



Optimal production and ordering strategies with defective items and allowable shortage under two-part trade credit

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KEYWORDS

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Abstract. This study investigated a production-inventory model with defective items under a two-part trade credit, where the agreement of conditionally freight concession is considered in an integrated supply chain. It is assumed here that the retailer conducts the inspection process before selling incoming items. All the defective items are discovered, stored, and sold as a single batch to a secondary market at a decreased price. Furthermore, shortages are allowed and completely backlogged for the retailer. The purpose of this study is to determine the optimal number of shipments per production cycle for the supplier and the optimal length of time when there is no inventory shortage and replenishment cycle for the retailer, such that the total profit function has a maximum value. In theoretical analysis, the existence and uniqueness of the optimal solutions are shown, and an algorithm is developed to find the optimal solutions. Furthermore, numerical examples are presented to demonstrate the solution procedures, and a sensitivity analysis of the optimal solutions regarding all parameters is also carried out.

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1. Introduction

The traditional Economic Order Quantity (EOQ) model does not investigate payment methods when the retailer receives goods from the supplier, and it is assumed that payment is made immediately upon receiving the consignment. However, in real business transactions, to attract new customers and increase sales or market shares, the supplier typically allows the retailer an extended period for making full payment. This is a common business practice because it benefits both the supplier and the retailer. For example, Emery [1] indicated that the supplier often increases

sales by offering trade credit. Moreover, the retailer can accumulate revenue from sales and earn interest on that revenue during this credit period. Petersen and Rajan [2] further noted that trade credit was the widely used and accepted short-term source of funding. Goyal [3] initially incorporated the issue of trade credit into EOQ model. Aggarwal and Jaggi [4] extended Goyal's model [3] to consider deteriorating items. Chang et al. [5] established an EOQ model for deteriorating items where the supplier provides a delay in payments to the purchaser if the order quantity is greater than or equal to a predetermined quantity, which is known as a conditionally permissible delay in payments. Ouyang et al. [6] presented an inventory model for non-instantaneous deteriorating items with permissible delay in payments. Teng [7] attempted to establish an EOQ model for the retailer, wherein a distinct trade credit was offered to customers

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with different types of credit. Ouyang et al. [8] expanded on the model proposed by Goyal [3] to consider deteriorating items and partially permissible delays in payment associated with order quantity. Yang et al. [9] investigated how the retailer determines the optimal ordering and payment policies when the supplier offers cash discounts or delayed payments depending on the order quantity. Sarker et al. [10] developed an inventory model for different types of time-varying demand, where different discount rates for different delay periods are considered. Sarkar et al. [11] considered a deteriorating inventory model with two-level trade credits for fixed lifetime products. Recently, Lashgari et al. [12] investigated an inventory control problem for deteriorating items with two-level trade credit linked to order quantity. Related articles include studies by Sana [13], Khanra et al. [14], Sarkar [15], Jaggi et al. [16], Khanra et al. [17], Ray [18], Khanra et al. [19], and their references.

The aforementioned studies have assumed that the items received are of perfect quality. However, in actual production environments, product quality is not consistently perfect because of imperfect manufacturing and poor handling procedures. Retailers frequently receive defective products, which affect practical inventory levels and increase the risk of shortages and frequency of purchases. Certain studies on inventory models have accounted for this complication. Rosenblatt and Lee [20] considered the effect of imperfect production processes on the Economic Production Quantity (EPQ) model. Porteus [21] incorporated the effect of the defective items into the EPQ model and considered investing capital in production processes to improve product quality. Lee and Rosenblatt [22] considered an economic manufacturing quantity model wherein production cycle length and equipment maintenance intervals were treated as decision variables. Lee and Rosenblatt [23] further incorporated maintenance and recovery costs of the machine into an EPQ model with imperfect production processes. Zhang and Gerchak [24] developed an EOQ model to determine the optimal order quantity and inspection strategy, in which defective products are randomly produced. Groenevelt et al. [25] established an EPQ model by accounting for equipment damage and related maintenance to determine optimal production quantity. Kim and Hong [26] extended the model proposed by Rosenblatt and Lee [20] to determine the optimal length of production run in deteriorating production processes. Wu et al. [27] investigated the effects of quality-guaranteed strategies on the optimal production quantity, wherein the manufacturer offers free repairs for defective products. Tayyab and Sarkar [28] revisited an EPQ model with an imperfect multi-stage production system by considering a random defective rate. Related articles include studies by Khan

et al. [29], Sarkar [30], Hsu and Hsu [31], Hsu et al. [32], Yu and Lin [33], Moussawi-Haidar et al. [34], and their references. Most of these studies have examined how defective products affect optimal production and ordering strategies. However, they have not considered the treatment of defective items.

To ensure quality of goods and maintain a good reputation, companies often make quality inspections frequently and establish disposal processes for defective items prior to sale. Salameh and Jaber [35] considered an EPQ model wherein defective products are discovered during inspection and, then, sold at discounted prices in the secondary markets. Chan et al. [36] incorporated product inspection of all goods into an EPQ model, wherein defective goods are treated by selling them at discounted prices, reworking them, or rejecting them. Chiu [37] developed an EPQ model that considered shortages, and assumed that randomly produced defective products were reworked or discarded. Related studies include those of Chiu [38], Kulkarni [39], Sarker et al. [40], El Saadany and Jaber [41], Sana [42], Sarkar et al. [43–44], Sarkar [45], Ouyang and Chang [46], Tsao et al. [47], Sarkar et al. [48–49], Sarkar and Moon [50], and so on.

When encountering a competitive market and a changing business environment, companies must enhance their operational efficiency, respond to customers' needs rapidly, attempt to reduce inventory costs, and increase profits through the integration of the supply chain system. Therefore, the issues of Supply Chain Management (SCM) about how to integrate suppliers with retailers to establish appropriate production-inventory models and determine the optimal production and ordering strategies that jointly achieve cost minimization or profit maximization have attracted much academic attention. Banerjee [51] developed a joint economic-lot-size model wherein the supplier produces to satisfy orders for a retailer on a lot-for-lot basis. Goyal [52] adjusted Banerjee's model, and noted that when the supplier's setup cost is substantially larger than the retailer's ordering cost, the lot-for-lot method is not optimal. Furthermore, he relaxed the assumption of lot-for-lot policy, surmising that his revised model provided a lower or equal joint total relevant cost. Lu [53] further extended the model proposed by Goyal [52] to consider an integrated inventory model for a single supplier and multiple retailers and relaxed the assumption that shipments could not be arranged before the production batch is completed. Recently, Pal et al. [54] considered a two-echelon competitive supply chain with trade credit policy. Alternative production-inventory models that have investigated various aspects of the coordination of supply chains are as follows: Goyal [55], Yao and Chiou [56], Chung and Wee [57], Chang et al. [58], Lin and Lin [59], Cárdenas-Barrón et al. [60], Lin et al. [61],

Su [62], Sana [63], Das et al. [64], Ouyang et al. [65], Giri and Sharma [66], Ouyang et al. [67], Sana [68], Sarkar [69], Mahata et al. [70], and their references.

To bring the production-inventory models of the supply chain into concurrence with the actual business environment and industrial demand, this paper examines the optimal production and order policies for an integrated supply chain system including:

1. The retailer's arriving lot contains some defective items that are assessed, stored, and then sold in a single batch to a secondary market at a decreased price;
2. Shortages are allowed for the retailer and completely backlogged;
3. If the order quantity of the retailer is greater than or equal to the specified threshold, the transportation cost is paid by the supplier; otherwise, it is paid by the retailer;
4. The supplier provides a two-part trade credit that allows the retailer to make full payment at the time or to pay at an earlier time with a cash discount.

First, the total profit functions for the supplier and retailer are developed and, then, integrated appropriately to determine the joint total profit function of the supply chain. The purpose of this study is to determine the optimal number of shipments per production cycle for the supplier, the optimal length of time wherein there is no inventory shortage, and the length of replenishment cycle for the retailer so as to maximize the joint total profit function. Furthermore, the existence and uniqueness of the optimal solutions are shown, and an algorithm is developed to find the optimal solutions. Finally, numerical examples are presented to demonstrate the solution procedures, and a sensitivity analysis of the optimal solutions with respect to all parameters is described. Different from the previous literature, the major issues considered in the above-mentioned studies compared with the present paper are summarized in Table 1.

2. Problem description

In this model, a single supplier and a single retailer are considered in a supply chain production-inventory system. The operation of this production inventory system is as follows: the retailer orders Q units per order and the supplier produces nQ units per production run and delivers them to the retailer in n shipments, where n is a integer. Each shipment contains certain defective items at a defect rate of λ , and 100% inspection is conducted by the retailer before selling them. All defective items will be discovered, stored, and then sold

to the secondary market with a lower unit price in a single batch after inspection. Further, to encourage the retailer to order more, the supplier provides the retailer with a conditionally freight concession. That is, when the order quantity of retailer Q is greater than or equal to a certain threshold, Q_d , then the transportation cost is absorbed by the supplier; otherwise, it is paid by the retailer. On the other hand, to facilitate the transaction and receive payment as soon as possible, the supplier provides the retailer with a two-part trade credit, which allows the retailer to make payments at time M_2 and, then, provides the retailer with a cash discount and a discount rate α ($0 < \alpha < 1$). If the retailer pays earlier at time M_1 , where $0 \leq M_1 < M_2$, the entire process is repeated. To develop this model, the notations and assumptions are used as follows.

P	Supplier's production rate;
D	Retailer's demand rate;
K	Supplier's setup cost per setup;
A	Retailer's ordering cost per order;
F	Fixed transportation cost per shipment;
r	Variable transportation cost per unit;
h_v	Supplier's holding cost per unit per unit time;
h_{b_1}	Retailer's holding cost per non-defective item per unit time excluding interest charge;
h_{b_2}	Retailer's holding cost per defective item per unit time excluding interest charge, where $h_{b_2} \leq h_{b_1}$;
π	Retailer's shortage cost per unit per unit time;
c	Supplier's production cost per unit;
v	Retailer's wholesale price per unit, where $v > c$;
p	Retailer's unit selling price of non-defective items, where $p > v$;
k	Retailer's unit selling price of defective items in the secondary market, where $0 < k < v$;
λ	Defective rate, where $\lambda \in [0, 1)$;
M_i	Trade credit period offered by the supplier, where $i = 1, 2$ and $0 \leq M_1 < M_2$;
I_v	Supplier's capital opportunity cost per dollar per unit time due to offering trade credit to the retailer;
I_e	Retailer's interest earned per dollar per unit time;

Table 1. A brief literature review of related references.

Reference	Trade credit	Individual /supply chain perspective	Defective item	Shortage	Quantity -dependent freight
[1,2]	No	Individual	No	No	No
[3,4,6,10] [14-15,18]	Yes	Individual (EOQ)	No	No	No
[5]	Conditionally	Individual (EOQ)	No	No	No
[7,8]	Partially	Individual (EOQ)	No	No	No
[9]	Two-part	Individual (EOQ)	No	No	No
[11]	Two-levels	Individual (EPQ)	No	No	No
[12]	Two-levels	Individual (EOQ)	No	Completely backlogging	No
[13]	Yes	Individual (EPQ)	No	No	No
[16]	Two-levels	Individual (EOQ)	No	No	No
[17,19]	Yes	Individual (EOQ)	No	Completely backlogging	No
[20,21-23,25-26] [29,35-36,40-45,49]	No	Individual (EPQ)	Yes	No	No
[24,28,32,50]	No	Individual (EOQ)	Yes	No	No
[27]	No	Individual	Yes	No	No
[30]	Yes	Individual (EOQ)	Yes	No	No
[31,33-34]	No	Individual (EOQ)	Yes	Completely backlogging	No
[37]	No	Individual (EPQ)	Yes	Partially backlogging	No
[38-39]	No	Individual (EPQ)	Yes	Completely backlogging	No
[46]	Yes	Individual (EPQ)	Yes	Completely backlogging	No
[47]	Yes	Individual (EPQ)	Yes	No	No
[48,61]	Yes	Supply chain	Yes	No	No
[51-53,55-56] [60,63,67-69]	No	Supply chain	No	No	No
[54, 58, 64]	Yes	Supply chain	No	No	No
[57]	No	Supply chain	No	Completely backlogging	No
[59]	No	Supply chain	Yes	No	No
[62, 66]	Yes	Supply chain	Yes	Completely backlogging	No
[65]	Two-part	Supply chain	Yes	No	No
[70]	Two-levels	Supply chain	No	No	No
Present paper	Two-part	Supply chain	Yes	Completely backlogging	Yes

I_c Retailer's capital opportunity cost per dollar in stocks per unit time;

I_p Supplier's interest earned per dollar per unit time when the retailer pays at early time M_1 ;

α Price discount rate offered by the supplier when the retailer pays at time M_1 , where $0 < \alpha < 1$;

Q_d Retailer's order quantity threshold at which shipping cost is absorbed by the supplier;

Q Retailer's order quantity;

B Maximum backlogging level during the stock-out period;

n Number of shipment from the supplier to the retailer per production cycle;

- t Retailer's length of cycle time during which the stock reaches zero;
- T Retailer's length of the replenishment cycle time.

Assumptions

- Similar to the models of Sarkar et al. [48], Sana [63], and Sarkar et al. [71], the production-inventory system considers a single supplier, a single retailer, and single commodity;
- Shortages are allowed for the retailer and all customers are willing to wait for the next delivery (see, for example [31,46]);
- Replenishment rate of the retailer is infinite, and the lead time is assumed to be negligible (this assumption was used by Sarkar et al. [10], El Saadany [41], Sana [68], Sett et al. [72], and so on);
- The retailer orders Q units per order and the supplier produces nQ units per production run and delivers them to the retailer in n shipments, where n is an integer;
- To achieve economies of scale on transportation, the supplier provides the retailer with a freight concession. When the order quantity of retailer Q is greater than or equal to Q_d , then transportation cost is absorbed by the supplier; otherwise, it is paid by the retailer;
- An arriving lot contains some defective items with defective rate λ , and the retailer may perform a 100% inspection to check the product quality before selling it. Defective items in each batch are discovered, stored and then sold to the secondary market in a single batch at the end of each cycle (see, for example, [73]). Hence, the retailer's holding cost includes two parts: non-defective items and defective items;
- To attract procurement from the retailer, the supplier provides the retailer with a two-part trade credit. That is, the supplier allows the retailer to make the payment at time M_2 and provides the retailer with a cash discount and a discount rate α ($0 < \alpha < 1$) if the retailer pays earlier at time M_1 , where $0 \leq M_1 < M_2$;
- During the time when the account has not been settled, the generated sale revenue is deposited in an interest-bearing account at a rate of I_e . At the end of this period ($M_i, i = 1, 2$), the retailer pays the purchasing cost to the supplier and incurs a capital opportunity cost at a rate of I_c for the items in stock;
- When the retailer pays earlier at time M_1 , the supplier may gain an interest earned at a rate of I_p during the time interval M_1, M_2 ;
- The retailer's inspection process is assumed fast, error-free and non-destructive. That is, the inspection time is ignored.

3. Model formulation

Based on the notations and assumptions mentioned above, this section first establishes the total profit functions for the supplier and retailer and, then, makes some appropriate combination of the two to obtain an integrated total profit function.

3.1. Supplier's total profit function

The supplier's total profit per production cycle is the gross profit on sale minus the total relevant cost, which consists of the setup cost, transportation cost, inventory holding cost, opportunity cost for offering trade credit, and interest earned during the time interval $[M_1, M_2]$ if the retailer make the payment at the time M_1 . These components are evaluated as follows:

- Gross profit on sale.* When the retailer pays at time M_i ($i = 1, 2$), the unit wholesale price is $(1 - \delta_i\alpha)v$, where $\delta_1 = 1, \delta_2 = 0$. Because the supplier's unit production cost is c , the supplier's gross profit on sale per production cycle is $n(1 - \delta_i\alpha)v - c]Q$;
- Setup cost.* The supplier's setup cost in a production cycle is K ;
- Transportation cost.* The transportation cost includes fixed and variable costs (see, for example, [74]). Further, if the retailer's order quantity is larger than or equal to specified threshold Q_d , then the transportation cost is absorbed by the supplier; otherwise, the transportation cost is paid by the retailer. Hence, the transportation cost is given by $I_{[Q_d, \infty)}(Q)(F + rQ)$, where $I_{[Q_d, \infty)}(Q)$ is an indicator function and defined as follows:

$$I_{[Q_d, \infty)}(Q) = \begin{cases} 1 & \text{if } Q \geq Q_d \\ 0 & \text{if } Q < Q_d. \end{cases}$$

Therefore, the supplier's transportation cost per production cycle is $nI_{[Q_d, \infty)}(Q)(F + rQ)$;

- Holding cost.* At the beginning, when a quantity of products are produced, the supplier will deliver them to the retailer immediately. After the first shipment, the supplier will schedule successive deliveries in every $(1 - \lambda)Q/D$ unit of time until the inventory level falls to zero. Consequently, the supplier's total inventory quantity per production cycle is equal to its cumulative inventory minus the retailer's cumulative inventory (see Figure 1) and is given by:

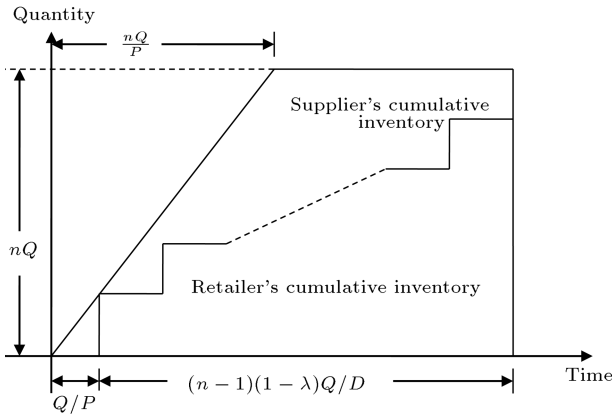


Figure 1. The supplier's inventory system.

$$\begin{aligned}
 & nQ \left[\frac{Q}{p} + \frac{(n-1)(1-\gamma)Q}{D} \right] - \frac{nQ}{2} \cdot \frac{nQ}{P} \\
 & - [1 + 2 + \dots + (n-1)]Q \cdot \frac{(1-\lambda)Q}{D} \\
 & = nQ^2 \left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right].
 \end{aligned}$$

With unit holding cost per unit time, h_v , the supplier's total holding cost per production cycle is as follows:

$$h_v nQ^2 \left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right].$$

Note that a similar derivation in the supplier's total holding cost can be found in the study of Sarkar and Majumder [75];

5. *Opportunity cost.* Because the supplier provides the retailer with a two-part trade credit, which implies that the retailer is allowed to make the payment at time M_i ($i = 1, 2$) after receiving the order quantity, there is an opportunity cost arising for the supplier due to the trade credit. The supplier's opportunity cost per production cycle is $nI_v(1 - \sigma_i\alpha)vQM_i$, where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$;
6. *Interest earned from sale revenue.* If the retailer pays earlier at time M_1 , then the supplier may use sale revenue $(1 - \alpha)vQ$ to gain an interest earned at a rate of I_P during the time interval $[M_1, M_2]$. Hence, when the retailer makes payments at time M_1 , the supplier's interest earned per replenishment cycle during the time interval $[M_1, M_2]$ is $I_p(1 - \alpha)vQ(M_2 - M_1)$. Otherwise, if the retailer pays at time M_2 , then the supplier's interest earned during $[M_1, M_2]$ is zero. Therefore, the supplier's interest earned per production cycle is as follows:

$$n\delta_i I_p(1 - \alpha)vQ(M_2 - M_1),$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$. Consequently,

the supplier's total profit per unit time (denoted by $TPV_i(n)$) is a function of n and can be expressed as follows:

$$\begin{aligned}
 TPV_i(n) &= \frac{1}{nT} \{ \text{gross profit} - \text{setup cost} \\
 & - \text{transportation cost} - \text{holding cost} \\
 & - \text{opportunity cost} + \text{interest earned} \} \\
 &= \frac{1}{T} \left\{ [(1 - \delta_i\alpha)v - c]Q - \frac{K}{n} \right. \\
 & - I_{[Q_d, \infty)}(Q)(F + rQ) - h_v Q^2 \\
 & \left. \left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right] \right. \\
 & - I_v(1 - \delta_i\alpha)vQM_i \\
 & \left. + \delta_i I_p(1 - \alpha)vQ(M_2 - M_1) \right\} \\
 &= \frac{[(1 - \delta_i\alpha)v - c]D}{1 - \lambda} - \frac{K}{nT} - I_{[Q_d, \infty)} \\
 & (Q) \left(\frac{F}{T} + \frac{rD}{1 - \lambda} \right) - \frac{h_v D^2 T}{(1 - \lambda)^2} \\
 & \left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right] \\
 & - \frac{I_v(1 - \delta_i\alpha)vDM_i}{1 - \lambda} \\
 & + \frac{\delta_i I_p(1 - \alpha)vD(M_2 - M_1)}{1 - \lambda}, \tag{1}
 \end{aligned}$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$.

3.2. Retailer's total profit function

With regard to the retailer, its total profit per production cycle is the gross profit on sale minus the total relevant cost, which consists of the ordering cost, transportation cost, inventory holding cost, shortage cost, opportunity cost, and interest earned. These components are evaluated as follows:

1. *Gross profit.* The retailer's sale revenue includes non-detective and defective items which are $p(1 - \lambda)Q = pDT$ and $k\lambda Q = k\lambda DT/(1 - \lambda)$, respectively. In addition, the retailer's total purchasing cost is $(1 - \delta_i\alpha)vQ = (1 - \delta_i\alpha)vDT/(1 - \lambda)$, $i = 1, 2$, and $\delta_1 = 1, \delta_2 = 0$. Hence, the retailer's gross profit per replenishment cycle is:

$$pDT + \frac{k\lambda DT}{1 - \lambda} - \frac{(1 - \delta_i\alpha)vDT}{1 - \lambda},$$

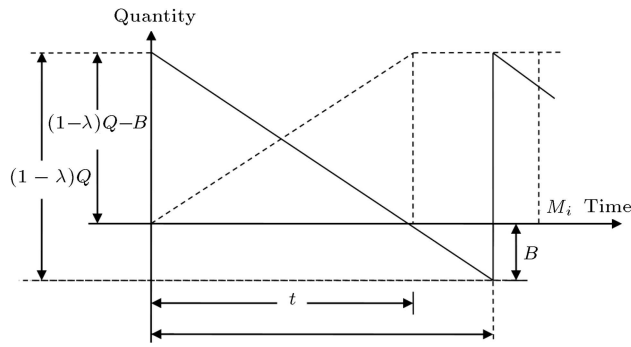


Figure 4. The retailer's inventory system when $t \leq T \leq M_i$ ($i = 1, 2$).

$$+I_e p D(T-t)M_i + I_e k \lambda (M_i - T) \frac{DT}{1-\lambda},$$

where $I_e p B M_i$ is the interest earned due to the revenue from backlogged demand, and $I_e k \lambda Q (M_i - T)$ is the interest earned for sale revenue of defective items. Because the retailer sells out the items (including non-defective and defective items) at time M_i ($i = 1, 2$), in this case, there is no interest charged.

Consequently, the retailer's total profit per unit time (denoted by $TPR_i(T, t)$) can be expressed as follows:

$$\begin{aligned}
 TPR_i(T, t) &= \frac{1}{T} \{ \text{gross profit - ordering cost} \\
 &\quad - \text{transportation cost - holding cost} \\
 &\quad - \text{shortage cost - opportunity cost} \\
 &\quad + \text{interest earned} \} \\
 &= \begin{cases} TPR_{i1}(T, t), & \text{if } M_i \leq t \leq T, \\ TPR_{i2}(T, t), & \text{if } t \leq M_i \leq T, \\ TPR_{i3}(T, t), & \text{if } t \leq T \leq M_i, \end{cases} \quad (2)
 \end{aligned}$$

where $i = 1, 2$,

$$\begin{aligned}
 TPR_{i1}(T, t) &= \frac{1}{T} \left\{ pDT + \frac{k\lambda DT}{1-\lambda} - \frac{(1-\delta_i\alpha)vDT}{1-\lambda} \right. \\
 &\quad - A - [1 - I_{[Q_d, \infty)}(Q)](F + rQ) - \frac{h_{b1}Dt^2}{2} \\
 &\quad - \frac{h_{b2}\lambda DT^2}{1-\lambda} - \frac{\pi D(T-t)^2}{2} - \frac{I_c(1-\delta_i\alpha)vD(t-M_i)^2}{2} \\
 &\quad - \frac{I_c(1-\delta_i\alpha)v\lambda DT(T-M_i)}{1-\lambda} + \frac{I_e p D M_i^2}{2} \\
 &\quad \left. + I_e p D(T-t)M_i \right\} = pD + \frac{k\lambda D}{1-\lambda} - \frac{(1-\delta_i\alpha)vD}{1-\lambda}
 \end{aligned}$$

$$\begin{aligned}
 &- \frac{A}{T} - [1 - I_{[Q_d, \infty)}(Q)] \left(\frac{F}{T} + \frac{rD}{1-\lambda} \right) - \frac{h_{b1}Dt^2}{2T} \\
 &- \frac{h_{b2}\lambda DT}{1-\lambda} - \frac{\pi D}{2} \left(T - 2t + \frac{t^2}{T} \right) \\
 &- \frac{I_c(1-\delta_i\alpha)vD(t-M_i)^2}{2T} \\
 &- \frac{I_c(1-\delta_i\alpha)v\lambda D(T-M_i)}{1-\lambda} + \frac{I_e p D M_i^2}{2T} \\
 &+ I_e p D M_i \left(1 - \frac{t}{T} \right), \quad (3)
 \end{aligned}$$

$$\begin{aligned}
 TPR_{i2}(T, t) &= \frac{1}{T} \left\{ pDT + \frac{k\lambda DT}{1-\lambda} \right. \\
 &\quad - \frac{(1-\delta_i\alpha)vDT}{1-\lambda} - A - [1 - I_{[Q_d, \infty)}(Q)] \\
 &\quad (F + rQ) - \frac{h_{b1}Dt^2}{2} - \frac{h_{b2}\lambda DT^2}{1-\lambda} - \frac{\pi D(T-t)^2}{2} \\
 &\quad - \frac{I_c(1-\delta_i\alpha)v\lambda DT(T-M_i)}{1-\lambda} \\
 &\quad \left. + I_e p Dt \left(M_i - \frac{t}{2} \right) + I_e p D(T-t)M_i \right\} \\
 &= pD + \frac{k\lambda D}{1-\lambda} - \frac{(1-\delta_i\alpha)vD}{1-\lambda} \\
 &\quad - \frac{A}{T} - [1 - I_{[Q_d, \infty)}(Q)] \left(\frac{F}{T} + \frac{rD}{1-\lambda} \right) \\
 &\quad - \frac{h_{b1}Dt^2}{2T} - \frac{h_{b2}\lambda DT}{1-\lambda} - \frac{\pi D}{2} \left(T - 2t + \frac{t^2}{T} \right) \\
 &\quad - \frac{I_c(1-\delta_i\alpha)v\lambda D(T-M_i)}{1-\lambda} \\
 &\quad + \frac{I_e p Dt}{T} \left(M_i - \frac{t}{2} \right) + I_e p D M_i \left(1 - \frac{t}{T} \right), \quad (4)
 \end{aligned}$$

$$\begin{aligned}
 TPR_{i3}(T, t) &= \frac{1}{T} \left\{ pDT + \frac{k\lambda DT}{1-\lambda} \right. \\
 &\quad - \frac{(1-\delta_i\alpha)vDT}{1-\lambda} - A - [1 - I_{[Q_d, \infty)}(Q)] \\
 &\quad (F + rQ) - \frac{h_{b1}Dt^2}{2} - \frac{h_{b2}\lambda DT^2}{1-\lambda} \\
 &\quad - \frac{\pi D(T-t)^2}{2} - I_e p Dt \left(M_i - \frac{t}{2} \right)
 \end{aligned}$$

$$\begin{aligned}
 &+ I_e p D M_i (T - t) + \frac{I_e k \lambda D T (M_i - T)}{1 - \lambda} \Big\} \\
 &= p D + \frac{k \lambda D}{1 - \lambda} - \frac{(1 - \delta_i \alpha) v D}{1 - \lambda} \\
 &- \frac{A}{T} - [1 - I_{[Q_d, \infty)}(Q)] \left(\frac{F}{T} + \frac{r D}{1 - \lambda} \right) \\
 &- \frac{h_{b_1} D t^2}{2 T} - \frac{h_{b_2} \lambda D T}{1 - \lambda} - \frac{\pi D}{2} \left(T - 2 t + \frac{t^2}{T} \right) \\
 &+ \frac{I_e p D t}{T} \left(M_i - \frac{t}{2} \right) + I_e p D M_i \left(1 - \frac{t}{T} \right) \\
 &+ \frac{I_e k \lambda D (M_i - T)}{1 - \lambda}, \tag{5}
 \end{aligned}$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$.

3.3. The integrated total profit function

When the supplier and retailer are treated as an integrated supply chain system and decide to share resources with each other to undertake mutually beneficial cooperation, the joint total profit per unit time can be obtained as the sum of the supplier and retailer's total profit per unit time and is a function of n, T and t as follows:

$$\begin{aligned}
 JTP_i(n, T, t) &= TPV_i(n) + TPR_i(T, t) \\
 &= \begin{cases} JTP_{i1}(n, T, t), & \text{if } M_i \leq t \leq T, \\ JTP_{i2}(n, T, t), & \text{if } t \leq M_i \leq T, \\ JTP_{i3}(n, T, t), & \text{if } t \leq T \leq M_i, \end{cases} \tag{6}
 \end{aligned}$$

where:

$$\begin{aligned}
 JTP_{i1}(n, T, t) &= TPV_i(n) + TPR_{i1}(T, t) \\
 &= p D + \frac{(k \lambda - c - r) D}{1 - \lambda} - \frac{A + F}{T} - \frac{K}{n T} \\
 &- \frac{h_v D^2 T}{(1 - \lambda)^2} \left[\frac{1}{P} + \frac{(n - 1)(1 - \lambda)}{2 D} - \frac{n}{2 P} \right] \\
 &- \frac{I_v (1 - \delta_i \alpha) v D M_i}{1 - \lambda} \\
 &+ \frac{\delta_i I_p (1 - \alpha) v D (M_2 - M_1)}{1 - \lambda} \\
 &- \frac{h_{b_1} D t^2}{2 T} - \frac{h_{b_2} \lambda D T}{1 - \lambda} - \frac{\pi D}{2} \left(T - 2 t + \frac{t^2}{T} \right) \\
 &- \frac{I_c (1 - \delta_i \alpha) v D (t - M_i)^2}{2 T}
 \end{aligned}$$

$$\begin{aligned}
 &- \frac{I_c (1 - \delta_i \alpha) v \lambda D (T - M_i)}{1 - \lambda} + \frac{I_e p D M_i^2}{2 T} \\
 &+ I_e p D M_i \left(1 - \frac{t}{T} \right), \tag{7}
 \end{aligned}$$

$$\begin{aligned}
 JTP_{i2}(n, T, t) &= TPV_i(n) + TPR_{i2}(T, t) \\
 &= p D + \frac{(k \lambda - c - r) D}{1 - \lambda} - \frac{A + F}{T} - \frac{K}{n T} \\
 &- \frac{h_v D^2 T}{(1 - \lambda)^2} \left[\frac{1}{P} + \frac{(n - 1)(1 - \lambda)}{2 D} - \frac{n}{2 P} \right] \\
 &- \frac{I_v (1 - \delta_i \alpha) v D M_i}{1 - \lambda} + \frac{\delta_i I_p (1 - \alpha) v D (M_2 - M_1)}{1 - \lambda} \\
 &- \frac{h_{b_1} D t^2}{2 T} - \frac{h_{b_2} \lambda D T}{1 - \lambda} - \frac{\pi D}{2} \left(T - 2 t + \frac{t^2}{T} \right) \\
 &- \frac{I_c (1 - \delta_i \alpha) v \lambda D (T - M_i)}{1 - \lambda} \\
 &+ \frac{I_e p D t}{T} \left(M_i - \frac{t}{2} \right) + I_e p D M_i \left(1 - \frac{t}{T} \right), \tag{8}
 \end{aligned}$$

$$\begin{aligned}
 JTP_{i3}(n, T, t) &= TPV_i(n) + TPR_{i3}(T, t) \\
 &= p D + \frac{(k \lambda - c - r) D}{1 - \lambda} - \frac{A + F}{T} - \frac{K}{n T} \\
 &- \frac{h_v D^2 T}{(1 - \lambda)^2} \left[\frac{1}{P} + \frac{(n - 1)(1 - \lambda)}{2 D} - \frac{n}{2 P} \right] \\
 &- \frac{I_v (1 - \delta_i \alpha) v D M_i}{1 - \lambda} \\
 &+ \frac{\delta_i I_p (1 - \alpha) v D (M_2 - M_1)}{1 - \lambda} \\
 &- \frac{h_{b_1} D t^2}{2 T} - \frac{h_{b_2} \lambda D T}{1 - \lambda} - \frac{\pi D}{2} \left(T - 2 t + \frac{t^2}{T} \right) \\
 &+ \frac{I_e p D t}{T} \left(M_i - \frac{t}{2} \right) + I_e p D M_i \left(1 - \frac{t}{T} \right) \\
 &+ \frac{I_e k \lambda D (M_i - T)}{1 - \lambda}, \\
 &i = 1, 2, \quad \delta_1 = 1, \quad \delta_2 = 0. \tag{9}
 \end{aligned}$$

In the following, our purpose here is to determine the optimal replenishment cycle length, T , the length of time during which the stock reaches zero, t , and the optimal number of shipments per production run from the supplier to the retailer, n , which maximizes the joint total profit per unit time, $JTP_i(n, T, t), i = 1, 2$.

4. Solution procedure

Firstly, for fixed M_i ($i = 1, 2$) and any given (T, t) , we temporarily relax the integer requirement on n and take the second partial derivative of $JTP_i(n, T, t)$ with respect to n , which gives:

$$\frac{\partial^2 JTP_i(n, T, t)}{\partial n^2} = \frac{\partial^2 JTP_{ij}(n, T, t)}{\partial n^2} = \frac{-2K}{n^3 T} < 0, \quad j = 1, 2, 3. \quad (10)$$

It is obvious that for any given (T, t) , $JTP_i(n, T, t)$ is concave function in n , where $i = 1, 2$. Hence, searching for the optimal solution of n is reduced to finding a local optimal solution. Next, for fixed M_i ($i = 1, 2$) and n , we will discuss how to find the optimal solution (T, t) . There are three cases arising as follows: (i) $M_i \leq t \leq T$, (ii) $t \leq M_i \leq T$, and (iii) $t \leq T \leq M_i$.

Case 1: $M_i \leq t \leq T$ ($i = 1, 2$). Taking the first and second partial derivatives of $JTP_{i1}(n, T, t)$ with respect to T and t , respectively, yields:

$$\begin{aligned} \frac{\partial JTP_{i1}(n, T, t)}{\partial T} &= \frac{n(A+F)+K}{nT^2} - \frac{h_v D^2}{(1-\lambda)^2} \\ &\left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right] + \frac{(h_{b1} + \pi + I_e p)Dt^2}{2T^2} \\ &- \frac{\pi D}{2} - \frac{[h_{b2} + I_c(1-\delta_i\alpha)v]\lambda D}{1-\lambda} \\ &+ \frac{[I_c(1-\delta_i\alpha)v - I_e p]D(t-M_i)^2}{2T^2}, \quad (11) \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T^2} &= \frac{-2[n(A+F)+K]}{nT^3} \\ &- \frac{(h_{b1} + \pi + I_e p)Dt^2 + [I_c(1-\delta_i\alpha)v - I_e p]D(t-M_i)^2}{T^3} \\ &\leq \frac{-2[n(A+F)+K]}{nT^3} \\ &- \frac{(h_{b1} + \pi)Dt^2 + I_c(1-\delta_i\alpha)vD(t-M_i)^2}{T^3} < 0, \quad (12) \end{aligned}$$

$$\begin{aligned} \frac{\partial JTP_{i1}(n, T, t)}{\partial t} &= -\frac{h_{b1}Dt}{T} + \pi D \left(1 - \frac{t}{T}\right) \\ &- \frac{I_c(1-\delta_i\alpha)vD(t-M_i)}{T} - \frac{I_e pDM_i}{T}, \quad (13) \end{aligned}$$

$$\frac{\partial^2 JTP_{i1}(n, T, t)}{\partial t^2} = -\frac{[h_{b1} + \pi + I_c(1-\delta_i\alpha)v]D}{T} < 0, \quad (14)$$

$$\begin{aligned} \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T \partial t} &= \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial t \partial T} \\ &= \frac{D[(h_{b1} + \pi)t + I_e pM_i + I_c(1-\delta_i\alpha)v(t-M_i)]}{T^2}. \quad (15) \end{aligned}$$

Based on Eqs. (12), (14), and (15), the determinant of Hessian matrix is:

$$\begin{aligned} J_{i1} &= \begin{vmatrix} \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T^2} & \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T \partial t} \\ \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial t \partial T} & \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial t^2} \end{vmatrix} \\ &= \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T^2} \times \frac{\partial^2 JTP_{i1}(n, T, t)}{\partial t^2} \\ &- \left[\frac{\partial^2 JTP_{i1}(n, T, t)}{\partial T \partial t} \right]^2 \\ &= \frac{2D[n(A+F)+K][h_{b1} + \pi + I_c(1-\delta_i\alpha)v]}{nT^4} \\ &+ \frac{D^2 M_i^2 [I_c(1-\delta_i\alpha)v - I_e p](h_{b1} + \pi + I_e p)}{T^4}, \quad (16) \end{aligned}$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$.

Therefore, the following result can be obtained from Eqs. (12), (14), and (16).

Theorem 1. For given M_i ($i = 1, 2$) and n , if $J_{i1} > 0$, then $JTP_{i1}(n, T, t)$ has a maximum value at point $(T, t) = (T_{i1}, t_{i1})$ which satisfies $\partial JTP_{i1}(n, T, t)/\partial T = 0$ and $\partial JTP_{i1}(n, T, t)/\partial t = 0$.

Case 2: $t \leq M_i \leq T$ ($i = 1, 2$). Similarly, taking the first and second partial derivatives of $JTP_{i2}(n, T, t)$ with respect to T and t , respectively, yields:

$$\begin{aligned} \frac{\partial JTP_{i2}(n, T, t)}{\partial T} &= \frac{n(A+F)+K}{nT^2} - \frac{h_v D^2}{(1-\lambda)^2} \\ &\left[\frac{1}{P} + \frac{(n-1)(1-\lambda)}{2D} - \frac{n}{2P} \right] + \frac{h_{b1} + \pi + I_e p}{2T^2} Dt^2 \\ &- \frac{\pi D}{2} - \frac{[h_{b2} + I_c(1-\delta_i\alpha)v]\lambda D}{1-\lambda}, \quad (17) \end{aligned}$$

$$\begin{aligned} \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T^2} &= \frac{-2[n(A+F)+K]}{nT^3} \\ &- \frac{(h_{b1} + \pi + I_e p)Dt^2}{T^3} < 0, \quad (18) \end{aligned}$$

$$\frac{\partial JTP_{i2}(n, T, t)}{\partial t} = -\frac{(h_{b1} + \pi + I_e p)Dt}{T} + \pi D, \quad (19)$$

$$\frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t^2} = -\frac{(h_{b1} + \pi + I_e p)D}{T} < 0, \quad (20)$$

$$\begin{aligned} \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T \partial t} &= \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t \partial T} \\ &= \frac{(h_{b1} + \pi + I_e p)Dt}{T^2}. \end{aligned} \quad (21)$$

Based on Eqs. (18), (20), and (21), the determinant of Hessian matrix is:

$$\begin{aligned} J_{i2} &= \begin{vmatrix} \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T^2} & \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T \partial t} \\ \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t \partial T} & \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t^2} \end{vmatrix} \\ &= \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T^2} \times \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t^2} \\ &\quad - \left[\frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T \partial t} \right]^2 \\ &= \frac{2D[n(A + F) + K](h_{b1} + \pi + I_e p)}{nT^4} > 0, \end{aligned} \quad (22)$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$.

Therefore, the following result can be found from Eqs. (18), (20), and (22).

Theorem 2. For given M_i ($i = 1, 2$) and n , $JTP_{i2}(n, T, t)$ has a maximum value at point $(T, t) = (T_{i2}, t_{i2})$ which satisfies $\partial JTP_{i2}(n, T, t)/\partial T = 0$ and $\partial JTP_{i2}(n, T, t)/\partial t = 0$.

Case 3: $t \leq T \leq M_i$ ($i = 1, 2$). Taking the first and second partial derivatives of $JTP_{i3}(n, T, t)$ with respect to T and t , respectively, yields:

$$\begin{aligned} \frac{\partial JTP_{i1}(n, T, t)}{\partial T} &= \frac{n(A + F) + K}{nT^2} - \frac{h_v D^2}{(1 - \lambda)^2} \\ &\quad \left[\frac{1}{P} + \frac{(n - 1)(1 - \lambda)}{2D} - \frac{n}{2P} \right] + \frac{h_{b1} + \pi + I_e p)Dt^2}{2T^2} \\ &\quad - \frac{\pi D}{2} - \frac{(h_{b2} + I_e k)\lambda D}{1 - \lambda}, \end{aligned} \quad (23)$$

$$\begin{aligned} \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial T^2} &= \frac{-2[n(A + F) + K]}{nT^3} \\ &\quad - \frac{(h_{b1} + \pi + I_e p)Dt^2}{T^3} < 0, \end{aligned} \quad (24)$$

$$\frac{\partial JTP_{i3}(n, T, t)}{\partial t} = -\frac{(h_{b1} + \pi + I_e p)Dt}{T} + \pi D, \quad (25)$$

$$\frac{\partial^2 JTP_{i3}(n, T, t)}{\partial t^2} = -\frac{(h_{b1} + \pi + I_e p)D}{T} < 0, \quad (26)$$

$$\begin{aligned} \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial T \partial t} &= \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial t \partial T} \\ &= \frac{(h_{b1} + \pi + I_e p)Dt}{T^2}. \end{aligned} \quad (27)$$

Based on Eqs. (24), (26), and (27), the determinant of Hessian matrix is:

$$\begin{aligned} J_{i3} &= \begin{vmatrix} \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial T^2} & \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial T \partial t} \\ \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial t \partial T} & \frac{\partial^2 JTP_{i3}(n, T, t)}{\partial t^2} \end{vmatrix} \\ &= \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T^2} \times \frac{\partial^2 JTP_{i2}(n, T, t)}{\partial t^2} \\ &\quad - \left[\frac{\partial^2 JTP_{i2}(n, T, t)}{\partial T \partial t} \right]^2 \\ &= \frac{2D[n(A + F) + K](h_{b1} + \pi + I_e p)}{nT^4} > 0, \end{aligned} \quad (28)$$

where $i = 1, 2$ and $\delta_1 = 1, \delta_2 = 0$.

Therefore, the following result can be obtained from Eqs. (24), (26), and (28).

Theorem 3. For given M_i ($i = 1, 2$) and n , $JTP_{i3}(n, T, t)$ has a maximum value at point $(T, t) = (T_{i3}, t_{i3})$ which satisfies $\partial JTP_{i3}(n, T, t)/\partial T = 0$ and $\partial JTP_{i3}(n, T, t)/\partial t = 0$.

By combining the above-mentioned results, the following algorithm can be developed to find the optimal solution (n^*, T^*, t^*) .

Algorithm

Step 1. Set $n = 1$.

Step 2. For given n and M_i , $i = 1, 2$.

Step 2-1. When J_{i1} defined in Eq. (16) is greater than zero, find T_{i1} and t_{i1} by setting Eqs. (11) and (13) equal to zero and, then, compare them with M_i , where $i = 1, 2$. If $M_i \leq t_{i1} \leq T_{i1}$, then calculate the corresponding joint total profit per unit time $JTP_1(n, T_{i1}, t_{i1})$ from Eq. (7). Otherwise, set $JTP_1(n, T_{i1}, t_{i1}) = 0$.

Step 2-2. Find T_{i2} and t_{i2} by setting Eqs. (17) and (19) equal to zero and, then, compare them with M_i , where $i = 1, 2$. If $t_{i2} \leq M_i \leq T_{i2}$, then calculate the corresponding joint total profit per unit time $JTP_2(n, T_{i2}, t_{i2})$ from Eq. (8). Otherwise, set $JTP_2(n, T_{i2}, t_{i2}) = 0$.

Step 2-3. Find T_{i3} and t_{i3} by setting Eqs. (23) and (25) equal to zero and, then, compare them with M_i , where $i = 1, 2$. If $t_{i3} \leq T_{i3} \leq M_i$, then calculate the corresponding joint total profit per unit time $JTP_3(n, T_{i3}, t_{i3})$ from Eq. (9). Otherwise, set $JTP_3(n, T_{i3}, t_{i3}) = 0$.

Step 2-4. Find $\max_{i=1,2; j=1,2,3} JTP_j(n, T_{ij}, t_{ij})$ and let:

$$JTP(n, T(n), t(n)) = \max_{i=1,2; j=1,2,3} JTP_j(n, T_{ij}, t_{ij}).$$

Step 3. Set $n = n + 1$, and repeat Steps 2-1 to 2-4 to get $JTP(n, T_{(n)}, t_{(n)})$.

Step 4. If:

$$JTP(n, T_{(n)}, t_{(n)}) < JTP(n-1, T_{(n-1)}, t_{(n-1)}),$$

then:

$$JTP(n^*, T^*, t^*) = JTP(n-1, T_{(n-1)}, t_{(n-1)}).$$

Hence:

$$(n^*, T^*, t^*) = (n-1, T_{(n-1)}, t_{(n-1)}),$$

is the optimal solution. Otherwise, return to Step 3.

5. Numerical examples

Example 1. To illustrate the solution procedure, an inventory system with the following data is considered:

- $P = 4500$ units/year;
- $D = 2000$ units/year;
- $K = \$300$ /setup;
- $A = \$50$ /order;
- $F = \$30$ /shipment;
- $r = \$0.01$ /unit;
- $h_v = \$1.5$ /unit/year;
- $h_{b_1} = \$2$ /unit/year;
- $h_{b_2} = \$1.8$ /unit/year;
- $\pi = \$3$ /unit/year;
- $c = \$10$ /unit;
- $v = \$20$ /unit;
- $p = \$40$ /unit;
- $k = \$10$ /unit;
- $\lambda = 0.03$;
- $I_v = 0.05$ /dollar/year;
- $I_e = 0.03$ /dollar/year;
- $I_c = 0.05$ /dollar/year;
- $M_1 = 30/365$ years;
- $M_2 = 60/365$ years;
- $\alpha = 0.01$;
- $I_p = 0.03$ /dollar/year;
- $Q_d = 500$ units.

By applying the algorithm of Section 4, the solution procedure is shown in Table 2. According to Table 2, the optimal solution is $(n^*, T^*, t^*) = (3, 0.2119, 0.1063)$. Therefore, the retailer's optimal ordering quantity is $Q^* = DT^*/(1 - \lambda) = 436.827$ units, the supplier's optimal production quantity is

Table 2. The solution process of Example 1.

n	t^*	T^*	$JTP(n, T^*, t^*)$
1	$t_{11} = 0.2133$	$T_{11} = 0.4066$	58221.2
2	$t_{11} = 0.1398$	$T_{11} = 0.2713$	58390.0
3	$t_{11} = 0.1063$	$T_{11} = 0.2119$	58397.5 ←
4	$t_{11} = 0.0866$	$T_{11} = 0.1775$	58364.0

Note: "←" denotes the optimal solution of the system.

$n^*Q^* = 1310.48$ units, and optimal joint total profit is $JTP(n^*, T^*, t^*) = \$58397.5$. In this situation, due to the retailer's optimal quantity $Q^* = 436.827 < Q_d = 500$, the transportation cost is paid by the retailer. In addition, the retailer's optimal payment policy is to make payments at $M_1 = 30/365$ years to enjoy the benefit of cash discount when the supplier provides a two-part trade credit.

Example 2. Using the same data as in Example 1, we study the effects of changes in the retailer's interest earned rate, $I_e \in \{0.03, 0.04, 0.05\}$, and interest charged rate, $I_c \in \{0.03, 0.04, 0.05\}$, on the optimal solutions. The computational results are shown in Table 3. Based on the numerical results of Table 3, the retailer's payment policy is dependent on its interest earned. When the retailer's interest earned rate exceeds a certain threshold (for example, $I_e = 0.05$ in Table 3), he/she will pay at time M_2 to enjoy the benefit of permissible delay in payments. Otherwise, the retailer will pay at early time M_1 to take the price discount instead. Furthermore, to enjoy the benefit of trade credit repeatedly, the retailer may order fewer quantities caused by shorter replenishment cycle as the retailer's interest earned rate, I_e , increases; hence, the joint total profit increases. On the other hand, the retailer's interest charged rate, I_c , has a negative impact on the retailer's optimal ordering quantity, supplier's production quantity, and the joint total profit. This is because the retailer may reduce the order quantity to avoid backlog capital when his/her interest charged rate increases. With the fixed numbers of deliveries, the production quantity will reduce. Hence, the decreasing joint total profit will ensue.

Example 3. In order to understand the impacts of the lengths of trade credit M_i and discount rate α on optimal solutions, the same data as in Example 1 are used, except $M_1 \in \{15/365, 30/365, 45/365\}$, $M_2 \in \{60/365, 90/365, 120/365\}$, and $\alpha \in \{0.05, 0.01, 0.015\}$. The computational results are shown in Table 4. According to Table 4, although the effect of the discount rate on the optimal solutions is weak, it has different impacts on the joint total profit in different lengths of trade credit, M_1 . When the length of trade credit of M_1 is low (for example, $M_1 = 15/365$ in Table 4), the joint total profit decreases as the

Table 3. Optimal solutions for various values of retailer's interest earned and charged.

I_c	I_e	t^*	T^*	n^*	Q^*	n^*Q^*	$JTP(n^*, T^*, t^*)$
0.03	0.03	$t_{11} = 0.1073$	$T_{11} = 0.2129$	3	438.891	1316.67	58400.9
	0.04	$t_{11} = 0.0995$	$T_{11} = 0.2104$	3	433.746	1301.24	58447.3
	0.05	$t_{22} = 0.0883$	$T_{22} = 0.2059$	3	424.477	1273.43	58555.4
0.04	0.03	$t_{11} = 0.1068$	$T_{11} = 0.2124$	3	437.849	1313.55	58399.2
	0.04	$t_{11} = 0.0991$	$T_{11} = 0.2099$	3	432.819	1298.46	58445.7
	0.05	$t_{22} = 0.0883$	$T_{22} = 0.2056$	3	423.860	1271.58	58554.9
0.05	0.03	$t_{11} = 0.1063$	$T_{11} = 0.2119$	3	436.827	1310.48	58397.5
	0.04	$t_{11} = 0.0987$	$T_{11} = 0.2095$	3	431.908	1295.72	58444.1
	0.05	$t_{22} = 0.0883$	$T_{22} = 0.2053$	3	423.246	1269.74	58554.4

Table 4. Optimal solutions under various values of α , M_1 and M_2 .

α	M_2	M_1	t^*	T^*	Q^*	n^*Q^*	$JTP(n^*, T^*, t^*)$
0.005	60/365	15/365	$t_{11} = 0.115712$	$T_{11} = 0.214772$	442.828	1328.48	58449.5
		30/365	$t_{11} = 0.106334$	$T_{11} = 0.211849$	436.802	1310.41	58397.1
		45/365	$t_{12} = 0.101317$	$T_{12} = 0.209388$	431.728	1295.19	58361.2
	90.365	15/365	$t_{11} = 0.115712$	$T_{11} = 0.214772$	442.828	1328.48	58550.7
		30/365	$t_{11} = 0.106334$	$T_{11} = 0.211849$	436.802	1310.41	58498.3
		45/365	$t_{12} = 0.101317$	$T_{12} = 0.209388$	431.728	1295.19	58462.4
	120.365	15/365	$t_{11} = 0.115712$	$T_{11} = 0.214772$	442.828	1328.48	58651.9
		30/365	$t_{11} = 0.106334$	$T_{11} = 0.211849$	436.802	1310.41	58599.5
		45/365	$t_{12} = 0.101317$	$T_{12} = 0.209388$	431.728	1295.19	58563.6
0.01	60/365	15/365	$t_{11} = 0.115739$	$T_{11} = 0.214792$	442.870	1328.61	58449.3
		30/365	$t_{11} = 0.116346$	$T_{11} = 0.211861$	436.827	1310.48	58397.3
		45/365	$t_{12} = 0.101321$	$T_{12} = 0.209396$	431.745	1295.23	58362.3
	90.365	15/365	$t_{11} = 0.115739$	$T_{11} = 0.214792$	442.87	1328.61	58549.9
		30/365	$t_{11} = 0.106346$	$T_{11} = 0.211861$	436.827	1310.48	58498.2
		45/365	$t_{12} = 0.101321$	$T_{12} = 0.209396$	431.745	1295.23	58462.9
	120.365	15/365	$t_{11} = 0.115739$	$T_{11} = 0.214792$	442.87	1328.61	58650.6
		30/365	$t_{11} = 0.106346$	$T_{11} = 0.211861$	436.827	1310.48	58598.8
		45/365	$t_{12} = 0.101321$	$T_{12} = 0.209396$	431.745	1295.23	58563.6
0.015	60/365	15/365	$t_{11} = 0.115767$	$T_{11} = 0.214812$	442.912	1328.73	58449.0
		30/365	$t_{11} = 0.106358$	$T_{11} = 0.211874$	436.853	1310.56	58397.9
		45/365	$t_{12} = 0.101325$	$T_{12} = 0.209404$	431.761	1295.28	58363.3
	90.365	15/365	$t_{11} = 0.115767$	$T_{11} = 0.214812$	442.912	1328.73	58549.2
		30/365	$t_{11} = 0.106358$	$T_{11} = 0.211874$	436.853	1310.56	58498.0
		45/365	$t_{12} = 0.101325$	$T_{12} = 0.209404$	431.761	1295.28	58463.5
	120.365	15/365	$t_{11} = 0.115767$	$T_{11} = 0.214812$	442.912	1328.73	58649.3
		30/365	$t_{11} = 0.106358$	$T_{11} = 0.211874$	436.853	1310.56	58598.2
		45/365	$t_{12} = 0.101325$	$T_{12} = 0.209404$	431.761	1295.28	58563.6

discount rate increases. Otherwise, if the length of trade credit of M_1 is large enough, the joint total profit increases as the discount rate increases. In addition, for the given values of α and M_1 , the length of trade credit of M_2 has no effect on the retailer and the supplier's optimal ordering and production policies since the optimal retailer's payment policy is payment at time M_1 ; however, the joint total profit increases when M_2 increases, implying an increase in the supplier's interest earned. Finally, for given values of α and M_2 , when the length of trade credit of M_1 increases, the retailer will pay at time M_1 to take the price discount and order less quantities to enjoy the benefit of trade credit repeatedly. However, the joint total profit of the supply chain system decreases as M_1 increases.

Example 4. In this example, we study the effects of changes in other parameters P , D , K , A , F , r , π , h_v , h_{hb_1} , h_{hb_2} , C , v , p , k , λ , I_v , I_p , and Q_d on the optimal solutions. The data in this example are identical to those in Example 1. The results of the comparison are shown in Table 5. Based on the results shown in Table 5, the following observations can be made:

- (a) When production rate P , the holding cost parameters of h_v , h_{b_1} , h_{b_2} or the retailer's wholesale price v increase, all the retailer's length of cycle time, during which the stock reaches zero t^* , the retailer's length of cycle time T^* , retailer order quantity Q^* , supplier production quantity n^*Q^* , and joint total profit $JTP(n^*, T^*, t^*)$ decrease;
- (b) As for the impact of the value of D or λ on the optimal solutions and joint total profit, the values of t^* and T^* decrease, yet Q^* and n^*Q^* increase when the value of D or λ increases. From the economic point of view, the retailer will order more and the supplier will produce more in response to increased demand rate or defective rate. While the demand rate has a positive effect, defective rate has a negative effect on the joint total profit;
- (c) The value of K , A or F has positive effect on the retailer's and the supplier solutions; however, they have negative effect on the joint total profit of the supply chain system. It is very intuitive of the retailer and supplier to, respectively, order and produce more as the costs such as setup cost, ordering cost, and fixed transportation cost increase. Thus, of course, the joint total profit will reduce;
- (d) Although the optimal solutions are not affected by the values of r , c , k , I_v or I_p , the joint total profit increases with a decrease in the values of r , c , or I_v , yet increases in the value of k or I_p . It is obvious that the retailer's order quantity does not affect

the parameters related to the supplier. Further, we find the number of shipments too rigid for changes in the supplier's parameters since the number must be an integer;

- (e) As the value of π increases, the value of t^* increases; however, the values of T^* , Q^* , n^*Q^* , and $JTP(n^*, T^*, t^*)$ decrease. This numerical result is also very intuitive because the retailer will try to avoid stockouts when the shortage cost increases;
- (f) The values of t^* , T^* , Q^* , and n^*Q^* decrease, while $JTP(n^*, T^*, t^*)$ increases with the increase of the value of p , because the retailer may order fewer quantities caused by shorter replenishment cycle as the retailer's selling price increases (implying the interest earned increases) to enjoy the benefit of trade credit repeatedly; hence, the joint total profit increases;
- (g) Although the optimal solutions and joint total profit are not affected by the value of Q_d , it is beneficial for the retailer when the order quantity threshold at which shipping cost is absorbed by the supplier is low (for example, $Q_d = 400 < Q^* = 436.827$ in Table 5).

6. Conclusion

Although the inventory-related literatures with trade credit have been widely published, few literatures have considered supply chain inventory model. Moreover, no previous studies have discussed the issue of the freight concession that could effectively promote the order quantity. Therefore, this study investigated an integrated supplier-retailer production and inventory model where the following issues were taken into account simultaneously: (1) The supplier provides a two-part trade credit which allows the retailer to either make full payments at a certain time or pay earlier with a cash discount, (2) The retailer can enjoy a freight concession if the order quantity is over the specified threshold, (3) The retailer's arriving lot contains defective items, and (4) Shortages are allowed for the retailer and completely backlogged. To make the model more rigorous, three theorems were proposed to ensure the existence and uniqueness of the optimal solutions; then, an algorithm was provided to reveal the optimal solutions. Furthermore, numerical examples demonstrating the solution procedures and a sensitivity analysis of the optimal solutions with respect to all parameters were presented. The numerical results yielded several main management insights: (1) When the supplier provides a two-part trade credit, the retailer may order fewer quantities caused by shorter replenishment cycle to enjoy the benefit of trade credit repeatedly. Further, if the retailer's interest earned exceeds a certain threshold (e.g., $I_e \geq 0.05$, Example

Table 5. Optimal solutions under different parametric values.

Parameters	Value	t^*	T^*	Q^*	n^*Q^*	$JTP(n^*, T^*, t^*)$
P	4400	0.1066	0.2123	437.741	1313.22	58400.9
	4500	0.1063	0.2119	436.827	1310.48	58397.5
	4600	0.1061	0.2114	435.958	1307.87	58394.2
D	1950	0.1077	0.2142	430.554	1291.66	56912.8
	2000	0.1063	0.2119	436.827	1310.48	58397.5
	2050	0.1051	0.2096	443.055	1329.16	59882.6
K	275	0.1034	0.2067	426.184	1278.55	58437.3
	300	0.1063	0.2119	436.827	1310.48	58397.5
	325	0.1092	0.2169	447.203	1341.61	58358.6
A	45	0.1046	0.2088	430.475	1291.42	58421.3
	50	0.1063	0.2119	436.827	1310.48	58397.5
	55	0.1081	0.2149	443.084	1329.25	58374.1
F	25	0.1046	0.2088	430.475	1291.42	58421.3
	30	0.1063	0.2119	436.827	1310.48	58397.5
	35	0.1081	0.2149	443.084	1329.25	58374.1
r	0.009	0.1063	0.2119	436.827	1310.48	58399.6
	0.01	0.1063	0.2119	436.827	1310.48	58397.5
	0.011	0.1063	0.2119	436.827	1310.48	58395.4
π	2.75	0.1018	0.2132	439.522	1318.56	58411.3
	3	0.1063	0.2119	436.827	1310.48	58397.5
	3.25	0.1105	0.2107	434.417	1303.25	58385.0
h_v	1.4	0.1089	0.2164	446.104	1338.31	58431.5
	1.5	0.1063	0.2119	436.827	1310.48	58397.5
	1.6	0.1039	0.2076	428.096	1284.29	58364.2
h_{b1}	1.95	0.1076	0.2123	437.746	1313.24	58400.2
	2	0.1063	0.2119	436.827	1310.48	58397.5
	2.05	0.1051	0.2114	435.931	1307.79	58394.9
h_{b2}	1.75	0.1064	0.2119	437.002	1311.01	58398.2
	1.8	0.1063	0.2119	436.827	1310.48	58397.5
	1.85	0.1063	0.2118	436.652	1309.96	58396.8
c	9.5	0.1063	0.2119	436.827	1310.48	59428.4
	10	0.1063	0.2119	436.827	1310.48	58397.5
	10.5	0.1063	0.2119	436.827	1310.48	57366.6
v	18	0.1066	0.2121	437.335	1312.01	58405.1
	20	0.1063	0.2119	436.827	1310.48	58397.5
	22	0.1061	0.2116	436.324	1308.97	58389.9
p	38	0.1075	0.2122	437.512	1312.53	54390.7
	40	0.1063	0.2119	436.827	1310.48	58397.5
	42	0.1052	0.2115	436.129	1308.39	62404.3

Table 5. Optimal solutions under different parametric values (continued).

Parameters	Value	t^*	T^*	Q^*	n^*Q^*	$JTP(n^*, T^*, t^*)$
k	9	0.1063	0.2119	436.827	1310.48	58335.6
	10	0.1063	0.2119	436.827	1310.48	58397.5
	11	0.1063	0.2119	436.827	1310.48	58459.4
λ	0.02	0.1076	0.2140	436.699	1310.10	58412.8
	0.03	0.1063	0.2119	436.827	1310.48	58397.5
	0.04	0.1051	0.2098	437.006	1311.02	58382.0
I_v	0.04	0.1063	0.2119	436.827	1310.48	58431.1
	0.05	0.1063	0.2119	436.827	1310.48	58397.5
	0.06	0.1063	0.2119	436.827	1310.48	58363.9
I_p	0.02	0.1063	0.2119	436.827	1310.48	58363.9
	0.03	0.1063	0.2119	436.827	1310.48	58397.5
	0.04	0.1063	0.2119	436.827	1310.48	58431.1
Q_d	400	0.1063	0.2119	436.827	1310.48	58397.5
	500	0.1063	0.2119	436.827	1310.48	58397.5
	600	0.1063	0.2119	436.827	1310.48	58397.5

2), the retailer may pay at time M_2 to benefit from the permissible delay in payments; otherwise, the retailer will pay at early time M_1 to receive a discount on the purchase price; (2) The retailer will order more and the supplier will produce more in response to increased defective rate of items; however, it has a negative effect on the joint total profit; (3) The number of shipments is rigid for changes in the supplier's parameters since it must be an integer; (4) Although the optimal solutions and joint total profit are not affected by the value of the order quantity threshold in the integrated supply chain, it is an important factor for determining whether the freight should be paid by the retailer or by the supplier.

The proposed model can be extended to include other aspects. For instance, it would be interesting to consider the supply chain system with multiple items or deteriorating items. In addition, inventory shortages are common in business. Some customers willingly wait for backlogged orders during shortage periods, whereas others do not. It is, therefore, necessary to relax the complete restriction on backlogging. Furthermore, the supplier and retailer are not necessarily integrated; the two parties may be only loosely associated or possibly in competition. Future researches should discuss the optimal decisions for the two parties from cooperative and competitive perspectives. On the other hand, staff negligence, aging equipment, ineffective inspection technology, and erroneous inspection results must be considered. Thus, a proportion of non-defective items might be misclassified as defective (termed as a Type I inspection error), and a proportion of defective items might be misclassified as non-defective (termed as

Type II inspection error). Hence, the effects of these inspection errors on any newly proposed model should be considered. Finally, similar to the transportation cost, the number of transportations increases which implies the increasing percentage of carbon emission. Carbon is a basic element in fossil energy, and cutting carbon equals cost savings and operational efficiency. Thus, the effect of carbon emission cost can be taken into account in the future research.

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