# Analytical approaches to the (2+1)-dimensional Heisenberg Ferromagnetic Spin Chain equation and their applications for optical devices 

Khalid K. Ali ${ }^{1, *}$, Abdel-Haleem Abdel-Aty ${ }^{2,3}$, M.S.Mehanna ${ }^{4}$<br>${ }^{1}$ Mathematics Department, Faculty of Science, Al-Azhar University, Nasr-City, Cairo, Egypt<br>${ }^{2}$ Department of Physics, College of Sciences, University of Bisha, PO Box 344, Bisha 61922, Saudi Arabia<br>${ }^{3}$ Physics Department, Faculty of Science, Al-Azhar University, Assiut 71524, Egypt<br>${ }^{4}$ Faculty of Engineering, MTI University, Cairo, Egypt Emails : ${ }^{1}$ khalidkaram2012@azhar.edu.eg,<br>${ }^{2}$ amabdelaty@ub.edu.sa, ${ }^{3}$ monamehanna@gmail.com<br>${ }^{*}$ Corresponding author. Te. +201033530861


#### Abstract

The Heisenberg ferromagnetic spin chain (HFSC) equation has substantial relevance in the fields of optics and electronics, particularly in the advancement of high-density electronic components and faster storage devices. This integrable nonlinear Schrödinger equation characterizes the propagation of nonlinear waves in ferromagnetic spin chain systems. In a recent research paper, two powerful analytical methods, the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{R} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method and the extended hyperbolic function method (EHFM), were implemented to solve the ( $2+1$ )-dimensional HFSC equation. Most of the results obtained from the study are presented graphically, which can aid in the visualization and interpretation of the gained results. These findings will be useful in the development and optimization of spintronic devices and other electronic components that rely on the behavior of spin systems. The analytical solutions of the HFSC equation yield important insights that enhance our understanding and facilitate the application of magnetism, thermal properties, and topological phenomena across diverse fields such as materials science, condensed matter physics, and quantum technologies. These findings play a crucial role in advancing our knowledge and practical utilization of these phenomena in real-world applications.


Keywords: Heisenberg equation; Solitons; $\left(\frac{\mathfrak{G}^{\prime}}{\sqrt[R \mathfrak{F}^{\prime}+\mathfrak{G}+\mathfrak{r}]{ }}\right)$ method; Extended hyperbolic function method.

## 1 Introduction

In the last decades, the Heisenberg ferromagnetic spin chain equation [1-3] has great applications in soliton theory and condensed matter physics. The study of this non-linear partial differential equation attracts researchers due to its wide applications in different fields, including mathematical physics $[4,5]$, fluid mechanics [6], the shock wave phenomena in plasma [7], nonlinear electrical transmission lattice occurring in science and engineering [8,9], optics and quantum information [10, 11], nonlinear optics [12, 13], condensed matter physics [14], geophysical fluid dynamics [15], coastal engineering, wave energy conversion, and fluid dynamics studies [16], plasma physics [17], optical fibers [18], hydrodynamics and solid-state physicss [19], electromagnetic signals [20], chaos theory [21], and others. Many researchers execute different techniques to get the soliton solutions of the non-linear partial differential equations. The present literature concern with the $(2+1)-$ dimensional Heisenberg ferromagnetic spin chain (HFSC) equation

$$
\begin{gather*}
i u_{t}+\alpha_{1} u_{x x}+\alpha_{2} u_{y y}+\alpha_{3} u_{x y}-\alpha_{4}|u|^{2} u=0,  \tag{1}\\
\alpha_{1}=\gamma^{4}\left(\Theta+\Theta_{2}\right), \alpha_{2}=\gamma^{4}\left(\Theta_{1}+\Theta_{2}\right), \alpha_{3}=2 \gamma^{4} \Theta_{2}, \alpha_{3}=2 \gamma^{4} B . \tag{2}
\end{gather*}
$$

where: $u=u(x, y, t), \gamma$ is the grid parameter, $\Theta$ and $\Theta_{2}$ are the coefficients of bilinear exchange interactions in the xy-plane, $\Theta_{2}$ is the neighboring interaction on the diagonal, $B$ is the uniaxial crystal field anisotropy parameter. The Heisenberg ferromagnetic spin chain equation has important applications in modern magnet theory. It provides a description for the non-linear characteristics of magnets. The field equivalent to the anisotropic and constant external field is formed, when the electromagnetic waves transfer in an isotropic ferromagnetic medium and also dissect the mathematical phenomenon [22,23]. Many authors gives a traveling wave solutions to the HFSC equation using miscellaneous techniques: Bashar et al. applied the improved F-expansion method and modified simple equation (MSE) [24], the $\exp (\varphi(\xi)$ )-expansion and the extended tanh-function methods are used by Bashar et al. [25], Osman et al. exerted the new extended FAN sub-equation method [26], Nisar et al. apply the extended $\left(G^{\prime} / G^{2}\right)$-expansion method [27], By applying projective Riccati equation and modified F-Expansion methods Aliyu et al. present their solutions [28], Yu-Lan Ma solved by using the bilinear method [29], Bulut et al. used extended sinh-Gordon equation method [30], the complete discrimination system method [31] applied by Han et al., Seadawy et al. applied generalized Riccati mapping and improved auxiliary equation methods [32], Abdul Al Woadud et al. used the modified Kudryashov method [33], Sahooa et al. studied by the modified Khater method [34], Islam et al. applied the unified method [35], Mohammed et al. applied the Jacobi elliptic function method [36], Zahran et al. applied the solitary wave ansatz and the PaulPainleve approach methods [37], Wang et al. employed the variational method and subequation method [38], Farah M. Al-Askar utilized the $\frac{G^{\prime}}{G}$-expansion method and the mapping method [39] and others.
The $(2+1)$-dimensional Heisenberg ferromagnetic spin chain equation has been applied to a wide variety of problems in optics, including the study of nonlinear optical fibers, the dynamics of liquid crystals, and the propagation of light in photonic crystals. The schedule of the paper is: Section 2 presents the algorithm of the suggested methods [40-46]. In Section 3, we exhibit the application of the methods. Most of the solutions are illustrated by graphs in section 4. The discussion of our results is introduced in Section 5. At the end, Section 6 offers a succinct conclusion.

## 2 The Strategies of the proposed Techniques

### 2.1 The $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathcal{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method [40]

We give the main steps of the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method. Consider the nonlinear partial differential equation

$$
\begin{equation*}
F\left(u, u_{t}, u_{x}, u_{y}, u_{x x}, u_{y y}, u_{x y}, \ldots\right)=0 \tag{3}
\end{equation*}
$$

where $u=u(x, y, t)$ represents the complex function to be calculated, while $F$ denotes a polynomial involving both $u$ and its associated partial derivatives.

Step 1: Insert the next wave transformation,

$$
\begin{equation*}
u(x, y, t)=e^{i \xi} v(\eta), \quad \xi=a_{1} x+b_{1} y-c_{1} t, \quad \eta=a_{2} x+b_{2} y-c_{2} t \tag{4}
\end{equation*}
$$

where $\xi$ is the envelope phase, $a_{2}$ is the wave number in the x -direction, $b_{2}$ is the wave numbers in the $y$-direction, $c_{2}$ represents the wave velocity, $c_{1}$ denotes the frequency of the pulse and $a_{1}, b_{1}$ are constants. Inserting Equation (4) into Equation (1), then Equation (1) transformed to an ordinary differential equation:

$$
\begin{equation*}
H\left(v^{\prime}, v^{\prime \prime}, v^{\prime \prime \prime}, \ldots\right)=0 \tag{5}
\end{equation*}
$$

where $H$ represents a polynomial involving $v(\eta)$ and its corresponding derivatives.

Step 2: Assume that the following represents the solution to Equation (5):

$$
\begin{equation*}
v(\eta)=\sum_{i=0}^{N} \mathfrak{m}_{i} \mathfrak{F}(\eta)^{i} \tag{6}
\end{equation*}
$$

where $\mathfrak{F}(\eta)=\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{k} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right), \mathfrak{G}(\eta)$ fulfill the next ODE,

$$
\begin{equation*}
\mathfrak{G}^{\prime \prime}(\eta)=-\frac{\lambda}{\mathfrak{K}} \mathfrak{G}^{\prime}(\eta)-\frac{\mu}{\mathfrak{K}^{2}} \mathfrak{G}(\eta)-\frac{\mu}{\mathfrak{K}^{2}} \mathfrak{r}, \tag{7}
\end{equation*}
$$

where: $\mathfrak{m}_{i}$ are unknown constants, $\mathfrak{K}, \mu, \lambda$, and $\mathfrak{r}$ are constants to be determined later. $\mathfrak{F}=\mathfrak{F}(\eta)$ is the solution of the ODE

$$
\begin{equation*}
\mathfrak{F}^{\prime}(\eta)=(\lambda-\mu-1) \mathfrak{F}(\eta)^{2}+\frac{(2 \mu-\lambda)}{\mathfrak{K}} \mathfrak{F}(\eta)-\frac{\mu}{\mathfrak{K}^{2}} \tag{8}
\end{equation*}
$$

Step 3: Finding the positive integer $N$ in Equation (5) requires balancing the highest power nonlinear term with the highest order derivative term.

Step 4: Two families of solutions to Equation (8) are presented:
Class 1: When $\Delta=\lambda^{2}-4 \mu>0$,

$$
\begin{equation*}
\mathfrak{G}=-\mathfrak{r}+p_{1} e^{\frac{1}{2, \mathfrak{R}}(-\lambda-\sqrt{\Delta}) \eta}+p_{2} e^{\frac{1}{2 \mathfrak{\kappa}}(-\lambda+\sqrt{\Delta}) \eta} \tag{9}
\end{equation*}
$$

$p_{1}$ and $p_{2}$ represent arbitrary constants, and they must satisfy the following relation: $\mathfrak{r}^{2}+p_{1}^{2}+p_{2}^{2} \neq 0$, then
$\mathfrak{F}(\eta)=\frac{p_{1}(\lambda+\sqrt{\Delta})+p_{2}(\lambda-\Delta) e^{\frac{\sqrt{\Delta} \eta}{\AA}}}{\mathfrak{K} p_{1}(\lambda-2+\sqrt{\Delta})+\mathfrak{K} p_{2}(\lambda-2-\Delta) e^{\frac{\sqrt{\Delta} \eta}{\Omega}}}$,
$\mathfrak{F}(\eta)=$
$\frac{\left[\lambda\left(p_{2}-p_{1}\right)-\sqrt{\Delta}\left(p_{2}+p_{1}\right)\right] \sinh \left(\frac{\sqrt{\Delta} \eta}{2 \mathfrak{\Re}}\right)+\left[\lambda\left(p_{2}+p_{1}\right)-\sqrt{\Delta}\left(p_{2}-p_{1}\right)\right] \cosh \left(\frac{\sqrt{\Delta} \eta}{2 \mathfrak{K}}\right)}{\mathfrak{K}\left[(\lambda-2)\left(p_{2}-p_{1}\right)-\sqrt{\Delta}\left(p_{2}+p_{1}\right)\right] \sinh \left(\frac{\sqrt{\Delta} \eta}{2 k}\right)+\mathfrak{K}\left[(\lambda-2)\left(p_{2}+p_{1}\right)-\sqrt{\Delta}\left(p_{2}-p_{1}\right)\right] \cosh \left(\frac{\sqrt{\Delta} \eta}{2 \mathfrak{K}}\right)}$

$$
\mathfrak{F}(\eta)= \begin{cases}\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}-\frac{\sqrt{\Delta}}{2 k(\lambda-\mu-1)} \tanh \left(\frac{\sqrt{\Delta} \eta}{2 \mathfrak{F}}\right), & (\lambda-2)\left(p_{2}-p_{1}\right)-\sqrt{\Delta}\left(p_{2}+p_{1}\right)=0  \tag{10}\\ \frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}-\frac{\sqrt{\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \operatorname{coth}\left(\frac{\sqrt{\Delta \eta}}{2 \mathfrak{R}}\right), & (\lambda-2)\left(p_{2}+p_{1}\right)-\sqrt{\Delta}\left(p_{2}-p_{1}\right)=0 .\end{cases}
$$

Class 2: When $\Delta=\lambda^{2}-4 \mu<0$,

$$
\begin{equation*}
\mathfrak{G}=-\mathfrak{r}+e^{\frac{-\lambda \eta}{2 \cdot /}}\left(p_{1} \cos \left(\frac{\sqrt{-\Delta} \eta}{2 k}\right)+p_{2} \sin \left(\frac{\sqrt{-\Delta \eta} \eta}{2 \mathfrak{K}}\right)\right), \tag{12}
\end{equation*}
$$

$$
\begin{gather*}
\mathfrak{F}(\eta)=\frac{\left(\lambda p_{1}-\sqrt{-\Delta} p_{2}\right) \cos \left(\frac{\sqrt{-\Delta} \eta}{2 \mathfrak{K}}\right)+\left(\lambda p_{2}+\sqrt{-\Delta} p_{1}\right) \sin \left(\frac{\sqrt{-\Delta} \eta}{2 \mathfrak{K}}\right)}{\mathfrak{K}\left((\lambda-2) p_{1}-\sqrt{-\Delta} p_{2}\right) \cos \left(\frac{\sqrt{-\Delta} \eta}{2 k}\right)+\mathfrak{K}\left((\lambda-2) p_{2}+\sqrt{-\Delta} p_{1}\right) \sin \left(\frac{\sqrt{-\Delta \eta} \eta}{2 \mathfrak{K}}\right)}  \tag{13}\\
\mathfrak{F}(\eta)= \begin{cases}\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}+\frac{\sqrt{-\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \tan \left(\frac{\sqrt{-\Delta} \eta}{2 \mathfrak{K}}\right), \quad(\lambda-2) p_{2}+\sqrt{-\Delta} p_{1}=0, \\
\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}-\frac{\sqrt{-\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \cot \left(\frac{\sqrt{-\Delta} \eta}{2 \mathfrak{K}}\right), \quad(\lambda-2) p_{1}-\sqrt{-\Delta} p_{2}=0 .\end{cases}  \tag{14}\\
\end{gather*}
$$

Step 4: After substituting Equation (6) and Equation (8) into Equation (5), the next step involves grouping all coefficients of $\mathfrak{F}(\eta)$ with identical powers and equating them to zero. Solving the resultant system of algebraic equations with the aid of Mathematica program to get the solution of Equation (1).

### 2.2 The extended hyperbolic function method (EHFM) [41-46]

Herein, we give the essential steps of the extended hyperbolic function method in the next:
Step 1: consider the solution to equation Equation (5) as follows:

$$
\begin{equation*}
v(\eta)=\sum_{j=0}^{N} f_{j}(G(\eta))^{j} \tag{15}
\end{equation*}
$$

where $G(\eta)$ satisfies two ODE, the next ODE is the first one:

$$
\begin{equation*}
G^{\prime}(\eta)=G(\eta) \sqrt{\mu G(\eta)^{2}+\beta} \tag{16}
\end{equation*}
$$

where $f_{N} \neq 0, f_{j}(j=0,1,2, \ldots, N), \beta, \mu \in R$, are constants to be determined later.
Step 2: From Equation (5), elaborating the homogeneous balance principle as previously discussed to obtain the value of $N$.

Step 3: substituting Equation (15) and Equation (16) in Equation (5), after aggregating all the coefficients of the $G(\eta)$ with the same power, putting them equal to zero, then solve the gained system of equations using the Mathematica program.

Step 4: The solutions of Equation (17) are eight families given in the next:
Family 1: When $\beta>0$ and $\mu>0$,

$$
\begin{equation*}
G(\eta)=-\sqrt{\frac{\beta}{\mu}} \operatorname{csch}\left(\sqrt{\beta}\left(\eta+\eta_{0}\right)\right) \tag{17}
\end{equation*}
$$

Family 2: When $\beta<0$ and $\mu>0$,

$$
\begin{equation*}
G(\eta)=\sqrt{-\frac{\beta}{\mu}} \sec \left(\sqrt{-\beta}\left(\eta+\eta_{0}\right)\right) \tag{18}
\end{equation*}
$$

Family 3: When $\beta>0$ and $\mu<0$,

$$
\begin{equation*}
G(\eta)=\sqrt{-\frac{\beta}{\mu}} \operatorname{sech}\left(\sqrt{\beta}\left(\eta+\eta_{0}\right)\right) \tag{19}
\end{equation*}
$$

Family 4: When $\beta<0$ and $\mu<0$,

$$
\begin{equation*}
G(\eta)=\sqrt{-\frac{\beta}{\mu}} \csc \left(\sqrt{-\beta}\left(\eta+\eta_{0}\right)\right) \tag{20}
\end{equation*}
$$

Family 5: When $\beta>0$ and $\mu=0$,

$$
\begin{equation*}
G(\eta)=\exp \left(\sqrt{\beta}\left(\eta+\eta_{0}\right)\right) \tag{21}
\end{equation*}
$$

Family 6: When $\beta<0$ and $\mu=0$,

$$
\begin{equation*}
G(\eta)=\cos \left(\sqrt{-\beta}\left(\eta+\eta_{0}\right)\right)+i \sin \left(\sqrt{-\beta}\left(\eta+\eta_{0}\right)\right) \tag{22}
\end{equation*}
$$

Family 7: When $\beta=0$ and $\mu>0$,

$$
\begin{equation*}
G(\eta)= \pm \frac{1}{\left(\sqrt{\mu}\left(\eta+\eta_{0}\right)\right)} \tag{23}
\end{equation*}
$$

Family 8: When $\beta=0$ and $\mu<0$,

$$
\begin{equation*}
G(\eta)= \pm \frac{i}{\left(\sqrt{-\mu}\left(\eta+\eta_{0}\right)\right)} \tag{24}
\end{equation*}
$$

Secondly, the $G(\eta)$ satisfies another ODE, given by:

$$
\begin{equation*}
G^{\prime}(\eta)=\mu G(\eta)^{2}+\beta \tag{25}
\end{equation*}
$$

then, there are six distinct solution families presented for Equation (25):
Family 1: When $\beta \mu>0$,

$$
\begin{equation*}
G(\eta)=\operatorname{sgn}(\beta) \sqrt{\frac{\beta}{\mu}} \tan \left(\sqrt{\beta \mu}\left(\eta+\eta_{0}\right)\right) \tag{26}
\end{equation*}
$$

Family 2: When $\beta \mu>0$,

$$
\begin{equation*}
G(\eta)=-\operatorname{sgn}(\beta) \sqrt{\frac{\beta}{\mu}} \cot \left(\sqrt{\beta \mu}\left(\eta+\eta_{0}\right)\right) \tag{27}
\end{equation*}
$$

Family 3: When $\beta \mu<0$,

$$
\begin{equation*}
G(\eta)=\operatorname{sgn}(\beta) \sqrt{-\frac{\beta}{\mu}} \tanh \left(\sqrt{-\beta \mu}\left(\eta+\eta_{0}\right)\right) \tag{28}
\end{equation*}
$$

Family 4: When $\beta \mu<0$,

$$
\begin{equation*}
G(\eta)=\operatorname{sgn}(\beta) \sqrt{-\frac{\beta}{\mu}} \operatorname{coth}\left(\sqrt{-\beta \mu}\left(\eta+\eta_{0}\right)\right) \tag{29}
\end{equation*}
$$

Family 5: When $\beta=0$ and $\mu>0$,

$$
\begin{equation*}
G(\eta)=-\frac{1}{\mu\left(\eta+\eta_{0}\right)} \tag{30}
\end{equation*}
$$

Family 6: When $\beta<0$ and $\mu=0$,

$$
\begin{equation*}
G(\eta)=\beta\left(\eta+\eta_{0}\right) \tag{31}
\end{equation*}
$$

Where: sgn is the known sign function.

## 3 Applications

Substituting by the wave transformation Equation (4) in Equation (1), we acquire the real part equation:

$$
\begin{equation*}
c_{1} v(\eta)-v(\eta)\left(a_{1}^{2} \alpha_{1}+b_{1}^{2} \alpha_{2}+a_{1} b_{1} \alpha_{3}+\alpha_{4} v(\eta)^{2}\right)+\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right) v^{\prime \prime}(\eta)=0 \tag{32}
\end{equation*}
$$

Balancing $v^{\prime \prime}$ with $v^{3}$ in Equation (32), we get $3 N=N+2$, then $N=1$, and the imaginary part equation is given by:

$$
\begin{equation*}
\left(-c_{2}+2 a_{1} a_{2} \alpha_{1}+2 b_{1} b_{2} \alpha_{2}+a_{2} b_{1} \alpha_{3}+a_{1} b_{2} \alpha_{3}\right) v^{\prime}(\eta)=0 . \tag{33}
\end{equation*}
$$

We get:

$$
\begin{equation*}
c_{2}=2 a_{1} a_{2} \alpha_{1}+2 b_{1} b_{2} \alpha_{2}+a_{2} b_{1} \alpha_{3}+a_{1} b_{2} \alpha_{3} . \tag{34}
\end{equation*}
$$

### 3.1 The $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method

Utilizing Equation (6), we express the solution to Equation (32) as:

$$
\begin{equation*}
v(\eta)=\mathfrak{m}_{0}+\mathfrak{m}_{1} \mathfrak{F}(\eta) . \tag{35}
\end{equation*}
$$

Substituting Equation (35) in Equation (32), then equating to zero all the coefficients with the same powers of $\mathfrak{F}(\eta)$, we acquire the following system of equations:

$$
\begin{gathered}
a_{2} \alpha_{3} b_{2} \lambda \mu \mathfrak{m}_{1}-2 a_{2} \alpha_{3} b_{2} \mu^{2} \mathfrak{m}_{1}-a_{1} \alpha_{3} b_{1} \mathfrak{m}_{0} \mathfrak{K}^{3}+a_{2}^{2} \alpha_{1} \lambda \mu \mathfrak{m}_{1}-2 a_{2}^{2} \alpha_{1} \mu^{2} \mathfrak{m}_{1}-a_{1}^{2} \alpha_{1} \mathfrak{m}_{0} \mathfrak{K}^{3} \\
\quad+\alpha_{2} b_{2}^{2} \lambda \mu \mathfrak{m}_{1}-2 \alpha_{2} b_{2}^{2} \mu^{2} \mathfrak{m}_{1}-\mathfrak{m}_{0} \mathfrak{K}^{3}\left(\alpha_{2} b_{1}^{2}+\alpha_{4} \mathfrak{m}_{0}^{2}\right)+c_{1} \mathfrak{m}_{0} \mathfrak{K}^{3}=0, \\
-a_{1} \alpha_{3} b_{1} \mathfrak{m}_{1} \mathfrak{K}^{3}+a_{2} \alpha_{3} b_{2} \lambda^{2} \mathfrak{m}_{1} \mathfrak{K}-4 a_{2} \alpha_{3} b_{2} \lambda \mu \mathfrak{m}_{1} \mathfrak{K}-2 a_{2} \alpha_{3} b_{2} \mu \mathfrak{m}_{1} \mathfrak{K}(\lambda-\mu-1) \\
+4 a_{2} \alpha_{3} b_{2} \mu^{2} \mathfrak{m}_{1} \mathfrak{K}-a_{1}^{2} \alpha_{1} \mathfrak{m}_{1} \mathfrak{K}^{3}+a_{2}^{2} \alpha_{1} \lambda^{2} \mathfrak{m}_{1} \mathfrak{K}-4 a_{2}^{2} \alpha_{1} \lambda \mu \mathfrak{m}_{1} \mathfrak{K}-2 a_{2}^{2} \alpha_{1} \mu \mathfrak{m}_{1} \mathfrak{K}(\lambda-\mu-1) \\
\quad+4 a_{2}^{2} \alpha_{1} \mu^{2} \mathfrak{m}_{1} \mathfrak{K}-\alpha_{2} b_{1}^{2} \mathfrak{m}_{1} \mathfrak{K}^{3}+\alpha_{2} b_{2}^{2} \lambda^{2} \mathfrak{m}_{1} \mathfrak{K}-4 \alpha_{2} b_{2}^{2} \lambda \mu \mathfrak{m}_{1} \mathfrak{K} \\
-2 \alpha_{2} b_{2}^{2} \mu \mathfrak{m}_{1} \mathfrak{K}(\lambda-\mu-1)+4 \alpha_{2} b_{2}^{2} \mu^{2} \mathfrak{m}_{1} \mathfrak{K}+c_{1} \mathfrak{m}_{1} \mathfrak{K}^{3}-3 \alpha_{4} \mathfrak{m}_{0}^{2} \mathfrak{m}_{1} \mathfrak{K}^{3}=0, \\
-3 a_{2} \alpha_{3} b_{2} \lambda \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)+6 a_{2} \alpha_{3} b_{2} \mu \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)-3 a_{2}^{2} \alpha_{1} \lambda \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)+6 a_{2}^{2} \alpha_{1} \\
\mu \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)-3 \alpha_{2} b_{2}^{2} \lambda \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)+6 \alpha_{2} b_{2}^{2} \mu \mathfrak{m}_{1} \mathfrak{K}^{2}(\lambda-\mu-1)-3 \alpha_{4} \mathfrak{m}_{0} \mathfrak{m}_{1}^{2} \mathfrak{K}^{3}=0, \\
2 a_{2} \alpha_{3} b_{2} \mathfrak{m}_{1} \mathfrak{K}^{3}(\lambda-\mu-1)^{2}+2 a_{2}^{2} \alpha_{1} \mathfrak{m}_{1} \mathfrak{K}^{3}(\lambda-\mu-1)^{2}+2 \alpha_{2} b_{2}^{2} \mathfrak{m}_{1} \mathfrak{K}^{3}(\lambda-\mu-1)^{2}-\alpha_{4} \mathfrak{m}_{1}^{3} \mathfrak{K}^{3}=0 .
\end{gathered}
$$

We acheive two sets of solutions:

## Set 1:

$$
\begin{align*}
\mathfrak{m}_{0} & =-\frac{(\lambda-2 \mu) \sqrt{\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}}}{\sqrt{2} \sqrt{\alpha_{4}} \mathfrak{K}}, \quad \mathfrak{m}_{1}=\frac{\sqrt{2}(\lambda-\mu-1) \sqrt{\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}}}{\sqrt{\alpha_{4}}},  \tag{36}\\
c_{1} & =\alpha_{1} a_{1}^{2}+\alpha_{3} a_{1} b_{1}+\frac{\left(\lambda^{2}-4 \mu\right)\left(\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}\right)}{2 \mathfrak{K}^{2}}+\alpha_{2} b_{1}^{2}
\end{align*}
$$

Set 2:

$$
\begin{align*}
& \mathfrak{m}_{0}=\frac{(\lambda-2 \mu) \sqrt{\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}}}{\sqrt{2} \sqrt{\alpha_{4}} \mathfrak{K}}, \quad \mathfrak{m}_{1}=\frac{\sqrt{2}(-\lambda+\mu+1) \sqrt{\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}}}{\sqrt{\alpha_{4}}},  \tag{37}\\
& c_{1}=\alpha_{1} a_{1}^{2}+\alpha_{3} a_{1} b_{1}+\frac{\left(\lambda^{2}-4 \mu\right)\left(\alpha_{1} a_{2}^{2}+\alpha_{3} a_{2} b_{2}+\alpha_{2} b_{2}^{2}\right)}{2 \mathfrak{K}^{2}}+\alpha_{2} b_{1}^{2}
\end{align*}
$$

We obtain the subsequent sets of solution families:
Family 1: When $\Delta=\lambda^{2}-4 \mu>0$,

$$
\begin{align*}
& u(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)} \times \\
& \left(\mathfrak{m}_{0}+\mathfrak{m}_{1}\left(\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}-\frac{\sqrt{\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \tanh \left(\frac{\sqrt{\Delta}\left(a_{2} x+b_{2} y-c_{2} t\right)}{2 \mathfrak{K}}\right)\right)\right), \tag{38}
\end{align*}
$$

Subject to the constraint: $(\lambda-2)\left(p_{2}-p_{1}\right)-\sqrt{\Delta}\left(p_{2}+p_{1}\right)=0$,

$$
\begin{align*}
& u(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)} \times \\
& \left(\mathfrak{m}_{0}+\mathfrak{m}_{1}\left(\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}-\frac{\sqrt{\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \operatorname{coth}\left(\frac{\sqrt{\Delta}\left(a_{2} x+b_{2} y-c_{2} t\right)}{2 \mathfrak{K}}\right)\right)\right), \tag{39}
\end{align*}
$$

Subject to the constraint: $(\lambda-2)\left(p_{2}+p_{1}\right)-\sqrt{\Delta}\left(p_{2}-p_{1}\right)=0$.
Family 2: When $\Delta=\lambda^{2}-4 \mu<0$,

$$
\begin{align*}
& u(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)} \times \\
& \left(\mathfrak{m}_{0}+\mathfrak{m}_{1}\left(\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}+\frac{\sqrt{-\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \tan \left(\frac{\sqrt{-\Delta}\left(a_{2} x+b_{2} y-c_{2} t\right)}{2 \mathfrak{K}}\right)\right)\right), \tag{40}
\end{align*}
$$

Subject to the constraint: $(\lambda-2) p_{2}+\sqrt{-\Delta} p_{1}=0$,

$$
\begin{align*}
& u(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)} \times \\
& \left(\mathfrak{m}_{0}+\mathfrak{m}_{1}\left(\frac{\lambda-2 \mu}{2 \mathfrak{K}(\lambda-\mu-1)}+\frac{\sqrt{-\Delta}}{2 \mathfrak{K}(\lambda-\mu-1)} \cot \left(\frac{\sqrt{-\Delta}\left(a_{2} x+b_{2} y-c_{2} t\right)}{2 \mathfrak{K}}\right)\right)\right), \tag{41}
\end{align*}
$$

Subject to the constraint: $(\lambda-2) p_{1}-\sqrt{-\Delta} p_{2}=0$.

### 3.2 The extended hyperbolic function method

Equation (15) introduce the solution as follows:

$$
\begin{equation*}
v(\eta)=f_{0}+f_{1} G(\eta) \tag{42}
\end{equation*}
$$

## The first form

Substituting Equation (42) and Equation (16) in Equation (32), then grouping terms of like powers and setting all coefficients to zero leads to the following set of equations:

$$
\begin{align*}
& c_{1} f_{0}-a_{1}^{2} f_{0} \alpha_{1}-b_{1}^{2} f_{0} \alpha_{2}-a_{1} b_{1} f_{0} \alpha_{3}-f_{0}^{3} \alpha_{4}=0 \\
& c_{1} f_{1}-a_{1}^{2} f_{1} \alpha_{1}+\beta a_{2}^{2} f_{1} \alpha_{1}-b_{1}^{2} f_{1} \alpha_{2}+\beta b_{2}^{2} f_{1} \alpha_{2}-a_{1} b_{1} f_{1} \alpha_{3}+\beta a_{2} b_{2} f_{1} \alpha_{3}  \tag{43}\\
& -3 f_{0}^{2} f_{1} \alpha_{4}=0,-3 f_{0} f_{1}^{2} \alpha_{4}=0 \\
& 2 \mu a_{2}^{2} f_{1} \alpha_{1}+2 \mu b_{2}^{2} f_{1} \alpha_{2}+2 \mu a_{2} b_{2} f_{1} \alpha_{3}-f_{1}^{3} \alpha_{4}=0 .
\end{align*}
$$

Solving this system yields two sets of solutions:

## Set 1:

$$
\begin{align*}
& f_{0}=0, \quad f_{1}=-\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}  \tag{44}\\
& c_{1}=a_{1}^{2} \alpha_{1}-\beta a_{2}^{2} \alpha_{1}+b_{1}^{2} \alpha_{2}-\beta b_{2}^{2} \alpha_{2}+a_{1} b_{1} \alpha_{3}-\beta a_{2} b_{2} \alpha_{3} .
\end{align*}
$$

## Set 2:

$$
\begin{align*}
& f_{0}=0, \quad f_{1}=\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}  \tag{45}\\
& c_{1}=a_{1}^{2} \alpha_{1}-\beta a_{2}^{2} \alpha_{1}+b_{1}^{2} \alpha_{2}-\beta b_{2}^{2} \alpha_{2}+a_{1} b_{1} \alpha_{3}-\beta a_{2} b_{2} \alpha_{3} .
\end{align*}
$$

Therefore, we derive the subsequent sets of solution families as follows:
Family 1: When $\beta>0$ and $\mu>0$,

$$
\begin{align*}
u_{1}(x, y, t) & =e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left( \pm\left(\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}_{4}}\right)\right. \\
& \left.\left(\sqrt{\frac{\beta}{\mu}} \operatorname{csch}\left(\sqrt{\beta}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) . \tag{46}
\end{align*}
$$

Family 2: When $\beta<0$ and $\mu>0$,

$$
\begin{gather*}
u_{2}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp\left(\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}\right)\right. \\
\left.\left(\sqrt{-\frac{\beta}{\mu}} \sec \left(\sqrt{-\beta}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) \tag{47}
\end{gather*}
$$

Family 3: When $\beta>0$ and $\mu<0$,

$$
\begin{align*}
u_{3}(x, y, t) & =e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp \pm\left(\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}\right)\right. \\
& \left.\left(\sqrt{-\frac{\beta}{\mu}} \operatorname{sech}\left(\sqrt{\beta}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) \tag{48}
\end{align*}
$$

Family 4: When $\beta<0$ and $\mu<0$,

$$
\begin{equation*}
u_{4}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp \pm\left(\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}\right)\left(\sqrt{-\frac{\beta}{\mu}} \csc \left(\sqrt{-\beta}\left(\eta+\eta_{0}\right)\right)\right)\right) \tag{49}
\end{equation*}
$$

Family 7: When $\beta=0$ and $\mu>0$,

$$
\begin{equation*}
u_{7}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp \pm\left(\frac{\sqrt{2 \mu\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}_{4}}\right)\left(\frac{1}{\left(\sqrt{\mu}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)}\right)\right) . \tag{50}
\end{equation*}
$$

## The Second form

Substituting Equation (42) and Equation (25) in Equation (32), then collecting terms of like powers and setting all the coefficients equal to zero, we acquire the following set of equations:

$$
\begin{align*}
& c_{1} f_{0}-a_{1}^{2} f_{0} \alpha_{1}-b_{1}^{2} f_{0} \alpha_{2}-a_{1} b_{1} f_{0} \alpha_{3}-f_{0}^{3} \alpha_{4}=0 \\
& c_{1} f_{1}-a_{1}^{2} f_{1} \alpha_{1}+2 \beta \mu a_{2}^{2} f_{1} \alpha_{1}-b_{1}^{2} f_{1} \alpha_{2}+2 \beta \mu b_{2}^{2} f_{1} \alpha_{2}-a_{1} b_{1} f_{1} \alpha_{3}+2 \beta \mu a_{2} b_{2} f_{1} \alpha_{3} \\
& -3 f_{0}^{2} f_{1} \alpha_{4}=0, \quad 3 f_{0} f_{1}^{2} \alpha_{4}=0  \tag{51}\\
& 2 \mu^{2} a_{2}^{2} f_{1} \alpha_{1}+2 \mu^{2} b_{2}^{2} f_{1} \alpha_{2}+2 \mu^{2} a_{2} b_{2} f_{1} \alpha_{3}-f_{1}^{3} \alpha_{4}=0 .
\end{align*}
$$

Solving this system yields two sets of solutions:

## Set 1:

$$
\begin{align*}
& f_{0}=0, \quad f_{1}=-\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha_{4}}}  \tag{52}\\
& c_{1}=a_{1}^{2} \alpha_{1}-2 \beta \mu a_{2}^{2} \alpha_{1}+b_{1}^{2} \alpha_{2}-2 \beta \mu b_{2}^{2} \alpha_{2}+a_{1} b_{1} \alpha_{3}-2 \beta \mu a_{2} b_{2} \alpha_{3}
\end{align*}
$$

Set 2:

$$
\begin{align*}
& f_{0}=0, \quad f_{1}=\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}}  \tag{53}\\
& c_{1}=a_{1}^{2} \alpha_{1}-2 \beta \mu a_{2}^{2} \alpha_{1}+b_{1}^{2} \alpha_{2}-2 \beta \mu b_{2}^{2} \alpha_{2}+a_{1} b_{1} \alpha_{3}-2 \beta \mu a_{2} b_{2} \alpha_{3} .
\end{align*}
$$

Therefore, the solitary wave solutions of Equation (1) are given by the next formulas:
Family 1: When $\beta \mu>0$,

$$
\begin{gather*}
u_{1}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp\left(\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha_{4}}}\right)\right. \\
\left.\left(\operatorname{sgn}(\beta) \sqrt{\frac{\beta}{\mu}} \tan \left(\sqrt{\beta \mu}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) . \tag{54}
\end{gather*}
$$

Family 2: When $\beta \mu>0$,

$$
\begin{gather*}
u_{2}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp\left(\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha_{4}}}\right)\right. \\
\left.\left(\operatorname{sgn}(\beta) \sqrt{\frac{\beta}{\mu}} \cot \left(\sqrt{\beta \mu}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) . \tag{55}
\end{gather*}
$$

Family 3:When $\beta \mu<0$,

$$
\begin{align*}
u_{3}(x, y, t) & =e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp\left(\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha_{4}}}\right)\right. \\
& \left.\left(\operatorname{sgn}(\beta) \sqrt{-\frac{\beta}{\mu}} \tanh \left(\sqrt{-\beta \mu}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right) \tag{56}
\end{align*}
$$

Family 4: When $\beta \mu<0$,

$$
\begin{align*}
u_{4}(x, y, t) & =e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left(\mp\left(\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha}_{4}}\right)\right.  \tag{57}\\
& \left.\left(\operatorname{sgn}(\beta) \sqrt{-\frac{\beta}{\mu}} \operatorname{coth}\left(\sqrt{-\beta \mu}\left(\left(a_{2} x+b_{2} y-c_{2} t\right)+\eta_{0}\right)\right)\right)\right)
\end{align*}
$$

Family 5: When $\beta=0$ and $\mu>0$,

$$
\begin{equation*}
u_{5}(x, y, t)=e^{i\left(a_{1} x+b_{1} y-c_{1} t\right)}\left( \pm\left(\frac{\mu \sqrt{2\left(a_{2}^{2} \alpha_{1}+b_{2}^{2} \alpha_{2}+a_{2} b_{2} \alpha_{3}\right)}}{\sqrt{\alpha_{4}}}\right)\left(\frac{1}{\mu\left(\eta+\eta_{0}\right)}\right)\right) . \tag{58}
\end{equation*}
$$

## 4 Graphical illustrations

In the present section, we exhibit our solutions graphically. The graphs are presented as follows: The graph of Equation (38) for $u(x, y, t)$ Equation (38) with set $1(36)$ applying the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$ expansion method is shown in Figure 1 at $\mathfrak{K}=2, \lambda=\sqrt{6}, \mu=1.3, a_{1}=1, a_{2}=1, b_{1}=1, b_{2}=$ $0.1, \alpha_{1}=0.1, \alpha_{2}=0.005, \alpha_{3}=0.005, \alpha_{4}=0.004, p_{2}=-3.02046 p_{1}$. Equation (38) for $u(x, y, t)$ with set 2 Equation (37) are plotted in Figure 2 using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathcal{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method at $\mathfrak{K}=$ $2, \lambda=\sqrt{6}, \mu=1.3, a_{1}=1, a_{2}=1, b_{1}=1, b_{2}=1, \alpha_{1}=0.1, \alpha_{2}=0.1, \alpha_{3}=0.005, \alpha_{4}=0.004, p_{2}=$ $-3.02046 p_{1}$. Figure 3 presents the graph of Equation (40) for $u(x, y, t)$ with set 1 Equation (36) employing the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method at $\mathfrak{K}=2, \lambda=0.01, \mu=0.3, a_{1}=0.1, a_{2}=0.1, b_{1}=$ $0.1, b_{2}=0.01, \alpha_{1}=0.3, \alpha_{2}=0.02, \alpha_{3}=0.4, \alpha_{4}=0.5, p_{2}=0.550452 p_{1}$. Figure 4 shows the graph of Equation (40) for $u(x, y, t)$ with set 2 Equation (37) using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K G}^{\prime}+\mathfrak{G}+\mathrm{r}}\right)$-expansion method at $\mathfrak{K}=2, \lambda=0.01, \mu=0.3, a_{1}=0.1, a_{2}=0.1, b_{1}=0.1, b_{2}=0.01, \alpha_{1}=0.3, \alpha_{2}=0.02, \alpha_{3}=$ $0.4, \alpha_{4}=0.1, p_{2}=0.550452 p_{1}$. Figure 5 shows the graph of (48) for $u_{3}(x, y, t)$ with set 1 Equation (44) applying the extended hyperbolic function method at $\alpha_{2}=0.3, \beta=0.1, \alpha_{3}=0.005, \mu=$ $-0.4, \alpha_{1}=0.005, a_{1}=1, b_{1}=1, \alpha_{4}=0.05, b_{2}=1, \eta_{0}=0.3, a_{2}=1$. Figure 6 presents the graph of Equation (48) for $u_{3}(x, y, t)$ with set 2 Equation (45) using the extended hyperbolic function method at $\beta=0.1, \alpha_{3}=0.005, \mu=-0.6, \alpha_{1}=0.005, a_{1}=1, \alpha_{2}=0.3, a_{2}=1, b_{1}=1, b_{2}=1, \eta_{0}=$ $0.3, \alpha_{4}=0.05$. Figure 7 shows the graph of Equation (56) for $u_{3}(x, y, t)$ with set 1 Equation (52) applying the extended hyperbolic function method at $\beta=-0.1, \alpha_{2}=0.5, \mu=0.4, \alpha_{1}=0.1, a_{2}=$ $1, \alpha_{3}=0.3, b_{1}=1, \alpha_{4}=0.6, b_{2}=1, \eta_{0}=0.8, a_{1}=1$. Finally, Figure 8 presents the graph of (56) for $u_{3}(x, y, t)$ with set 2 Equation (53) using the extended hyperbolic function method at $\alpha_{2}=0.5, \beta=-0.1, \mu=0.4, \alpha_{1}=0.1, a_{2}=1, \alpha_{3}=0.3, b_{1}=1, \alpha_{4}=0.6, b_{2}=1, \eta_{0}=0.8, a_{1}=1$.


Figure 1: Solution Equation (38) for $u(x, y, t)$ (Set 1, Equation (36)) obtained using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$ )expansion method with parameters: $\mathfrak{K}=2, \lambda=\sqrt{6}, \mu=1.3, a_{1}=1, a_{2}=1, b_{1}=1, b_{2}=0.1, \alpha_{1}=$ $0.1, \alpha_{2}=0.005, \alpha_{3}=0.005, \alpha_{4}=0.004, p_{2}=-3.02046 p_{1}$.


Figure 2: Solution Equation (38) for $u(x, y, t)$ (Set 2, Equation (37)) obtained using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$ )expansion method with parameters: $\mathfrak{K}=2, \lambda=\sqrt{6}, \mu=1.3, a_{1}=1, a_{2}=1, b_{1}=1, b_{2}=1, \alpha_{1}=$ $0.1, \alpha_{2}=0.1, \alpha_{3}=0.005, \alpha_{4}=0.004, p_{2}=-3.02046 p_{1}$.


Figure 3: Solution Equation (40) for $u(x, y, t)$ (Set 1, Equation (36)) obtained using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathcal{S}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$ )expansion method with parameters: $\mathfrak{K}=2, \lambda=0.01, \mu=0.3, a_{1}=0.1, a_{2}=0.1, b_{1}=0.1, b_{2}=$ $0.01, \alpha_{1}=0.3, \alpha_{2}=0.02, \alpha_{3}=0.4, \alpha_{4}=0.5, p_{2}=0.550452 p_{1}$.


Figure 4: Solution Equation (39) for $u(x, y, t)$ (Set 2, Equation (37)) obtained using the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$ expansion method with parameters: $\mathfrak{K}=2, \lambda=0.01, \mu=0.3, a_{1}=0.1, a_{2}=0.1, b_{1}=0.1, b_{2}=$ $0.01, \alpha_{1}=0.3, \alpha_{2}=0.02, \alpha_{3}=0.4, \alpha_{4}=0.1, p_{2}=0.550452 p_{1}$.


Figure 5: Solution Equation (48) for $u_{3}(x, y, t)$ (Set 1, Equation (44)) obtained using the Extended Hyperbolic Function method with parameters: $\alpha_{2}=0.3, \beta=0.1, \alpha_{3}=0.005, \mu=-0.4, \alpha_{1}=$ $0.005, a_{1}=1, b_{1}=1, \alpha_{4}=0.05, b_{2}=1$, and $\eta_{0}=0.3, a_{2}=1$.


Figure 6: Solution Equation (48) for $u_{3}(x, y, t)$ (Set 2, Equation (45)) obtained using the extended hyperbolic function method with parameters: $\beta=0.1, \alpha_{3}=0.005, \mu=-0.6, \alpha_{1}=0.005, a_{1}=$ $1, \alpha_{2}=0.3, a_{2}=1, b_{1}=1, b_{2}=1, \eta_{0}=0.3, \alpha_{4}=0.05$.


Figure 7: Solution Equation (56) for $u_{3}(x, y, t)$ (Set 1, Equation (52)) obtained using the extended hyperbolic function method with parameters: $\beta=-0.1, \alpha_{2}=0.5, \mu=0.4, \alpha_{1}=0.1, a_{2}=1, \alpha_{3}=$ $0.3, b_{1}=1, \alpha_{4}=0.6, b_{2}=1, \eta_{0}=0.8, a_{1}=1$.


Figure 8: Solution Equation (56) for $u_{3}(x, y, t)$ (Set 2, Equation (53)) obtained using the extended hyperbolic function method with parameters: $\alpha_{2}=0.5, \beta=-0.1, \mu=0.4, \alpha_{1}=0.1, a_{2}=1, \alpha_{3}=$ $0.3, b_{1}=1, \alpha_{4}=0.6, b_{2}=1, \eta_{0}=0.8, a_{1}=1$.

## 5 Discussion

The (2+1)-dimensional Heisenberg ferromagnetic spin chain (HFSC) equation is an important nonlinear Schrödinger equation that can be used to model the dynamics of spin systems in magnetic materials. Analytical solutions of this equation can provide insights into the fundamental physics of spin systems and their interactions with light, which can be useful in the design and optimization of various devices in optics and related fields.
The $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method is a versatile and systematic approach for solving a wide range of nonlinear partial differential equations. This method is applicable to diverse problems, with the flexibility to determine key parameters, providing insights into the system's behavior. It categorizes solutions into distinct classes based on the discriminant, making it a valuable tool for understanding complex physical and mathematical phenomena. The extended hyperbolic function method excels in solving nonlinear partial differential equations, its capability to handle diverse nonlinearities makes it a valuable tool for obtaining precise mathematical solutions. These solutions can be used to design and optimize various devices in optics and related fields.
Graphs are formidable tools for illustrating and clarifying solution representations. With the specified parameter values indicated alongside each graph, the profiles of the two-dimensional graphs exhibit a characteristic bell-shaped form and the wave moves to the right as time increases in Figures 5 and 6. In Figures $1,2,3,4,7$ and 8 the reverse wave moves to the right as time progresses.

## 6 Conclusion

The Heisenberg ferromagnetic spin chain equation has important applications in optics and related fields, including spintronics, quantum dots, and quantum optics. The model can aid in the design and optimization of various devices and can provide insights into the fundamental physics of spin systems and their interactions with light. In this study, We have scrutinized the ( $2+1$ )-dimensional Heisenberg ferromagnetic spin chain equation by using two strong analytical methods, the first one is the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method and the second one is the extended hyperbolic function method (EHFM). Our methods carry new soliton solutions with various types as: bright soliton solutions, dark soliton solutions, periodic solutions, Singular solutions, and others. Choosing appropriate values for the parameters we present most of our solutions graphically to show the power of the proposed methods.
The obtained solutions in this research have many forms: hyperbolic, trigonometric, power, exponential, and rational functions, and the solutions presented analytically in other researches have also many forms, and therefore it is difficult to make a comparison in tables. However, a comparison with recent references $[30,32]$ was made during the solution through graphics, which proved the compatibility of our results with others.
In future research we can applying the $\left(\frac{\mathfrak{G}^{\prime}}{\mathfrak{K} \mathfrak{G}^{\prime}+\mathfrak{G}+\mathfrak{r}}\right)$-expansion method and the extended hyperbolic function technique (EHFM) to:
1-Extending the equation to higher dimensions, including (3+1) or beyond. This expansion would significantly enhance our understanding of the equation's behavior in more complex systems, shedding light on emergent phenomena and collective interactions within the spin chain. 2-Solve the nonlinear modified Gardner (mG) equation, which holds particular importance in comprehending the intricate dynamics of quantum electron-positron ion magneto plasmas [47].

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## Biographies

## Khalid K. Ali

I have authored/co-authored over 160 scientific papers in top-ranked International Journals and Conference Proceedings. My research interests include Numerical Analysis, Finite Difference Methods, Finite Element Methods, Computational Mathematics, Partial differential equations, Integral equations, Integro-differential equation, and q-calculus.

## Abdel-Haleem Abdel-Aty

Professor (Assistant) at University of Bisha Saudi Arabia. I have authored/co-authored over 256 scientific papers in top-ranked International Journals and Conference Proceedings. My research interests include theories of quantum measurement, nanomechanical modeling, highly non-classical light, practical information security, and optical implementations of quantum information tasks. His current research interests include quantum resources, optical and atomic implementations of quantum information tasks and protocols, mathematical modeling, differential equations and applications in science and engineering and classifications algorithms.

## M.S.Mehanna

Professor (Assistant) at Modern Technology and Information University. I have authored/coauthored over 27 scientific papers in top-ranked International Journals and Conference Proceedings. My research interests include Computational Mathematics, Partial differential equations, Integral equations, Integro-differential equation and applications in science, engineering and classifications algorithms.

