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Soft computing-based approach for capacity prediction of FRP-strengthened RC joints

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KEYWORDS RC Joint; FRP; Capacity; ANN. **Abstract.** Shear failure of RC beam-column joints is a brittle failure that occurs with no prior warning and induces tremendous damages due to collapse of column and joint before the connected beam. This paper is focused on one particular method of strengthening the RC joints, that is, the use of FRP composites as a confining element. The results of previous studies have shown that strengthening the RC beam-column joints with FRP composites could improve their shear capacity. In this study, the data collected from the existing standards and studies regarding the FRP strengthened RC joints were used to develop an artificial neural network model to predict the shear strength contribution of FRP jacket. The developed model was then used to evaluate the role of different parameters in this contribution and, finally, derive a formula to contribute FRP jacket to the shear strength of the RC beam-column joints.

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1. Introduction

The idea of using Fibe-Reinforced Polymer (FRP) composites as a confining component was first introduced by Fardis and Khalili in 1982 [1]. Later, this idea was developed through laboratory and analytical works of other researchers; for instance, Lee and Fenves used FRP jacket for shear and flexural strengthening of joints [2]; Antonopoulos and Triantafillou studied the use of Fiber-Reinforced Polymer (FRP) composites for strengthening beam-column joints while taking the role of fiber debonding into account [3]; Parvin and Granata [4,5] studied the effect of FRP on RC joints through computer modeling as well as laboratory work. These studies have been generally focused on augmenting the shear strength.

*. Corresponding author. Tel.: +98 23 33533781; Fax: +98 23 33654121 E-mail address: naderpour@semnan.ac.ir (H. Naderpour) The effectiveness of FRP for shear strengthening of RC joints is associated with multiple factors including dimensions of joint, elasticity modulus of composite material, etc. Considering the complexity of shear failure mechanism and the multitude of parameters affecting the shear capacity of FRP jacket, the use of Artificial Neural Networks (ANN) could be a good solution for finding the relationships between these parameters and their effect on shear strength contribution of FRP component. In this study, an ANN model is developed to predict the shear strength contribution of FRP jacket to shear-strengthened RC joints.

2. Artificial neural network

Artificial Neural Network (ANN) is an intelligent system with extensive applications in science and engineering since the late 1980s. ANNs can be described as an extremely simple electronic model of the human brain. Learning mechanisms of the brain are based primarily on experience, and the extraordinary power of the brain to absorb these experiences originates



Figure 1. Typical computational models of artificial neural networks (p = input vector, w = input variables weight, n = internal processing function, f = activation function, and a = output vector).

from the presence of a tremendous number of neurons and their natural connections. The core principles of ANN models are based on a similar logic [6-11]. A schematic representation of neurons in a network is shown in Figure 1. Application of ANNs in predicting the response of structural elements has been considered by some researchers [12-19].

2.1. ANNs' input parameters

This study was performed using a set of empirical data regarding the FRP-strengthened RC joints. In all collected data, shear strength contribution of FRP was obtained through the following procedure. First, in each experiment, at least one control specimen was used to determine the baseline shear strength of the joint. This baseline shear strength is the sum of shear strength contribution of concrete and that of steel stirrups (when present). Next, the shear strengths of the FRP-strengthened specimens identical to the control specimens were obtained. Finally, the shear strength contribution of FRP was obtained by subtracting the baseline shear strength from the shear strength of the corresponding FRP-strengthened specimen.

Initially, data pertaining to 155 FRPstrengthened joint specimens were collected [20-51]. Of these 155 specimens, 34 specimens had shown debonding during the test and could not be used. In addition, 55 specimens had an undesirable mechanism of failure (failure in beam before FRP reaching its capacity in the joint) and were, therefore, removed from the data. The use of such data instances in the network training leads to error, because the joint specimen fails before reaching its maximum shear capacity, meaning that it would have sustained a greater shear force if the beam had a greater shear capacity. In addition, 8 specimens were also strengthened with other types of reinforcement and were, therefore, removed from the data to ensure the uniformity of inputs. Therefore, ultimately, 58 specimens remained for analysis.

After collecting suitable data for the network, it is required to choose the parameters that affect the output values. After reviewing the literature [52,53], it was concluded that shear strength contribution of FRP was influenced by the six following parameters:

- Effective depth of the FRP on the joint and the angle between the axis of the column and fiber orientation, $D \pmod{3}$;
- Cross-sectional area of the column, A_c (mm²);
- Compressive strength of the concrete, f'_c (MPa);
- Elasticity modulus of the FRP, E (GPa);
- Thickness FRP, t_f (mm);
- Tensile strength of the FRP, F_{fu} (MPa).

In this study, shear strength contribution of FRP (V_f) is considered as the output.

Table 1 shows the statistical characteristics of the laboratory specimens used in the networks.

3. Modeling of the artificial neural network

In total, 9 networks with different hidden neurons (2 to 10) were trained. The next step after the training is to identify the best network and, then, to compare its results with the experimental data. The Mean Squared Error (MSE) and regression value of the developed ANNs are shown, respectively, in Figures 2 and 3.

All ANNs were trained using the Levenberg-Maequardt algorithm with back propagation method [54]. The back propagation-based ANNs often use the transfer functions of Log sigmoid and Tan sigmoid. These functions can be used for the output function, which means limiting the output to a small

| Input nodes | $f_{c}^{\prime}~(\mathrm{MPa})$ | E (GPa) | $D_{fu}~({ m MPa})$ | $t_f~(\mathrm{mm})$ | $D \ (mm)$ | $A_c \ (\mathrm{mm}^2)$ | $V_f~({ m kN})$ |
|--------------------|---------------------------------|---------|---------------------|---------------------|------------|-------------------------|-----------------|
| Min | 13.5 | 27.6 | 135.5 | 0.053 | 100 | 24000 | 4.12 |
| Max | 64.7 | 285 | 4965.8 | 3.3 | 707.1 | 148555 | 69 |
| Average | 29.64 | 175.9 | 2832.6 | 0.76 | 342.7 | 63124 | 19.4 |
| Variance | 124.8 | 6729.2 | 1708859 | 0.699 | 22989.8 | $1.22^{*}10^{9}$ | 199.18 |
| Standard deviation | 11.17 | 82.03 | 1307.2 | 0.83 | 151.5 | 34880.3 | 14.11 |

Table 1. Statistical criteria of experimental data.



Figure 2. Mean Squared Error (MSE) versus the number of hidden-layer neurons.



Figure 3. Correlation coefficient versus the number of hidden-layer neuron.

value. The better option for the output function is the Purlin function that allows the output to take any value. The stop condition for training algorithm is the minimization of MSE, that is, the mean squared difference between the output and the target value.

One of the criteria based on which the best ANN can be determined is the regression value. The regression value (R) measures the correlation between the ANN outputs and the target values; R = 1represents a perfect correlation between the output and the target value, while R = 0 means that any relationship between the output and the target value would be random. In this study, MSE and regression value were used as the criteria for selecting the ideal network.

As observed, all ANNs were properly trained, and the obtained errors were very small. The highest errors (MSE) were 0.35 and 0.44, which belonged to ANNs with 10 and 7 hidden neurons; the lowest errors were 0.18 and 0.16, observed in ANNs with 5 and 6 hidden neurons. In the most accurate ANNs (those with 5 and 6 hidden neurons), the regression values for the entire data were 94% and 98%. As can be seen, the ANN with 6 hidden neurons had a very good MSE (0.16) and a very high correlation coefficient. The regression values of this ANN for training, verification, test data, and the entire data were 0.999, 0.939, 0.970, and 0.982, respectively. Considering these four criteria, the ANN with 6 hidden neurons was chosen as the best network and the one to be used for the remainder of work.



Figure 4. Performance Trained network with 6 neurons in the hidden layer.



Figure 5. Learning curve networks trained with 6 neurons in the hidden layer.

MSE graph of the ANN with 6 hidden neurons (Figure 4) shows a decreasing trend, representing the network's learning process. This graph has three curves: the MSE for training data, validation data, and test data. At the beginning of the learning, this ANN has an error of about 8%; however, as the learning process continues, network weights are adjusted and errors decrease until reaching down, at the twentieth step, to the values of 0.008, 0.2, and 0.1 for training, validation, and test data.

The graphs illustrating the process of learning, and regressions values of input data are plotted respectively in Figures 5 and 6. A decreasing trend of gradient graph depicted in Figure 5 represents the trend of learning. This gradient reduction continues until MSE reaches down to its minimum value. At this point, learning stops; from this point onwards, gradient is constant. The regression values shown in Figure 6 imply the proper training of the network and demonstrate the close proximity between its outputs and the target vector.

In view of the described results, it was concluded



Figure 6. Regression data for training and testing the accuracy of the network with 6 neurons in the hidden layer.

that the ANN modeled with six hidden neurons was properly trained for input and output data, and it is suitable for the remainder of this work.

3.1. Comparison of the ANN results with experimental data

To validate the developed ANN, its results were compared with the experimental data. Figure 7 and Table 2 show the relationship between experimentally obtained shear strength contribution of FRP jacket and the value obtained from the developed network. In this figure, the points on the 45-degree line represent zero difference between the experimental data and the results of the proposed formulas; the distance of each point from the 45-degree line represents the magnitude of error in the calculated value.

4. The proposed formula for predicting shear strength contribution of FRP component

The above comparisons show the good agreement of the ANN results with the experimental data. However, the direct use of ANN is not a common practice in engineering design; instead, this paper provides a nonlinear relationship capable of predicting the FRP shear strength contribution.

To derive this formula, first, each parameter needs to be initialized with a value (within its variation



Figure 7. Error compared to the values obtained by neural networks and relationships.

range). Here, values close to the average values of the parameters were chosen for this purpose. The base values assumed for different variables are shown in Table 3. After determining the base values, one of the six input parameters was considered as a variable, and the range of its variation was divided into several parts. This division needs to include the upper and lower bounds of the variation range as well as the base value.

| Range of error (%) | Number of data in the range of error | Percentage of data in the range of error (%) |
|-----------------------|---|---|
| ± 10 | 40 | 68.9 |
| ± 20 | 46 | 97.3 |
| ± 30 | 53 | 91.3 |
| ± 40 | 55 | 94.8 |
| ± 60 | 56 | 96.5 |
| ± 130 | 57 | 98.2 |
| ± 220 | 58 | 100 |

Table 2. Comparison between errors of the values obtained by neural networks and experimental data.

Table 3. Range of input parameters and base values for each parameter.

| Input nodes | $f_{c}^{\prime}~(\mathrm{MPa})$ | E (GPa) | $F_{fu}~({ m MPa})$ | $t_f~(\mathrm{mm})$ | $D \ (mm)$ | $A_{c} \ (\mathrm{mm}^{2})$ |
|-------------------|---------------------------------|---------|---------------------|---------------------|------------|-----------------------------|
| Min | 13.5 | 27.6 | 135.5 | 0.053 | 100 | 24000 |
| Max | 64.7 | 285 | 4965.8 | 3.3 | 707.1 | 148555 |
| Average | 29.64 | 175.9 | 2832.6 | 0.76 | 342.7 | 63124.17 |
| Base | 30 | 180 | 2800 | 0.75 | 350 | 63000 |
| Input correlation | $30/f_c'$ | 180/E | $2800/F_{fu}$ | $0.75/T_{f}$ | 350/D | $63000/A_{c}$ |



Figure 8. Network output changes in relation to changes in effective (D) with constant five other parameters.

The relationship between the ANN output and parameter (D) was examined. This parameter was chosen because of the low sensitivity shown during the weight analysis. To determine the relationship between the ANN output and parameter (D), the other 5 parameters were initialized with their base values, and (D) was gradually changed from its minimum value to its maximum. The effects of these changes on the ANN output are shown in Figure 8. After determining the relationship between (D) and the ANN output, the same procedure was used to determine the relationship between the output and other 5 parameters.

The algorithm's structure was derived from the algorithm of Leung et al. (2006) for calculating the final strain of FRP in flexural-strengthened beams [55,56].

The resulting model is in the form of Eqs. (1) to (6):

$$V_{\text{equation}} = (C_{f_c'} \cdot C_E \cdot C_{F_{fu}} \cdot C_{T_f} \cdot C_D \cdot C_{A_c}), \tag{1}$$

$$C_{f'_{c}} = C_{f'_{c}}(E, F_{fu}, T_{f}, A_{c}),$$
(2)

$$C_E = C_E(f'_c, F_{fu}, T_f, A_c), \qquad (3)$$

$$C_{F_{fu}} = C_{F_{fu}}(E, f'_c, T_f, A_c),$$
(4)

$$C_{T_f} = C_{T_f}(E, F_{fu}, f'_c, A_c),$$
(5)

$$C_{A_c} = C_{A_c}(E, F_{fu}, T_f, f'_c).$$
(6)

To obtain V_f from Eq. (1), six correction factors should be calculated and, then, multiplied by each other. According to Figure 8, C_D can be obtained from Eq. (7).

$$C_D = -58.4 * \left(\frac{D}{350}\right)^3 + 172.2 * \left(\frac{D}{350}\right)^2 - 117.9 * \left(\frac{D}{350}\right)^2 + 31.3.$$
(7)

Figures 8 to 28 show the graphs of correction factors of the other 5 parameters.

After averaging the values obtained for each parameter, the correction factors are determined as follows:

$$C_{f'_c} = 0.535 * \left(\frac{f'_c}{30}\right) + 0.25,\tag{8}$$



Figure 9. Change ratio E of correction coefficient $C_{f'c}$.



Figure 10. Change ratio F_{fu} of correction coefficient $C_{f'c}$.



Figure 11. Change ratio T_f of correction coefficient $C_{f'c}$.



Figure 12. Change ratio A_c of correction coefficient $C_{f'c}$.



Figure 13. Change ratio f'_c of correction coefficient C_E .



Figure 14. Change ratio F_{fu} of correction coefficient C_E .



Figure 15. Change ratio T_f of correction coefficient C_E .



Figure 16. Change ratio A_c of correction coefficient C_E .



Figure 17. Change ratio f'_c of correction coefficient C_{Ffu} .



Figure 18. Change ratio E of correction coefficient C_{Ffu} .



Figure 19. Change ratio T_f of correction coefficient C_{Ffu} .



Figure 20. Change ratio A_c of correction coefficient C_{Ffu} .



Figure 21. Change ratio f'c of correction coefficient C_{Tf} .



Figure 22. Change ratio E of correction coefficient C_{Tf} .



Figure 23. Change ratio F_{fu} of correction coefficient C_{Tf} .



Figure 24. Change ratio A_c of correction coefficient C_{Tf} .



Figure 25. Change ratio f'c of correction coefficient C_{Ac} .



Figure 26. Change ratio E of correction coefficient C_{Ac} .



Figure 27. Change ratio F_{fu} of correction coefficient C_{Ac} .



Figure 28. Change ratio T_f of correction coefficient C_{Ac} .

$$C_E = 1.995 * \left(\frac{E}{180}\right)^3 - 3.65 * \left(\frac{E}{180}\right)^2 + 2$$
$$* \left(\frac{E}{180}\right) + 0.54, \tag{9}$$

$$C_{F_{fu}} = 0.64 * \left(\frac{F_{fu}}{2800}\right)^3 - 1.99 * \left(\frac{F_{fu}}{2800}\right)^2 + 2.07$$
$$* \left(\frac{F_{fu}}{2800}\right) + 0.355, \qquad (10)$$

$$C_{T_f} = 0.1 * \left(\frac{T_f}{0.75}\right) + 0.82,\tag{11}$$

$$C_{A_c} = 0.515 * \left(\frac{A_c}{63000}\right)^3 - 2.3 * \left(\frac{A_c}{63000}\right)^2 + 3.2$$
$$* \left(\frac{A_c}{63000}\right) - 0.45. \tag{12}$$

The errors in FRP shear strength contribution obtained by the proposed formulas are shown in Table 4. Figure 29 shows the relationship between the experimental data and those obtained by the proposed formulas. In this figure, the points on the 45-degree line represent zero difference between the experimental data and the results of the proposed formulas; each point's distance from the 45-degree line represents the magnitude of error in calculated value.

As the graph of Figure 29 shows, most points obtained by the proposed formula are positioned near the bisector line, which indicates the good ability of this formula to predict the shear strength contribution of FRP component.

5. Statistical results of the proposed formula

In this section, a number of statistical criteria for the error of the proposed formula to predict FRP shear strength contribution are examined.



Figure 29. Comparison of experimental results with predicted values by the proposed equation.

5.1. Average error $(_{eAvg})$

The average error of the proposed formula was calculated using Eq. (13), and the value of this criterion for 58 available data instances was calculated as 33.3%.

$$\bar{e} = \frac{\sum_{i=1}^{N} (v_i - v_{it})}{N}.$$
(13)

5.2. Standard deviation

This criterion can express the dispersion of results compared to the mean values. Eq. (14) gives the variance for the proposed formula, and the root of this parameter is the standard deviation. The standard deviation of the proposed formula is 8.02%, which indicates the low dispersion of its results.

$$\operatorname{var} = \frac{\sum_{i=1}^{N} \left(v_i - \overline{v} \right)^2}{N}.$$
(14)

| Range of | Number of error data in the | Percentage error of data in | | |
|-----------|-----------------------------|-------------------------------|--|--|
| error (%) | proposed equations | the proposed equations $(\%)$ | | |
| ± 10 | 11 | 18.9 | | |
| ± 20 | 21 | 36.2 | | |
| ± 30 | 32 | 55.1 | | |
| ± 40 | 38 | 65.5 | | |
| ± 50 | 45 | 77.5 | | |
| ± 60 | 47 | 81 | | |
| ± 70 | 51 | 87.9 | | |
| ± 80 | 56 | 96.5 | | |
| ± 90 | 57 | 98.2 | | |
| ± 160 | 58 | 100 | | |

Table 4. Error values obtained by the proposed equations.

5.3. Root Mean Square Error (RMSE)

The other criterion used to measure the error of the proposed formula is the Root Mean Square Error (RMSE); the smaller the values of RMSE, the lower the error of theoretical results, as compared to experimental data. Through Eq. (15), the value of this criterion for the proposed formula was calculated as 14.88%, indicating the good accuracy of the proposed formula:

$$RMSE = \sqrt{\frac{\sum_{i=1}^{N} (v_i - v_{it})^2}{N}}.$$
(15)

6. Conclusion

In this paper, first, the previous studies on the shear capacity of the FRP-strengthened RC joints were reviewed. The shear strength contribution of FRP to the RC joints can be influenced by many factors, and given the complex mechanism and danger of shear failure, estimating this contribution is of significant importance in preventing early shear failure of the column before the beam. It was concluded that shear strength contribution of FRP was influenced by the six following parameters: effective depth of the FRP in the joint and the angle between the axis of the column and fiber orientation, cross-sectional area of the column, compressive strength of the concrete, modulus of elasticity of the FRP, thickness FRP, and tensile strength of the FRP. Furthermore, shear strength contribution of FRP was considered as the output. In addition, the authors attempted to provide a formula for estimating the shear strength contribution of FRP jacket.

Artificial neural networks provided a general practical method for real-valued, discrete-valued, and vector-valued functions from examples; therefore, they have been widely used in the various applications of engineering fields.

Finally, the artificial neural network architecture was used to develop a model for predicting the FRP shear strength contribution, and the developed model was then used to derive a formula for estimating the shear force sustained solely by the FRP jacket in the RC joint. In the end, the results of the proposed formula were compared with the experimental data. The precision of the proposed equation was verified by the existing experimental data, and a favorable level of agreement was obtained.

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