$$

Assuming that the demand parameters are lognormally distributed, the above-conditional probabilistic model can be represented as follows:

$$D = m_{D|S_a}(x) \cdot \varepsilon, \quad (12)$$

where ε is a lognormal random variable with a median equal to unity and conditional logarithmic standard deviation, $\sigma_{\ln \varepsilon} = \beta_{D|S_a}$. A power-law relationship, which conforms to both of our perception of structural performance and also helps reduce the analytical effort [11], can be constructed between the median demand and spectral acceleration as follows:

$$m_{D|S_a}(x) = a \cdot x^b, \quad (13)$$

where ‘ a ’ and ‘ b ’ are the regression parameters to be obtained by probabilistic seismic demand analysis methods, e.g. cloud analysis, strip method, or incremental dynamic analysis method [11]. The cloud analysis is used in the present study, further of which is detailed in Section 5.

Assuming that structural capacity is also lognormal with uncorrelated D and C , following the fundamentals of the first-order reliability analysis method, the damage fragility can be obtained as follows:

$$\begin{aligned} F_R(x) &= \Phi \left[-\frac{\ln m_C - \ln m_{D|S_a}}{\sqrt{\beta_C^2 + \beta_{D|S_a}^2}} \right] \\ &= \Phi \left[\frac{\ln m_{D|S_a} - \ln m_C}{\sqrt{\beta_{D|S_a}^2 + \beta_C^2}} \right]. \end{aligned} \quad (14)$$

Here, $F_R(x)$ is the fragility that the demand will reach

or exceed the capacity for a specified value of $S_a = x$, m_C is the median capacity, and β_C is its lognormal SD. Substituting Eq. (13) in the above equation yields:

$$\begin{aligned} F_R(x) &= \Phi \left[\frac{\ln(ax^b) - \ln m_C}{\sqrt{\beta_{D|S_a}^2 + \beta_C^2}} \right] \\ &= \Phi \left[\frac{\ln x - \ln(m_C/a)^{1/b}}{\frac{1}{b} \sqrt{\beta_{D|S_a}^2 + \beta_C^2}} \right] \\ &= \Phi \left[\frac{\ln(x/m_R)}{\beta_R} \right]. \end{aligned} \quad (15)$$

Eq. (15) represents the probability of failure for a given value of S_a termed as damage fragility, where m_R and β_R are the median and dispersion of the damage fragility defined as follows:

$$\begin{aligned} m_R &= (m_C/a)^{1/b}, \\ \beta_R &= \frac{1}{b} \sqrt{\beta_{D|S_a}^2 + \beta_C^2}, \end{aligned} \quad (16)$$

where:

$$\beta_C = \sqrt{\beta_{C_R}^2 + \beta_{C_U}^2}.$$

It is to be noted that β_C contains two components of uncertainty. Aleatory component, β_{C_R} , is the result of structural uncertainty propagation obtained through capacity analysis of the considered structure for different performance levels. On the other hand, β_{C_U} arises due to uncertainty with regard to assumption of structural modelling. Due to non-availability of specific information on epistemic uncertainty, we have assumed a value of 0.2 for the present study [15].

3.3. Seismic risk evaluation

Once the conditional failure probability of seismic demand reaching or exceeding random structural capacity for a given value of S_a , i.e., $F_R(X)$, is obtained from Eq. (14), the seismic risk can be readily obtained. By substituting Eqs. (9) and (15) into Eq. (4) and carrying out the integration, failure limit state probability P_{LS} can be obtained as:

$$\begin{aligned} P_{LS} &= P[D \geq C] = \sum_x P[D \geq C | S_a = x] \cdot P[S_a \geq x] \\ &= \int_x F_R(x) \cdot |d\lambda_{S_a}(x)| = \lambda_{IM}(m_R) \exp \left(\frac{1}{2} k^2 \beta_R^2 \right) \\ &= \lambda_{IM}(m_R) \exp \left[\frac{1}{2} \frac{k^2}{b^2} (\beta_{D|S_a}^2 + \beta_C^2) \right]. \end{aligned} \quad (17)$$

These formulae for obtaining annual limit state probability can be directly used by substituting the values of m_R and β_R from Eq. (16) into Eq. (17) and the hazard curve given by Eq. (9).

4. Generation of ground motion database

In the framework of PBEE, ground motion record is the most important input for proper evaluation of structural demand parameters through NLTHA. The current practice selects a suite of ground motion records whose intensities are exceeded with some specified probability at a given site and whose other properties typically determined by PSHA. Three options available for this are: recorded accelerograms from strong motion database; artificial accelerograms that match the target response spectra; and simulated accelerograms from theoretical modelling of fault rupture. The most acceptable form of SFA of structures employs recorded accelerograms. However, recorded accelerograms specific to the hazard level in the study region are limited. To augment the ground motion database, artificial and synthetic accelerograms are further generated identifying the most vulnerable combination of M_j and R_i for the specific hazard level to ensure the variability in the input ground motions. These are discussed in the following subsections.

4.1. Natural accelerogram records

The natural accelerograms recorded for rock site during past earthquakes in the region are selected. The selected records cover a magnitude range (M_w) from 6.0 to 8.0 and epicentral distance within 300 km corresponding to the considered hazard level as identified from disaggregation of PSHA. For disaggregation study, a target hazard level is identified and contribution of each source is calculated by obtaining the probability of exceedance of the target hazard level for each of the sources [16] as follows:

$$P(M = M_j, R = R_i | \text{PSV}(T) \geq z) = \frac{\lambda(\text{PSV}(T) > z, M = M_j, R = R_i)}{\lambda(\text{PSV}(T) > z)}, \quad (18)$$

where $P(M = M_j, R = R_i | \text{PSV}(T) \geq z)$ is the probability that an earthquake of magnitude M_j occurring at distance R_i exceeds the target hazard level. The target hazard level is identified from UHS as 0.3 g (S_a

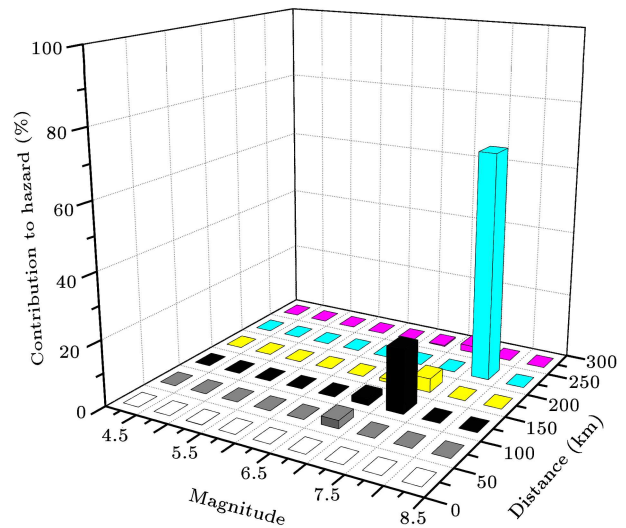


Figure 3. Results of disaggregation study for Guwahati City for S_a at $T = 1.0$ sec, $P = 0.1$, and $Y = 50$ years.

at the fundamental period of the considered frame). Eventually, the annual occurrence rate as defined by the numerator of the right-hand side of Eq. (18) refers to the values of the probability term, $q(z|M_j R_i)$, in Eq. (6), and the denominator is the sum of all these probabilities. These values are already obtained in PSHA for all the considered magnitude and epicentral ranges. Figure 3 shows the results of disaggregation study for Guwahati city.

Due to limited recorded accelerograms in the region, accelerograms from northern Himalayan earthquakes are also included. We have excluded the earthquakes with epicentral distance within 10 km to avoid possible directivity pulse effect. Table 1 lists the details of the selected accelerograms available at COSMOS virtual data centre (<http://strongmotion-center.org/vdc/scripts/default.t.plx>).

4.2. Spectrum compatible accelerograms

Artificial accelerograms are generated by matching the acceleration response spectra for rock hard soil site with 5% damping factor as recommended by Bureau of Indian Standard [3]. Following Gasparini and Vanmarcke [17], stationary stochastic process is

Table 1. Selected accelerograms records.

Name	Event date	Station	Comp.	Mag. (Ms)	Dist. (km)	Depth (km)	Site geology	PGA (g)
Indo-burma Border	6 Aug., 1988	Baigao	S28W	7.2	230	90	Soft rock	0.217
Indo-burma Border	6 Aug., 1988	Berlongfer	N14W	7.2	201	90	Soft rock	0.337
Indo-burma Border	8 May, 1997	Jellalpur	N02E	6.0	24	34	Soft rock	0.136
Indo-burma Border	8 May, 1997	Katakhal	S01W	6.0	40	34	Soft rock	0.159
Uttarkashi, India	19 Oct., 1991	Bhatwari	N85E	7.0	53	10	Rock	0.248
Uttarkashi, India	19 Oct., 1991	Uttarkashi	N75E	7.0	31	10	Rock	0.304
Chamoli, India	28 Mar., 1999	Gopewar	N20E	6.6	14	15	Rock	0.353
Chamoli, India	28 Mar., 1999	Ukhimath	N75W	6.6	29	15	Rock	0.091

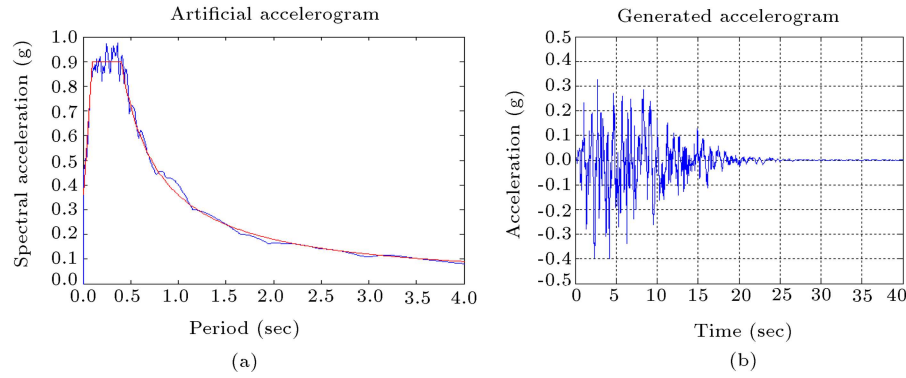


Figure 4. (a) Spectrally-matched ordinates of generated accelerogram. (b) Typical generated accelerogram by spectral matching.

obtained with the same general aspect but with different characteristics though by defining a vector of amplitudes and simulating different arrays of phase angles. These amplitudes are calculated using the Power Spectral Density (PSD) and the random phase angles are generated in the interval of 0 to 2π . The PSD function as proposed by Kaul [18] is adopted in this study. Further, to produce the transient nature of the earthquakes, the steady-state motions are multiplied by a deterministic envelope function [19]. This method of generating artificial accelerograms is iterative. For each cycle, the response spectrum generated for the simulated ground motion is compared with the target one (at a set of control frequencies). The ratio between the desired response and the computed response spectra is obtained at each cycle, and the corresponding PSD is recalculated as a function of the square of the aforementioned ratio. Using the modified PSD, another new accelerogram is simulated and a new response spectrum is obtained. The procedure is repeated with a new set of phase angles until the desired and computed response spectra converge. One such typical spectrally-matched ordinate and the corresponding accelerogram are shown in Figure 4.

4.3. Generation of synthetic accelerograms

The stochastic method as proposed by Boore [20] that combines parametric descriptions of amplitude spectrum with a random phase as a function of magnitude and distance from the source is considered in the present study for generation of synthetic accelerograms. This method is widely used to predict ground motions for regions where recordings of motion from potentially damaging earthquakes are scarce [21]. The Fourier amplitude spectrum of ground motion at a site is expressed as follows:

$$\text{Ground motion } (f) = C \times \text{Source } (f) \times \text{Path } (f) \times \text{Site } (f), \quad (19)$$

where $C = R_{\theta\varphi}FH/4\pi\sigma\beta^3$ is the scaling factor in which $R_{\theta\varphi}$ represents the radiation pattern for a range

of azimuths θ and take-off angles φ ; F represents the free surface effect; and H is the reduction factor that accounts for the partitioning of energy into two horizontal components. The crustal density and shear wave velocity are represented by α and β , respectively. By using ω -square model [22], the source spectrum is obtained as:

$$\text{Source } (f) = (2\pi f)^2 \frac{M_0}{[1 + (f/f_c)^2]}, \quad (20)$$

where M_0 is seismic moment and corner frequency, f_c is obtained from $f_c = 4.9 \times 10^6 \beta (\Delta\sigma/M_0)^{1/3}$ in which f_c is in Hertz, β is in km/s, the stress drop, $\Delta\sigma$, is in bars, and M_0 is in dyne-cm. The path term is defined in terms of the geometrical spreading (GSP) factor and the frequency-dependent quality factor $Q(f)$ and is given as follows:

$$\text{Path } (f) = \text{GSP}(r) \cdot e^{-\pi f r / Q(f) \beta}. \quad (21)$$

The site term is defined in terms of frequency-dependent amplification and diminution factor as:

$$\text{Site } (f) = A(f) \times D(f), \quad (22)$$

where $A(f)$ represents the site amplification. The diminution factor $D(f)$ is given by $D(f) = e^{(-\pi k_0 f)}$, where k_0 is the distance-independent high frequency attenuation operator (Kappa factor). Three widely used techniques for estimation of site amplification are: Standard Spectral Ratio (SSR), generalised inversion (GINV), and Horizontal to Vertical Spectral Ratio (HVSr) [23]. The use of SSR method requires a reference rock site station; for GINV method, sites with known site responses are required [23]. As the stochastic model requires knowledge of many parameters related to source, site, and path characteristic, a detailed exploration of all the alternatives to achieve those will be extensive. With the readily available information, we found HVSr method as a practical alternative for site-response estimation. Thus, amplification function, $A(f)$, is estimated from HVSr.

Table 2. The parameters adopted for synthetic ground motion generation.

Parameters	Values	References
Stress Drop ($\Delta\sigma$)	250 bars	Raghukanth and Somala [21]
Quality Factor (Q_f)	$224f^{0.93}$	Raghukanth and Somala [21]
Geometrical spreading factor (GSP)	$1/r$ for $r < 100$ km, $1/10\sqrt{r}$ for $r > 100$ km	Singh et al. [24]
Distance-dependent factor (b)	0.05	Boore [20]
Shear wave velocity (β)	3.6 km/sec	Mitra et al. [25]
Crustal density (σ)	2900 kg/m ³	Mitra et al. [25]
kappa factor (k_0)	$(0.057/V_{s,30}^{0.8}) - 0.02$	Chandler et al. [26]
V_{s30}	1.97 km/s	Chandler et al. [26]
Reduction Factor (H)	$1/\sqrt{2}$	Boore [20]
Radiation pattern ($R_{\theta\phi}$)	0.55	Boore [20]
Free surface amplification (F)	2.0	Boore [20]

However, the site response should be studied further to explore the available alternatives.

The disaggregation study reveals that earthquakes between magnitudes (M_w) 6.0 to 8.0 have major contribution to the estimated hazard level. Strong motion data for Guwahati is very limited and most of which are not complying with the magnitude-distance range estimated from the PSHA disaggregation. Thus, Loharghat station is selected as the representative station which is closest to the Guwahati. In this regard, it may be noted that one earthquake record satisfying the above criteria is available for Guwahati, i.e., Bhutan earthquake (2009) having $M_w = 6.2$ and epicentral distance of 126 km. There are also recording stations operated by IIT, Guwahati which are not publicly available. Those may be considered for realistic HVSr analysis. However, this needs further study. In COSMOS virtual database, only one earthquake record is available for Loharghat station, which corresponds to the Indo-Burma Border earthquake (August, 1988). The three orthogonal components of the ground motion of this record are used to calculate HVSr. Fourier spectra of these three components are calculated and smoothed. Smoothed Fourier spectrums of two horizontal motions are then averaged using a quadratic mean. The average spectrum is divided by the smoothed vertical spectrum to get the HVSr. The HVSr when multiplied by the near-surface attenuation term, $e^{(-\pi k_0 f)}$, gives the overall site amplification [21].

With the knowledge of the HVSr and the Fourier amplitude for stochastic point source model, synthetic accelerogram generation is straight forward. So, white Gaussian noise is generated with zero mean and unit SD and filtered to retain the frequencies between 0 to 50 Hz. The filtered Gaussian noise is then windowed

by the envelope function [19]. This windowed noise is Fourier transformed and normalized with its root mean square value. The normalized ordinates of the Fourier amplitudes are then multiplied by the Fourier amplitude of the ground motion model. The inverse Fourier transform of this Fourier spectrum gives the accelerogram in time domain. Following this procedure, eight accelerograms are generated for different magnitudes between M_w 6.0 to 8.0 and epicentral range within 300 km. Table 2 summarizes various parameters used for the ground motion simulations and the specific values adopted in the present study along with useful references. Figure 5(a) compares the actual and typical simulated acceleration spectra at Loharghat Station. Figure 5(b) depicts the synthetic accelerogram generated for $M_w = 6.0$, $R = 150$ km, and focal depth = 15 km.

5. Case Study: A seven-storey RC frame

5.1. Description of the representative frame

A seven-storey RC framed building considered to be located in Guwahati city of NE India and designed according to Indian codes is considered for numerical elucidation of the analytical seismic risk assessment. The building consists of three bays of 4.0 m width in the longitudinal direction and 5 m width in the transverse direction. A transverse 2-D frame is extracted from the building for the analysis (Figure 6(a)). The dead load consists of self-weight of structural and nonstructural members. The live load is assumed to be 1.5 kN/m² for roof (accessible) and 3.0 kN/m² for floors. The building frame is first analyzed by response spectrum method, following specifications given by BIS [3] with the following input parameters: Zone (V), importance

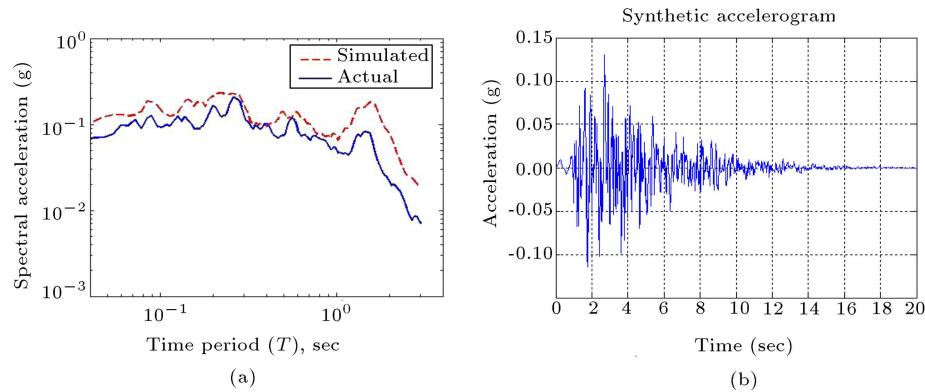


Figure 5. (a) Acceleration spectra for actual and simulated accelerograms of Loharghat station. (b) Generated accelerogram from the modified Fourier spectrum.

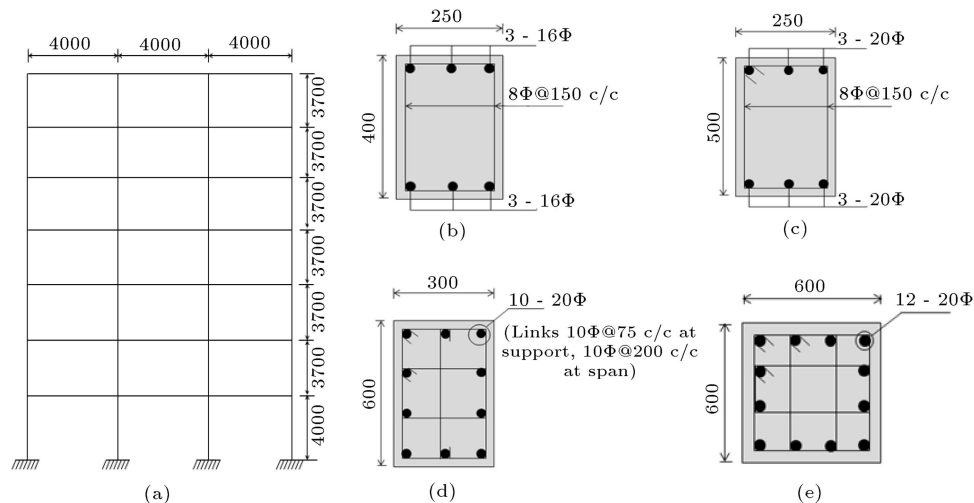


Figure 6. (a) The elevation of considered building frame. (b) Section of roof beams. (c) Section of floor beams. (d) Section of outer columns, (e) Section of inner columns.

factor (I) of 1.0, response reduction factor (R) of 5.0 (SMRF), and soil type (hard soil site, and spectral acceleration (S_a) for 5% damped spectra). The concrete grade is considered as M_{25} (i.e., compressive strength of concrete is 25 N/mm^2). The reinforcing steel grade is taken as HYSD500 (i.e., yield strength of steel is 500 N/mm^2). From the modal analysis, the time period of the structure at the fundamental mode is found to be 1.07 sec. All the peak response quantities for various modes are combined as per the Complete Quadratic Combination (CQC) rule [3]. The reinforcement and geometric dimension details of the beam and column sections are shown in Figure 6(b) to (e).

5.2. Nonlinear time history analysis

The nonlinear responses of the structure are calculated by NLTHA using SAP2000 software considering the accelerograms as described in Section 4. The stress-strain characteristics of concrete beams and columns are considered as per Mander's model [27]. For reinforcing steel, simple stress-strain model with isotropic

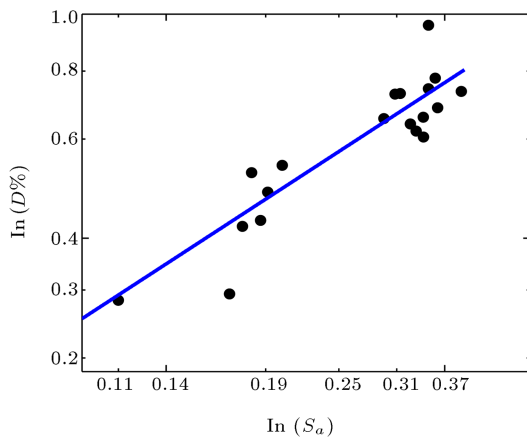
strain-hardening behaviour is adopted. These stress strain models of concrete and steel are available in the SAP2000 software. The beams and columns are modelled with lumped plasticity model. For this purpose, the nonlinear hinges are assigned at the beam and column ends. The beams are modelled with moment hinges (M3), whereas the columns are modelled with axial-moment (P-M3) interacting hinges. Auto hinges are assigned according to the tables of FEMA 356 [28]. The NLTHA is carried out by Hilbert-Huges-Taylor (HHT) integration scheme [29]. From the NLTHA, the maximum Inter Storey Drift (ISD) values are obtained for the ground motion records, representing the structural demands D .

5.3. Cloud analysis for estimation of demand parameters

The power-law relationship between the median maximum ISD and spectral acceleration values (Eq. (13)) involves two regression parameters ' a ' and ' b ', which are obtained from the cloud analysis. The set of

Table 3. Properties of the random structural parameters.

Uncertainty sources	Random variable	Mean	COV	Distribution type
Dead load	Unit weight	25 kN/m ³	0.07	Normal
Live load	Intensity of load, q_{live}	3 kN/m ²	0.41	Gamma
Grade M25 concrete	Characteristic compressive strength, f_{ck}	25 N/mm ²	0.21	Lognormal
Grade Fe 500 steel	Characteristic yield, strength f_y	500 N/mm ²	0.07	Lognormal

**Figure 7.** Cloud analysis through demand values.

ISD values obtained from the NLTHA for each of the ground motion records of the bin forms the basis of cloud analysis. In order to estimate the statistical properties of the “cloud” response, conventional linear regression is applied to the cloud of response values in the natural logarithmic scale. This results in a relation that predicts the median drift demand for a given level of spectral acceleration:

$$\ln m_D = \ln a + b \cdot \ln(S_a). \quad (23)$$

The logarithmic SD of the regression measuring the second moment of the data points around the predicted curve gives the estimate of dispersion measure $\beta_{D|S_a}$ [11]:

$$\beta_{D|S_a} = \sqrt{\frac{\sum (\ln d_i - \ln(a \cdot S_a^b))^2}{n - 2}}. \quad (24)$$

From the NLTHA of the frame with twenty-four accelerograms, the cloud analysis is performed as shown in Figure 7. The power-law relationship between the median demand and spectral acceleration is then given by:

$$m_D(S_a) = 1.713 \cdot S_a^{0.828}, \quad \beta_{D|S_a} = 0.263.$$

5.4. Probabilistic seismic capacity analysis

The Random Pushover Analysis (RPA) is used to obtain the probabilistic seismic capacity of the considered frame. For the present study, four structural

parameters are considered to be random as listed in Table 3.

With the assumed distribution types of the structural parameters, 100 random samples are generated using Latin Hypercube Sampling (LHS) with reduced correlation. To reduce the correlation among the various parameters, the correlation reduction technique in transformed variable space [30] is adopted. Using the 100 generated sets of random parameters, the pushover analysis is performed. The maximum ISD values are calculated corresponding to each limit state considering the square root of the sum of the squares distribution method for lateral load distribution pattern. Rather than conventional roof displacement versus base shear curve, the pushover curve plots maximum ISD values versus base shear since the pushover analysis is applied to obtain the median capacity values (m_C) and associated SD (β_{CR}).

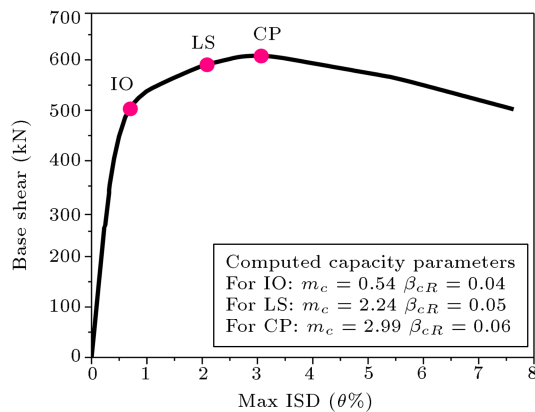
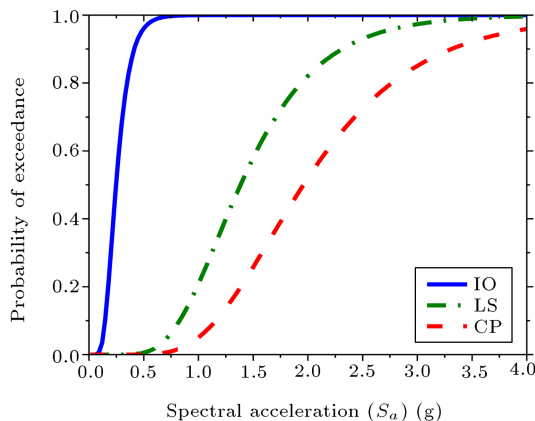
As per FEMA 356 [28], the three structural limit states or performance levels, namely the Immediate Occupancy (IO), Life Safety (LS), and Collapse Prevention (CP), are considered in the present study. The IO level corresponds to the post-earthquake damage state with the occurrence of very limited structural damage. It is identified as the point in the pushover curves where the first yield deformation occurs. The LS performance level is defined as the post-earthquake damage state in which significant damage to the structure has occurred, but some margin against either partial or total structural collapse remains. It is considered to be the deformation corresponding to 0.75 times the deformation at the CP level [28]. The CP performance state means the post-earthquake damage state in which the building is on the verge of partial or total collapse. The CP limit state is identified from the pushover curve as the deformation (θ_c) corresponding to the peak shear resistance of the structure [28]. Figure 8 shows the median pushover curve, thus obtained with the median capacity values (m_C) and the associated SD (β_{CR}) obtained for each limit state.

5.5. Fragility curves and seismic risk evaluation

The various parameters required for fragility curve and seismic risk evaluation are summarized in Table 4. With these parameters, the fragility curves corresponding to all the three limit states (i.e., IO, LS, and CP) are

Table 4. The various parameters for obtaining fragility curves.

Limit states	IM	PSHA		CA			RPA		Damage fragility	
		k_0	k	a	b	$\beta_{D S_a}$	m_C	β_C	m_{RC}	β_{RC}
IO	S_a	0.004	-2.72	1.713	0.828	0.263	0.54	0.20	0.25	0.40
LS	S_a	0.004	-2.72	1.713	0.828	0.263	2.24	0.20	1.38	0.40
CP	S_a	0.004	-2.72	1.713	0.828	0.263	3.00	0.22	1.96	0.42

**Figure 8.** The median pushover curve and computed capacity parameters.**Figure 9.** The seismic fragility curves corresponding to different limit states.**Table 5.** The annual failure probability for different limit states.

Limit state	P_{LS}
IO	0.06170
LS	0.00057
CP	0.00023

obtained for the considered RC frame and are shown in Figure 9.

Using the fragility and hazard curves, the annual failure probabilities corresponding to the spectral acceleration hazard level of 10% probability of exceedance in 50 years for different limit states are calculated. Table 5 lists the estimated annual failure probabilities.

6. Summary and conclusions

The analytical SFA of RC framed building located in Guwahati city, NE India is presented in the framework of PBEE for different limit states, namely IO, LS, and CP. The following observations are made:

1. From the NLTHA of the RC frame, the computed maximum inter-storey drift demands obtained for the spectrally-matched accelerograms are relatively higher than those obtained from the natural or synthetically generated accelerograms;
2. The synthetic accelerograms are able to capture the inherent randomness of the recorded accelerograms to a great extent and yield more realistic drift response of the structure than the spectrally-matched one when compared to the responses obtained for natural recorded accelerograms;
3. The estimated fragility curves show that the structure is associated with high probability of failure (almost 60%) for IO limit state corresponding to the spectral acceleration hazard level at the fundamental periods of the structure. However, for LS and CP limit states, the performance of the structure is rather satisfactory. At this hazard level, the structure shows relatively high risk of annual failure (about 6%) for IO limit state, whereas the annual failure probability is much less for LS and CP limit states.

Based on those observations, it may be opined that a medium-rise RC framed building located in the study area with moderate fundamental period, when designed according to the guidelines of IS codes, is most likely to perform beyond its elastic range (i.e., beyond IO level) when subjected to the prevalent hazard level identified in this study. However, the reinforcement provided as per ductility-based detailing is sufficient enough to prevent life-threatening risk and/or complete collapse of the structure. The analytical seismic risk assessment procedure presented here is generic in nature and can be readily applied to other building typologies located in the region.

Acknowledgement

The financial support received in TSD Scheme No.

DST/TSG/STS/2012/45, 21.1.13 from the DST, Govt. of India (for the project entitled “Seismic vulnerability assessment of existing buildings to supplement rehabilitation practices with special emphasis to North Eastern Region”) in connection with this work is gratefully acknowledged.

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